Dirichlet's principle and well posedness of steady state solutions in peridynamics

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The steady state peridynamic model

Consider the "elliptic" nonlocal model:

$$(\mathsf{PD}) \qquad \qquad \begin{cases} \mathcal{L}(u)(x) = b(x), & x \in \Omega \\ u(x) = g(x), & x \in \Gamma, \end{cases}$$

where

$$\mathcal{L}(u)(x) := 2 \int_{\Omega \cup \Gamma} (u(x') - u(x)) \mu(x, x') \, dx',$$

- Ω is an open bounded subset of \mathbb{R}^n
- $\Gamma \subset \mathbb{R}^n \backslash \Omega$ denotes a "collar" domain surrounding Ω which has nonzero volume
- $\mu(x, x')$ is nonegative, $\mu(x, x') = \mu(x', x)$.

Remark: The integral operator is defined on the boundary Γ as well.

Notation

 $\begin{array}{l} \alpha:\Omega\cup\Gamma\times\Omega\cup\Gamma\to\mathbb{R}^n,\ u:\Omega\cup\Gamma\to\mathbb{R}^n,\ f:\Omega\cup\Gamma\times\Omega\cup\Gamma\to\mathbb{R}^n\\ ({\sf i}) \text{ Generalized nonlocal gradient} \end{array}$

$$\mathfrak{G}(u)(x,x'):=(u(x')-u(x))lpha(x,x'),\quad x,x'\in\Omega,$$

(ii) Generalized nonlocal divergence

$$\mathcal{D}(f)(x) := \int_{\Omega \cup \Gamma} (f(x,x')\alpha(x,x') - f(x',x)\alpha(x',x))dx', \quad x \in \Omega,$$

(iii) Generalized nonlocal normal component

$$\mathbb{N}(f)(x) := -\int_{\Omega\cup\Gamma} (f(x,x')lpha(x,x') - f(x',x)lpha(x',x))dx', \quad x\in\Gamma.$$

Note: For the given peridynamic model we will use $\mu=\alpha^2$

Useful nonlocal calculus identities

Gunzburger & Lehoucq:

- $\mathcal{L}u = \mathcal{D}(\mathfrak{G}(u))$
- For $u, v \in L^2(\Omega \cup \Gamma)$

$$\int_{\Omega} v \mathcal{D}(\mathfrak{G}(u)) dx + \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{G}(u) \mathfrak{G}(v) dx' dx = \int_{\Gamma} v \mathcal{N}(\mathfrak{G}(u)) dx.$$

• For $u, v \in L^2(\Omega \cup \Gamma)$, v = 0 over Γ

$$\int_{\Omega} (\mathcal{L} u) v \, dx = - \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{G}(v) \cdot \mathfrak{G}(u) dx' dx.$$

Nonlocal boundary conditions

Dirichlet Problem:

$$\begin{cases} \mathcal{L} u = b, \quad x \in \Omega \\ u = g, \quad x \in \Gamma \end{cases}$$

Neumann Problem:

$$\begin{cases} \mathcal{L}u = b, \quad x \in \Omega\\ \int_{\Gamma} (u' - u) \mu(x, x') dx' = g, \quad x \in \Gamma, \end{cases}$$

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where $u' = u(x'), \ u = u(x).$

Set up for the Dirichlet's principle. Spaces

Introduce the inner product

$$\langle u, v \rangle_{\mu} = \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} (u(x') - u(x))(v(x') - v(x))\mu(x, x')dx'dx + (u, v)_{L^{2}(\Omega \cup \Gamma)},$$

The space

$$\mathcal{W} := \{ w \in L^2(\Omega) | \langle w, w \rangle_{\mu} < \infty, w = 0 \text{ on } \Gamma \},$$

endowed with the norm

$$\|\mathbf{w}\|_{\mathcal{W}} = \langle \mathbf{w}, \mathbf{w} \rangle_{\mu}^{1/2}.$$

is a Banach space whenever μ is nonnegative and symmetric.

The energy functional

The energy functional associated with the peridynamic problem (PD) is given by:

$$\mathfrak{F}[u] = \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} (u(x') - u(x))^2 \mu(x, x') dx' dx + \int_{\Omega} b(x) u(x) dx,$$

for u in the class of admissible functions

$$\mathcal{A}=\{w\in L^2(\Omega)\ | u=g+u_0, ext{ for some } u_0\in \mathcal{W}\},$$

Convention: \mathcal{A} will also be denoted by $g + \mathcal{W}$.

The Nonlocal Dirichlet's Principle

Theorem Let $\mu(x, x')$ be nonnegative and symmetric. (i) Assume u solves the nonlocal peridynamics problem

(PD)
$$\begin{cases} \mathcal{L}(u)(x) = b(x), & x \in \Omega \\ u(x) = g(x), & x \in \Gamma. \end{cases}$$

Then

$$\mathcal{F}[u] \leq \mathcal{F}[v]$$

for every $v \in A$.

(ii) Conversely, if u ∈ A satisfies 𝔅[u] ≤ 𝔅[v] for every v ∈ A, then u solves the above nonlocal peridynamics problem.

Proof:

(i) If $w \in A$, then u - w = 0 over Γ . Integration by parts yields:

$$0 = \int_{\Omega} (Lu - b)(u - w) dx$$

= $-\int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{S}(u) \cdot \mathfrak{S}(u - w) dx' dx - \int_{\Omega} b(u - w) dx$

By Cauchy-Schwarz we obtain:

$$\frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{S}(u) \cdot \mathfrak{S}(u) dx' dx + \int_{\Omega} bu dx \\ \leq \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{S}(w) \cdot \mathfrak{S}(w) dx' dx + \int_{\Omega} bw dx$$

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(ii) Fix $v \in W$ and write

$$i(\tau) := \mathcal{F}[u + \tau v]_{\mathfrak{F}}$$

where $\tau \in \mathbb{R}$. Since $u + \tau v \in \mathcal{A}$ for each τ , the scalar function $i(\cdot)$ has a minimum at zero. Thus i'(0) = 0, $(' = \frac{d}{d\tau})$, provided the derivative exists. Now we have

$$i(\tau) = \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \frac{1}{2} \mathfrak{G}(u) \cdot \mathfrak{G}(u) + \tau \mathfrak{G}(u) \cdot \mathfrak{G}(v) + \frac{\tau^2}{2} \mathfrak{G}(v) \cdot \mathfrak{G}(v) dx' dx + \int_{\Omega} b(u + \tau v) dx$$

Hence, after integration by parts we obtain:

$$0 = i'(0) = \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} \mathfrak{G}(u) \cdot \mathfrak{G}(v) dx' dx + \int_{\Omega} v b dx = \int_{\Omega} (\mathcal{L}u - b) v dx$$

A particular kernel

Assumption A. For every $x' \in \mathcal{H}_x$, there exists a constant $C_0 > 0$ such that $\mu(x, x') \ge C_0$. In other words, for all $x \in \Omega \cup \Gamma$ we have:

$$C_0\chi_\delta(x,x')\leq \mu(x,x'),$$

where
$$\chi_{\delta}(x,x') = \begin{cases} 1, & |x-x'| \leq \delta \\ 0, & |x-x'| > \delta. \end{cases}$$

Remark: The prototype kernel

$$\mu(x,x') = \begin{cases} \frac{1}{|x-x'|^{\beta}} & \text{for } |x-x'| \leq \delta \\ 0 & \text{for } |x-x'| > \delta, \end{cases}$$

satisfies this assumption for all $\beta > 0$.

Prototype kernel:

$$\mu(x,x') = \begin{cases} \frac{1}{|x-x'|^{\beta}} & \text{for } |x-x'| \ge \delta\\ 0 & \text{for } |x-x'| < \delta, \end{cases}$$

where $\beta \geq 0$.

- β ≥ n ⇒ strong singularity; work in the framework of Nikolskii spaces H^{(β-n)/2}(Ω)
- $\beta < n \implies$ weak singularity; work with L^2 spaces (with weights?)

More "elliptic" properties of \mathcal{L}

Proposition

The operator \mathcal{L} admits the following properties:

(a) If
$$u \equiv constant$$
 then $\mathcal{L}u = 0$.

(b) Let x ∈ Ω ∪ Γ. For any maximal point x₀ that satisfies u(x₀) ≥ u(x), we have -Lu(x₀) ≥ 0. Similarly, if x₁ is a minimal point such that u(x₁) ≤ u(x), then -Lu(x₁) ≤ 0.
(c) Lu is a positive semidefinite operator, i.e. ⟨-Lu, u⟩ ≥ 0.
(d) ∫_{Ω∪Γ} -Lu(x)dx = 0.

(e) Weak mean-value inequality.

If μ satisfies (A) and u is a **nonnegative** solution of $\mathcal{L}u(x) = 0$ then:

$$u(x) \geq \frac{1}{|\mathcal{H}_x|} \int_{\mathcal{H}_x} u(y) dy$$

(f) Maximum and minimum principle (Rossi) Assume that $u \in C(\Omega)$ solves (PD) with f = 0. If

$$u(x_0) = \max_{x \in \Omega \cup \Gamma} u(x)$$

then $x_0 \in \Gamma$. Similarly, if

$$u(x_0) = \max_{x \in \Omega \cup \Gamma} u(x)$$

then $x_0 \in \Gamma$.

Lemma

(Nonlocal Poincaré's Inequality - Rossi, Aksoylu &Parks) If $u \in L^{p}(\Omega), p > 1, m \ge 1$, and \mathcal{G} is as defined in (3), then there exist $\lambda_{Pncr} = \lambda_{Pncr}(\Omega, \Gamma, \delta, m) > 0$ and $C_{g} > 0$ such that the following inequality holds:

 $\lambda_{Pncr} \|u\|_{L^p(\Omega)} \leq \|\mathfrak{G}(u)\|_{L^p(\Omega\cup\Gamma imes\Omega\cup\Gamma)} + C_g.$

Wellposedness of the system (PD)

Theorem

With $\mathcal{F}[u]$ defined as before and μ satisfying assumption (A) we have that

 $inf \{ \mathcal{F}[u] : u \in \mathcal{A} \}$

attains its minimum, and furthermore this minimizer is unique. Hence, there exists a unique solution to (PD) in A for every f, g in A.

Existence of solutions

Follows from **convexity** of \mathcal{F} and **coercivity** of \mathcal{F} . First note that since $\mathcal{F}[u] \ge 0$ for $u \in L^2(\Omega)$, we have that

$$inf \{ \mathfrak{F}[u] : u \in \mathcal{A} \} = m \ge 0.$$

Let $\{u_{\nu}\}$ be a minimizing sequence so that $\mathcal{F}[u_{\nu}] \to m$. Thus there exists M > 0 such that $\mathcal{F}[u_{\nu}] < M$. We will show that the sequence u_{ν} is bounded in L^2 (coercivity.).

$$\begin{split} \mathcal{M} &> \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} [\mathfrak{G}(u_{\nu})]^2 dx' dx + \int_{\Omega} b(x) u_{\nu}(x) dx \\ &\geq \frac{1}{2} \|\mathfrak{G}(u_{\nu})\|_{L^2(\Omega \cup \Gamma \times \Omega \cup \Gamma)}^2 - \frac{\varepsilon}{2} \|b\|_{L^2(\Omega)}^2 - \frac{1}{2\varepsilon} \|u_{\nu}\|_{L^2(\Omega)}^2, \end{split}$$

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Existence contd.

By the nonlocal Poincaré's inequality we have:

$$M > C_1 \|u_{\nu}\|_{L^2(\Omega)}^2 + C_2 \|g\|_{L^2(\Gamma)}^2 - C_3 \|b\|_{L^2(\Omega)}^2$$

Thus, we can find $\gamma > 0$ such that

$$\|u_{\nu}\|_{L^{2}(\Omega)} \leq \gamma.$$

Therefore, we may extract a subsequence $\{u_{\nu}\}$ and find $\bar{u} \in L^{2}(\Omega)$ such that $u_{\nu} \to \bar{u}$ in $L^{2}(\Omega)$. By Mazur's Lemma we can find a sequence of convex combinations of u_{ν} , denoted by $\bar{u}_{\nu} \to \bar{u}$ in $L^{2}(\Omega)$, hence

$$\lim_{\nu\to\infty} \mathfrak{F}[\bar{u}_{\nu}] \leq m.$$

By Fatou's lemma

$$\mathcal{F}[\bar{u}] \leq \lim_{\nu \to \infty} \mathcal{F}[\bar{u}_{\nu}],$$

hence, from the above inequalities we have that $\bar{\boldsymbol{u}}$ is a minimizer since

$$\mathcal{F}[\bar{u}] \leq m.$$

Uniqueness of solutions

Let $\bar{u}, \bar{v} \in L^2(\Omega)$ be minimizers of \mathcal{F} with $\bar{u} \neq \bar{v}$. Set

$$ar{w}=rac{ar{u}+ar{v}}{2}\in L^2(\Omega).$$

By the strict convexity of the integrand, we have

$$m \leq \mathcal{F}[\bar{w}] \leq \frac{1}{2}\mathcal{F}[\bar{u}] + \frac{1}{2}\mathcal{F}[\bar{v}] = m.$$

Hence \bar{w} is a minimizer of \mathcal{F} . This implies that

$$\frac{1}{2}\mathcal{F}[\bar{u}] + \frac{1}{2}\mathcal{F}[\bar{v}] - \mathcal{F}[\bar{w}] = 0.$$

Thus

$$\int_{\Omega\cup\Gamma}\int_{\Omega\cup\Gamma}\frac{\mathfrak{G}[\bar{u}]^2}{2}+\frac{\mathfrak{G}[\bar{v}]^2}{2}-\mathfrak{G}[\bar{w}]dx'dx=0.$$

Again, by strict convexity, the integrand is strictly positive – contradiction!!

Fick diffusion in peridynamics models

Consider the nonlocal flux that satisfies a nonlocal Fourier's law:

$$\mathfrak{Q}[u](x,x') = -a\mathfrak{G}[u](x,x'),$$

The nonlocal conservation law:

$$u_t = -\mathcal{D}(\mathcal{Q}).$$

We obtain the nonlocal peridynamic diffusion law

$$u_t = \mathcal{D}(a\mathfrak{G}(u)) = a\mathcal{L}u.$$

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Hyperbolic diffusion in peridynamics

Assum that the flux $\ensuremath{\mathbb{Q}}$ is given by the Cattaneo-Vernotte equation

$$\mathfrak{Q}_t + a \mathfrak{Q} = -\mathfrak{G}(u).$$

Differentiate the conservation law $u_t = -\mathcal{D}(\Omega)$ with respect to time:

$$u_{tt} = -\mathcal{D}(\mathfrak{Q}_t).$$

Substituted into the above equation yields:

or

$$u_{tt} = -\mathcal{D}(-\mathfrak{G}(u) - a\mathfrak{Q}) = \mathcal{D}(\mathfrak{G}(u)) + \mathcal{D}(a\mathfrak{Q}) = \mathcal{L}u - au_t.$$

$$u_{tt} - \mathcal{L}u + au_t = 0.$$

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Importance of hyperbolic diffusion (classical case)

Consider the classical heat and damped wave equations:

$$\begin{cases} v_t - \Delta v = 0 \text{ in } \mathbb{R}^n \\ v|_{t=0} = v_0 \text{ in } \mathbb{R}^n. \end{cases} \begin{cases} u_{tt} - \Delta u + u_t = 0 \text{ in } \mathbb{R}^n \\ (u, u_t)|_{t=0} = u_0 + u_1 \text{ in } \mathbb{R}^n. \end{cases}$$

- hyperbolic diffusion is important in unsteady heat conduction (the second sound of helium)
- the long time behavior of u with initial conditions (u_0, u_1) can be very well approximated by the long time behavior of v with initial condition $v_0 = u_0 + u_1$ (Abstract Diffusion Phenomenon - JDE)

Questions and future directions

- 1. physical interpretation of the exponent β in μ ;
- 2. what if μ depends on time? OR the horizon changes with space (different phases of the material)
- 3. weakly singular kernels (0 < s < n): Harnack's inequality
- 4. obtain regularity results via Calculus of Variations techniques
- wellposedness and regularity for time dependent models (diffusion, elasticity,..)
- nonlinear local problems: very difficult since there is no gain in "smoothness" (higher integrability or more derivatives for the solution)
- 7. wellposedness in weighted spaces