From random Poincaré maps to stochastic mixed-mode-oscillation patterns

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Mixed-mode oscillations (MMOs)



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Deterministic models reproducing these oscillations exist and have been abundantly studied

They often involve singular perturbation theory

We want to understand the effect of noise on oscillatory patterns

Noise may also induce oscillations not present in deterministic case

The deterministic Koper model

$$\varepsilon \dot{x} = f(x, y, z) = y - x^3 + 3x$$

$$\dot{y} = g_1(x, y, z) = kx - 2(y + \lambda) + z$$

$$\dot{z} = g_2(x, y, z) = \rho(\lambda + y - z)$$

▷ 0 < $\varepsilon \ll 1$ ▷ $k, \lambda, \rho \in \mathbb{R}$: control parameters The deterministic Koper model

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▷ Critical manifold: $C_0 = \{f = 0\} = \{y = x^3 - 3x\}$

▷ Folds: $L = \{f = 0, \partial_x f = 0\} = \{y = x^3 - 3x, x = \pm 1\} = L^+ \cup L^-$

Critical manifold



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ho \in \mathbb{R}$: control parameters

▷ Critical manifold: $C_0 = \{f = 0\} = \{y = x^3 - 3x\}$

 \triangleright Reduced flow on C_0 (Fenichel theory): eliminate y

$$\dot{x} = \frac{kx - 2(x^3 - 3x + \lambda) + z}{3(x^2 - 1)}$$
$$\dot{z} = \rho(\lambda + x^3 - 3x - z)$$

 ⋈ Generic fold points: \dot{x} diverges as $x → \pm 1$ ⋈ Folded node singularity: \dot{x} finite, (desingularized) system has a node

Folded node singularity

Normal form [Benoît, Lobry '82, Szmolyan, Wechselberger '01]:

$$\epsilon \dot{x} = y - x^{2}$$

$$\dot{y} = -(\mu + 1)x - z \qquad (+ \text{ higher-order terms})$$

$$\dot{z} = \frac{\mu}{2}$$

Folded node singularity

Normal form [Benoît, Lobry '82, Szmolyan, Wechselberger '01]:



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Folded node singularity

Theorem [Benoît, Lobry '82, Szmolyan, Wechselberger '01]: For $2k + 1 < \mu^{-1} < 2k + 3$, the system admits k canard solutions The j^{th} canard makes (2j + 1)/2 oscillations



Global dynamics



Canard orbits track unstable manifold (for some time)

Global dynamics



Canard orbits track unstable manifold (for some time)
Typical orbits may jump earlier to stable manifold



▷ Poincaré map $\Pi : \Sigma \to \Sigma$, invertible, 2-dimensional ▷ Due to contraction along C_0 , close to 1d, non-invertible map



The stochastic Koper model

$$dx_t = \frac{1}{\varepsilon} f(x_t, y_t, z_t) dt + \frac{\sigma}{\sqrt{\varepsilon}} F(x_t, y_t, z_t) dW_t$$

$$dy_t = g_1(x_t, y_t, z_t) dt + \sigma' G_1(x_t, y_t, z_t) dW_t$$

$$dz_t = g_2(x_t, y_t, z_t) dt + \sigma' G_2(x_t, y_t, z_t) dW_t$$

▷ W_t : *k*-dimensional Brownian motion ▷ σ, σ' : small parameters (may depend on ε)

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Random Poincaré map

In appropriate coordinates

 $d\varphi_t = \widehat{f}(\varphi_t, X_t) dt + \widehat{\sigma}\widehat{F}(\varphi_t, X_t) dW_t \qquad \varphi \in \mathbb{R}$ $dX_t = \widehat{g}(\varphi_t, X_t) dt + \widehat{\sigma}\widehat{G}(\varphi_t, X_t) dW_t \qquad X \in E \subset \Sigma$

▷ all functions periodic in φ (say period 1) ▷ $\hat{f} \ge c > 0$ and $\hat{\sigma}$ small $\Rightarrow \varphi_t$ likely to increase ▷ process may be killed when X leaves E

Random Poincaré map



 $> X_0, X_1, \ldots$ form (substochastic) Markov chain

Random Poincaré map



 $\triangleright X_0, X_1, \ldots$ form (substochastic) Markov chain

▷ τ : first-exit time of $Z_t = (\varphi_t, X_t)$ from $\mathcal{D} = (-M, 1) \times E$ ▷ $\mu_Z(A) = \mathbb{P}^Z \{ Z_\tau \in A \}$: harmonic measure (wrt generator \mathcal{L}) ▷ [Ben Arous, Kusuoka, Stroock '84]: under hypoellipticity cond, μ_Z admits (smooth) density h(Z, Y) wrt Lebesgue on $\partial \mathcal{D}$ ▷ For $B \subset E$ Borel set

$$\mathbb{P}^{X_0}\{X_1 \in B\} = K(X_0, B) := \int_B K(X_0, dy)$$

where $K(x, dy) = h((0, x), (1, y)) dy =: k(x, y) dy$















Random Poincaré map

Observations:

- ▷ Size of fluctuations depends on noise intensity
 - and canard number k: high order canards are more sensitive
- ▷ Saturation effect: constant distribution of z_{n+1} for $k > k_{C}(\sigma, \sigma')$
- ▷ Consequence: if $k_{\rm C} < k_{\rm det}^*$, number of SAOs increases

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Questions:

- ▷ Prove saturation effect
- ▷ How does $k_{\rm C}$ depend on σ, σ' ?
- ▷ How does size of fluctuations depend on σ, σ' and canard number k?
- \triangleright In particular, size of fluctuations for $k > k_{\rm C}$?

Size of noise-induced fluctuations

$$\zeta_{t} = (x_{t}, y_{t}, z_{t}) - (x_{t}^{\det}, y_{t}^{\det}, z_{t}^{\det})$$

$$d\zeta_{t} = \frac{1}{\varepsilon} A(t)\zeta_{t} dt + \frac{\sigma}{\sqrt{\varepsilon}} \mathcal{F}(\zeta_{t}, t) dW_{t} + \frac{1}{\varepsilon} \underbrace{b(\zeta_{t}, t)}_{=\mathcal{O}(||\zeta_{t}||^{2})} dt$$

$$\zeta_{t} = \frac{\sigma}{\sqrt{\varepsilon}} \int_{0}^{t} U(t, s) \mathcal{F}(\zeta_{s}, s) dW_{s} + \frac{1}{\varepsilon} \int_{0}^{t} U(t, s) b(\zeta_{s}, s) ds$$

where U(t,s) principal solution of $\varepsilon \dot{\zeta} = A(t)\zeta$.

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Lemma (Bernstein-type estimate):

$$\mathbb{P}\left\{\sup_{0\leqslant s\leqslant t}\left\|\int_{0}^{s}\mathcal{G}(\zeta_{u},u)\,\mathrm{d}W_{u}\right\| > h\right\} \leqslant 2n\exp\left\{-\frac{h^{2}}{2V(t)}\right\}$$

where $\int_{0}^{s}\mathcal{G}(\zeta_{u},u)\mathcal{G}(\zeta_{u},u)^{T}\,\mathrm{d}u\leqslant V(s)$ and $n=3$

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$$\begin{aligned} \zeta_t &= (x_t, y_t, z_t) - (x_t^{\text{det}}, y_t^{\text{det}}, z_t^{\text{det}}) \\ & \mathsf{d}\zeta_t = \frac{1}{\varepsilon} A(t)\zeta_t \,\mathsf{d}t + \frac{\sigma}{\sqrt{\varepsilon}} \mathcal{F}(\zeta_t, t) \,\mathsf{d}W_t + \frac{1}{\varepsilon} \underbrace{b(\zeta_t, t)}_{=\mathcal{O}(||\zeta_t||^2)} \,\mathsf{d}t \\ & \zeta_t = \frac{\sigma}{\sqrt{\varepsilon}} \int_0^t U(t, s) \mathcal{F}(\zeta_s, s) \,\mathsf{d}W_s + \frac{1}{\varepsilon} \int_0^t U(t, s) b(\zeta_s, s) \,\mathsf{d}s \end{aligned}$$

where U(t,s) principal solution of $\varepsilon\dot{\zeta} = A(t)\zeta$.

Lemma (Bernstein-type estimate): $\mathbb{P}\left\{\sup_{0 \le s \le t} \left\| \int_{0}^{s} \mathcal{G}(\zeta_{u}, u) \, \mathrm{d}W_{u} \right\| > h \right\} \leqslant 2n \exp\left\{-\frac{h^{2}}{2V(t)}\right\}$

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Remark: more precise results using ODE for covariance matrix of

$$\zeta_t^0 = \frac{\sigma}{\sqrt{\varepsilon}} \int_0^t U(t,s) \mathcal{F}(0,s) \, \mathrm{d} W_s$$

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Transition	Δx	Δy	Δz
$\Sigma_2 \rightarrow \Sigma_3$	$\sigma + \sigma'$		$\sigma\sqrt{\varepsilon} + \sigma'$
$\Sigma_3 \rightarrow \Sigma_4$	$\sigma + \sigma'$		$\sigma\sqrt{\varepsilon} + \sigma'$
$\Sigma_4 ightarrow \Sigma_4'$	$\frac{\sigma}{\varepsilon^{1/6}} + \frac{\sigma'}{\varepsilon^{1/3}}$		$\sigma \sqrt{\varepsilon \log \varepsilon } + \sigma'$
$\Sigma_4' ightarrow \Sigma_5$		$\sigma\sqrt{\varepsilon} + \sigma'\varepsilon^{1/6}$	$\sigma\sqrt{\varepsilon} + \sigma'\varepsilon^{1/6}$
$\Sigma_5 \rightarrow \Sigma_6$	$\sigma + \sigma'$		$\sigma\sqrt{\varepsilon} + \sigma'$
$\Sigma_6 \rightarrow \Sigma_1$	$\sigma + \sigma'$		$\sigma\sqrt{\varepsilon} + \sigma'$
$\Sigma_1 ightarrow \Sigma_1'$		$(\sigma + \sigma') \varepsilon^{1/4}$	σ'
$\Sigma_1' o \Sigma_1''$		$(\sigma + \sigma')(\varepsilon/\mu)^{1/4}$	$\sigma'(arepsilon/\mu)^{1/4}$
if $z = \mathcal{O}(\sqrt{\mu})$			
$\Sigma_1'' o \Sigma_2$		$(\sigma + \sigma')\varepsilon^{1/4}$	$\sigma' \varepsilon^{1/4}$

Example: Analysis near the regular fold



Proposition: For $h_1 = \mathcal{O}(\varepsilon^{2/3})$,

$$\mathbb{P}\left\{ \|(y_{\tau_{\Sigma_{5}}}, z_{\tau_{\Sigma_{5}}}) - (y^{*}, z^{*})\| > h_{1} \right\}$$

$$\leq \frac{C|\log \varepsilon|}{\varepsilon} \left(\exp\left\{ -\frac{\kappa h_{1}^{2}}{\sigma^{2}\varepsilon + (\sigma')^{2}\varepsilon^{1/3}} \right\} + \exp\left\{ -\frac{\kappa\varepsilon}{\sigma^{2} + (\sigma')^{2}\varepsilon} \right\} \right)$$
Hereful if $\tau, \tau' \ll \sqrt{\varepsilon}$

Useful if $\sigma, \sigma' \ll \sqrt{\varepsilon}$

The global return map

Theorem [B, Gentz, Kuehn, 2013]

$$\begin{split} P_2 &= (x_2^*, y_2^*, z_2^*) \in \Sigma_2 \\ (x_1^*, y_1^*, z_1^*) \text{ deterministic first-hitting point of } \Sigma_1 \\ (x_1, y_1^*, z_1) \text{ stochastic first-hitting point of } \Sigma_1 \end{split}$$

$$\begin{split} \mathbb{P}^{P_2} \Big\{ |x_1 - x_1^*| > h \text{ or } |z_1 - z_1^*| > h_1 \Big\} \\ \leqslant \frac{C |\log \varepsilon|}{\varepsilon} \Big(\exp \Big\{ -\frac{\kappa h^2}{\sigma^2 + (\sigma')^2} \Big\} + \exp \Big\{ -\frac{\kappa h_1^2}{\sigma^2 \varepsilon |\log \varepsilon| + (\sigma')^2} \Big\} \\ + \exp \Big\{ -\frac{\kappa \varepsilon}{\sigma^2 + (\sigma')^2 \varepsilon^{-1/3}} \Big\} \Big) \end{split}$$

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$$\mathbb{P}^{P_2}\left\{|x_1 - x_1^*| > h \text{ or } |z_1 - z_1^*| > h_1\right\}$$

$$\leq \frac{C|\log \varepsilon|}{\varepsilon} \left(\exp\left\{-\frac{\kappa h^2}{\sigma^2 + (\sigma')^2}\right\} + \exp\left\{-\frac{\kappa h_1^2}{\sigma^2 \varepsilon |\log \varepsilon| + (\sigma')^2}\right\} + \exp\left\{-\frac{\kappa \varepsilon}{\sigma^2 + (\sigma')^2 \varepsilon^{-1/3}}\right\}\right)$$

$$\begin{split} & \triangleright \text{ Useful for } \sigma \ll \sqrt{\varepsilon}, \ \sigma' \ll \varepsilon^{2/3} \\ & \triangleright \Delta x \asymp \sigma + \sigma' \\ & \triangleright \Delta z \asymp \sigma \sqrt{\varepsilon |\log \varepsilon|} + \sigma' \end{split}$$

Thm 1: (Canard spacing) For z = 0, the k^{th} canard lies at dist. $\sqrt{\varepsilon} e^{-c(2k+1)^2 \mu}$ from primary canard



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Thm 2: Size of fluctuations $(\sigma + \sigma')(\varepsilon/\mu)^{1/4}$ up to $z = \sqrt{\varepsilon\mu}$ $(\sigma + \sigma')(\varepsilon/\mu)^{1/4} e^{z^2/(\varepsilon\mu)}$ for $z \ge \sqrt{\varepsilon\mu}$



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Consequence: Dichotomy

▷ Canards with $k \leq \sqrt{1/\mu}$: $\Delta z \approx \sigma \sqrt{\varepsilon |\log \varepsilon|} + \sigma'$ (assuming $\varepsilon \leq \mu$) ▷ Canards with $k > \sqrt{|\log(\sigma + \sigma')|/\mu}$: $\Delta z \leq \mathcal{O}(\sqrt{\varepsilon \mu |\log(\sigma + \sigma')|})$



Local analysis near the folded node: early escapes



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Summary

- $\triangleright \sqrt{1/\mu} < k_{\rm C} \leqslant \sqrt{|\log(\sigma + \sigma')|/\mu}$ $\triangleright \text{ For } k \leqslant k_{\rm C}, \text{ dispersion } \Delta z \asymp \sigma \sqrt{\varepsilon |\log \varepsilon|} + \sigma'$ $\triangleright \text{ For } k > k_{\rm C}, \text{ dispersion } \Delta z \leqslant \mathcal{O}(\sqrt{\varepsilon \mu |\log(\sigma + \sigma')|})$
- ▷ If the deterministic system has MMO pattern with k^* SAOs and $k^* < k_c$ then noise increases number of SAOs



Further ways to analyse random Poincaré map

Theory of singularly perturbed Markov chains



Further ways to analyse random Poincaré map

> Theory of singularly perturbed Markov chains



Further ways to analyse random Poincaré map

▷ Theory of singularly perturbed Markov chains



▷ For coexisting stable periodic orbits: Metastable transitions



Thanks for your attention – Further reading

N.B. and Barbara Gentz, *Noise-induced phenomena in slow-fast dynamical systems, A sample-paths approach*, Springer, Probability and its Applications (2006)

N.B. and Barbara Gentz, *Stochastic dynamic bifurcations and excitability*, in C. Laing and G. Lord, (Eds.), *Stochastic methods in Neuroscience*, p. 65-93, Oxford University Press (2009)



N.B., *Stochastic dynamical systems in neuroscience*, Oberwolfach Reports **8**:2290–2293 (2011)

N.B., Barbara Gentz and Christian Kuehn, *Hunting French Ducks in a Noisy Environment*, J. Differential Equations **252**:4786–4841 (2012). arXiv:1011.3193

N.B. and Damien Landon, *Mixed-mode oscillations and interspike interval statistics in the stochastic FitzHugh–Nagumo model*, Nonlinearity **25**:2303–2335 (2012). arXiv:1105.1278

N.B. and Barbara Gentz, *On the noise-induced passage through an unstable periodic orbit II: General case*, preprint arXiv:1208.2557

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