# Polarity of points for systems of linear spde's in critical dimensions 

Robert C. Dalang

Ecole Polytechnique Fédérale de Lausanne

Based on joint work with:
Carl Mueller and Yimin Xiao

- Introduction to the problem of polarity of points
- Existing results for Gaussian and non-Gaussian random fields
- The "standard method" for non-critical dimensions
- Talagrand's idea for handling critical dimensions (fBM)
- Our results for a class of Gaussian processes
- Application to systems of linear stochastic heat and wave equations in critical dimensions


## Polarity of points for random fields

Let $U=\left(U(x), x \in \mathbb{R}^{k}\right)$ be an $\mathbb{R}^{d}$-valued continuous stochastic process.
Fix $I \subset \mathbb{R}^{k}$, compact with positive Lebesgue measure.
The range of $U$ over $I$ is the random compact set

$$
U(I)=\{U(x), x \in I\} .
$$

## Question. Fix $z \in \mathbb{R}^{d}$. Is $z$ hit by $U$, that is,

Polarity. If $P\{\exists x \in I: U(x)=z\}=0$, then $z$ is polar for $U$.
Typically, there is a critical value $Q(k)$ such that

- if $d<Q(k)$, then points are not polar
- if $d>Q(k)$, then points are polar.
- at the critical valued $d=Q(k): ? ? ?$


## Polarity of points for random fields

Let $U=\left(U(x), x \in \mathbb{R}^{k}\right)$ be an $\mathbb{R}^{d}$-valued continuous stochastic process.
Fix $I \subset \mathbb{R}^{k}$, compact with positive Lebesgue measure.
The range of $U$ over $I$ is the random compact set

$$
U(I)=\{U(x), x \in I\} .
$$

Question. Fix $z \in \mathbb{R}^{d}$. Is $z$ hit by $U$, that is,

$$
P\{\exists x \in I: U(x)=z\}>0 ?
$$

Polarity. If $P\{\exists x \in I: U(x)=z\}=0$, then $z$ is polar for $U$.
Typically, there is a critical value $Q(k)$ such that:

- if $d<Q(k)$, then points are not polar
- if $d>Q(k)$, then points are polar.
- at the critical valued $d=Q(k): ? ? ?$


## Polarity of points for random fields

Let $U=\left(U(x), x \in \mathbb{R}^{k}\right)$ be an $\mathbb{R}^{d}$-valued continuous stochastic process.
Fix $I \subset \mathbb{R}^{k}$, compact with positive Lebesgue measure.
The range of $U$ over $I$ is the random compact set

$$
U(I)=\{U(x), x \in I\} .
$$

Question. Fix $z \in \mathbb{R}^{d}$. Is $z$ hit by $U$, that is,

$$
P\{\exists x \in I: U(x)=z\}>0 ?
$$

Polarity. If $P\{\exists x \in I: U(x)=z\}=0$, then $z$ is polar for $U$.
Typically, there is a critical value $Q(k)$ such that:

- if $d<Q(k)$, then points are not polar.
- if $d>Q(k)$, then points are polar.
- at the critical valued $d=Q(k)$ : ???


## First example: the Brownian sheet

Let $\left(W(x), x \in \mathbb{R}_{+}^{k}\right)$ denote an $k$-parameter $\mathbb{R}^{d}$-valued Brownian sheet, that is, a centered continuous Gaussian random field

$$
W(x)=\left(W_{1}(x), \ldots, W_{d}(x)\right)
$$

with covariance

$$
E\left[W_{i}(x) W_{j}(y)\right]=\delta_{i, j} \prod_{\ell=1}^{k} \min \left(x_{\ell}, y_{\ell}\right), \quad i, j \in\{1, \ldots, d\}
$$

where $x=\left(x_{1}, \ldots, x_{k}\right)$ and $y=\left(y_{1}, \ldots, y_{k}\right)$.
The case $k=1$ : Brownian motion $B=\left(B(t), t \in \mathbb{R}_{+}\right)$.
The case $k>1$ : multi-parameter extension of Brownian motion.
A few references: Orey \& Pruitt (1973), R. Adler (1978), W. Kendall (1980),
J.B. Walsh (1986), D. \& Walsh (1992), Khoshnevisan \& Shi (1999)
D. Khoshnevisan, Multiparameter processes, Springer (2002)

## First example: the Brownian sheet

Let $\left(W(x), x \in \mathbb{R}_{+}^{k}\right)$ denote an $k$-parameter $\mathbb{R}^{d}$-valued Brownian sheet, that is, a centered continuous Gaussian random field

$$
W(x)=\left(W_{1}(x), \ldots, W_{d}(x)\right)
$$

with covariance

$$
E\left[W_{i}(x) W_{j}(y)\right]=\delta_{i, j} \prod_{\ell=1}^{k} \min \left(x_{\ell}, y_{\ell}\right), \quad i, j \in\{1, \ldots, d\}
$$

where $x=\left(x_{1}, \ldots, x_{k}\right)$ and $y=\left(y_{1}, \ldots, y_{k}\right)$.
The case $k=1$ : Brownian motion $B=\left(B(t), t \in \mathbb{R}_{+}\right)$.
The case $k>1$ : multi-parameter extension of Brownian motion.
A few references: Orey \& Pruitt (1973), R. Adler (1978), W. Kendall (1980),
J.B. Walsh (1986), D. \& Walsh (1992), Khoshnevisan \& Shi (1999)
D. Khoshnevisan, Multiparameter processes, Springer (2002).

## Hitting probabilities for the Brownian sheet

Let $\left(W(x), x \in \mathbb{R}_{+}^{k}\right)$ denote a $k$-parameter $\mathbb{R}^{d}$-valued Brownian sheet.

## Theorem 1 (Khoshnevisan and Shi, 1999)

Fix $M>0$ and $0<a_{\ell}<b_{\ell}<\infty(\ell=1, \ldots, k)$. Let

$$
I=\left[a_{1}, b_{1}\right] \times \cdots \times\left[a_{k}, b_{k}\right] \quad\left(\subset \mathbb{R}^{k}\right)
$$

There exists $0<C<\infty$ such that for all compact sets $A \subset B(0, M)\left(\subset \mathbb{R}^{d}\right)$,

$$
\frac{1}{C} \operatorname{Cap}_{d-2 k}(A) \leqslant P\{W(I) \cap A \neq \emptyset\} \leqslant C \operatorname{Cap}_{d-2 k}(A)
$$

(see also F. Hirsch and S. Song (1991, 1995).
Example. $A=\{z\}$

so points are polar in the critical dimension $d=2 k$

## Hitting probabilities for the Brownian sheet

Let $\left(W(x), x \in \mathbb{R}_{+}^{k}\right)$ denote a $k$-parameter $\mathbb{R}^{d}$-valued Brownian sheet.

## Theorem 1 (Khoshnevisan and Shi, 1999)

Fix $M>0$ and $0<a_{\ell}<b_{\ell}<\infty(\ell=1, \ldots, k)$. Let

$$
I=\left[a_{1}, b_{1}\right] \times \cdots \times\left[a_{k}, b_{k}\right] \quad\left(\subset \mathbb{R}^{k}\right)
$$

There exists $0<C<\infty$ such that for all compact sets $A \subset B(0, M)\left(\subset \mathbb{R}^{d}\right)$,

$$
\frac{1}{C} \operatorname{Cap}_{d-2 k}(A) \leqslant P\{W(I) \cap A \neq \emptyset\} \leqslant C \operatorname{Cap}_{d-2 k}(A)
$$

(see also F. Hirsch and S. Song (1991, 1995).
Example. $A=\{z\}$.

$$
\operatorname{Cap}_{d-2 k}(\{z\})= \begin{cases}1 & \text { if } d<2 k \\ 0 & \text { if } d \geqslant 2 k\end{cases}
$$

so points are polar in the critical dimension $d=2 k$.

## Anisotropic Gaussian random fields (Biermé, Lacaux \& Xiao, 2007)

Let $\left(V(x), x \in \mathbb{R}^{k}\right)$ be a centered continuous Gaussian random field with values in $\mathbb{R}^{d}$ with i.i.d. components: $V(x)=\left(V_{1}(x), \ldots, V_{d}(x)\right)$. Set

$$
\Delta(x, y)=\left\|V_{1}(x)-V_{1}(y)\right\|_{L^{2}}
$$

Let I be a "rectangle". Assume the two conditions:
and for all $x, y \in I$,
( $H_{j}$ is the Hölder exponent for coordinate $j$ )
(C2) There is $c>0$ such that for all $x, y \in I$

## Anisotropic Gaussian random fields (Biermé, Lacaux \& Xiao, 2007)

Let $\left(V(x), x \in \mathbb{R}^{k}\right)$ be a centered continuous Gaussian random field with values in $\mathbb{R}^{d}$ with i.i.d. components: $V(x)=\left(V_{1}(x), \ldots, V_{d}(x)\right)$. Set

$$
\Delta(x, y)=\left\|V_{1}(x)-V_{1}(y)\right\|_{L^{2}}
$$

Let I be a "rectangle". Assume the two conditions:
(C1) There exists $0<c<\infty$ and $\left.H_{1}, \ldots, H_{k} \in\right] 0,1[$ such that for all $x \in I$,

$$
c^{-1} \leqslant \Delta(0, x) \leqslant c
$$

and for all $x, y \in I$,

$$
c^{-1} \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{H_{j}} \leqslant \Delta(x, y) \leqslant c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{H_{j}}
$$

( $H_{j}$ is the Hölder exponent for coordinate $j$ ).
(C2) There is $c>0$ such that for all $x, y \in I$

## Anisotropic Gaussian random fields (Biermé, Lacaux \& Xiao, 2007)

Let $\left(V(x), x \in \mathbb{R}^{k}\right)$ be a centered continuous Gaussian random field with values in $\mathbb{R}^{d}$ with i.i.d. components: $V(x)=\left(V_{1}(x), \ldots, V_{d}(x)\right)$. Set

$$
\Delta(x, y)=\left\|V_{1}(x)-V_{1}(y)\right\|_{L^{2}}
$$

Let I be a "rectangle". Assume the two conditions:
(C1) There exists $0<c<\infty$ and $\left.H_{1}, \ldots, H_{k} \in\right] 0,1[$ such that for all $x \in I$,

$$
c^{-1} \leqslant \Delta(0, x) \leqslant c
$$

and for all $x, y \in I$,

$$
c^{-1} \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{H_{j}} \leqslant \Delta(x, y) \leqslant c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{H_{j}}
$$

( $H_{j}$ is the Hölder exponent for coordinate $j$ ).
(C2) There is $c>0$ such that for all $x, y \in I$,

$$
\operatorname{Var}\left(V_{1}(y) \mid V_{1}(x)\right) \geqslant c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{2 H_{j}}
$$

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux \& Xiao, 2007)

Fix $M>0$. Set

$$
Q=\sum_{j=1}^{k} \frac{1}{H_{j}} .
$$

Then there is $0<C<\infty$ such that for every compact set $A \subset B(0, M)$,

$$
C^{-1} \operatorname{Cap}_{d-Q}(A) \leqslant P\{V(I) \cap A \neq \emptyset\} \leqslant C \mathcal{H}_{d-Q}(A) .
$$

Example. $A=\{z\}$


If $d=Q$. Theorem 2 says: $0 \leqslant P\{\exists x \in I: V(x)=z\} \leqslant 1$ (not informative)!

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux \& Xiao, 2007)

Fix $M>0$. Set

$$
Q=\sum_{j=1}^{k} \frac{1}{H_{j}} .
$$

Then there is $0<C<\infty$ such that for every compact set $A \subset B(0, M)$,

$$
C^{-1} \operatorname{Cap}_{d-Q}(A) \leqslant P\{V(I) \cap A \neq \emptyset\} \leqslant C \mathcal{H}_{d-Q}(A) .
$$

Example. $A=\{z\}$

$$
\operatorname{Cap}_{d-Q}(\{z\})=\left\{\begin{array}{ll}
1 & \text { if } d<Q, \\
0 & \text { if } d=Q, \\
0 & \text { if } d>Q,
\end{array} \quad \mathcal{H}_{d-Q}(\{z\})= \begin{cases}\infty & \text { if } d<Q \\
1 & \text { if } d=Q \\
0 & \text { if } d>Q\end{cases}\right.
$$

If $d=Q$, Theorem 2 says: $0 \leqslant P\{\exists x \in I: V(x)=z\} \leqslant 1$ (not informative)!

## Anisotropic Gaussian fields

## Theorem 2 (Biermé, Lacaux \& Xiao, 2007)

Fix $M>0$. Set

$$
Q=\sum_{j=1}^{k} \frac{1}{H_{j}}
$$

Then there is $0<C<\infty$ such that for every compact set $A \subset B(0, M)$,

$$
C^{-1} \operatorname{Cap}_{d-Q}(A) \leqslant P\{V(I) \cap A \neq \emptyset\} \leqslant C \mathcal{H}_{d-Q}(A) .
$$

Example. $A=\{z\}$

$$
\operatorname{Cap}_{d-Q}(\{z\})=\left\{\begin{array}{ll}
1 & \text { if } d<Q, \\
0 & \text { if } d=Q, \\
0 & \text { if } d>Q,
\end{array} \quad \mathcal{H}_{d-Q}(\{z\})= \begin{cases}\infty & \text { if } d<Q \\
1 & \text { if } d=Q \\
0 & \text { if } d>Q\end{cases}\right.
$$

If $d=Q$, Theorem 2 says: $0 \leqslant P\{\exists x \in I: V(x)=z\} \leqslant 1$ (not informative)!

## Funaki's random string

Let $\left(u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}\right)$ be an $\mathbb{R}^{d}$-valued random field such that

$$
\frac{\partial}{\partial t} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+\dot{W}(t, x), \quad x \in \mathbb{R}, t>0
$$

$u(0, \cdot): \mathbb{R} \rightarrow \mathbb{R}^{d}$ given, $\dot{W}(t, x)$ is space-time white noise.

## Theorem 3 (Mueller \& Tribe, 2002) <br> The critical dimension for hitting points is $d=6$ and points are polar in this dimension.

Their proof uses the "stationary pinned string," then scaling and time reversal (method of Paul Lévy).
It does not apply to the wave equation, nor to heat equation with deterministic non-constant coefficients, such as

$$
\frac{\partial}{\partial t} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+\sigma(t, x) \dot{W}(t, x)
$$

where $(t, x) \mapsto \sigma(t, x)$ is deterministic but not constant.
(They also treat the issue of double points for this random field)

## Funaki's random string

Let $\left(u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}\right)$ be an $\mathbb{R}^{d}$-valued random field such that

$$
\frac{\partial}{\partial t} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+\dot{W}(t, x), \quad x \in \mathbb{R}, t>0
$$

$u(0, \cdot): \mathbb{R} \rightarrow \mathbb{R}^{d}$ given, $\dot{W}(t, x)$ is space-time white noise.

## Theorem 3 (Mueller \& Tribe, 2002)

The critical dimension for hitting points is $d=6$ and points are polar in this dimension.

```
Their proof uses the "stationary pinned string," then scaling and time reversal
(method of Paul Lévy).
It does not apply to the wave equation, nor to heat equation with deterministic
non-constant coefficients, such as
\partial
where (t,x)\mapsto\sigma(t,x) is deterministic but not constant.
(They also treat the issue of double noints for this random field)

\section*{Funaki's random string}

Let \(\left(u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}\right)\) be an \(\mathbb{R}^{d}\)-valued random field such that
\[
\frac{\partial}{\partial t} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+\dot{W}(t, x), \quad x \in \mathbb{R}, t>0
\]
\(u(0, \cdot): \mathbb{R} \rightarrow \mathbb{R}^{d}\) given, \(\dot{W}(t, x)\) is space-time white noise.

\section*{Theorem 3 (Mueller \& Tribe, 2002)}

The critical dimension for hitting points is \(d=6\) and points are polar in this dimension.

Their proof uses the "stationary pinned string," then scaling and time reversal (method of Paul Lévy).
It does not apply to the wave equation, nor to heat equation with deterministic non-constant coefficients, such as
\[
\frac{\partial}{\partial t} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+\sigma(t, x) \dot{W}(t, x),
\]
where \((t, x) \mapsto \sigma(t, x)\) is deterministic but not constant.
(They also treat the issue of double points for this random field)

\section*{Systems 1d nonlinear wave equations}

Let \(\left(u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}\right)\) be an \(\mathbb{R}^{d}\)-valued random field such that
\[
\frac{\partial^{2}}{\partial t^{2}} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+b(u(t, x))+\sigma(u(t, x)) \dot{W}(t, x), \quad x \in \mathbb{R}, t>0
\]
\(u(0, \cdot), \frac{\partial}{\partial t} u(0, \cdot): \mathbb{R} \rightarrow \mathbb{R}^{d}\) given, \(\dot{W}(t, x)\) is space-time white noise, \(v \mapsto b(v)\) and \(v \mapsto \sigma(v)\) Lipschitz.

\section*{Theorem 4 (D. \& E. Nualart, 2004)}

The critical dimension for hitting noints is \(d=4\) and points are polar in this dimension.

The proof uses Malliavin calculus and Cairoli's maximal inequality for multi-parameter martingales.

\section*{Systems 1d nonlinear wave equations}

Let \(\left(u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}\right)\) be an \(\mathbb{R}^{d}\)-valued random field such that \(\frac{\partial^{2}}{\partial t^{2}} u(t, x)=\frac{\partial^{2}}{\partial x^{2}} u(t, x)+b(u(t, x))+\sigma(u(t, x)) \dot{W}(t, x), \quad x \in \mathbb{R}, t>0\),
\(u(0, \cdot), \frac{\partial}{\partial t} u(0, \cdot): \mathbb{R} \rightarrow \mathbb{R}^{d}\) given,
\(\dot{W}(t, x)\) is space-time white noise, \(v \mapsto b(v)\) and \(v \mapsto \sigma(v)\) Lipschitz.

\section*{Theorem 4 (D. \& E. Nualart, 2004)}

The critical dimension for hitting points is \(d=4\) and points are polar in this dimension.

The proof uses Malliavin calculus and Cairoli's maximal inequality for multi-parameter martingales.

\section*{Other nonlinear systems of spde's}

Let \(u=\left\{u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}^{k}\right\}\) be an \(\mathbb{R}^{d}\)-valued continuous process that solves a system of nonlinear heat equations \((k \geqslant 1)\) driven by \(\dot{W}\).

When \(k=1, \dot{W}\) can be space-time white noise: \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s) \delta(x, y)\) When \(k>1, \dot{W}\) is spatially homogeneous: \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}\)

\section*{Theorem 5 (D., Khoshnevisan \& Nualart, 2007, 2013)}

Fix \(\eta>0\). Then
\[
c_{\eta} \operatorname{Cap}_{d-Q+\eta}(A) \leqslant P\{u(I \times J) \cap A \neq \emptyset\} \leqslant C_{\eta} \mathcal{H}_{d-Q-\eta}(A)
\]

Remarks. (a) This is similar to the result of Biermé, Lacaux and Xiao (2007)
(b) In the critical dimension \(d=Q\left(=\frac{4+2 k}{2-\beta}\right)\), this is not informative!
(c) For wave equations \((k \in\{1,2,3\})\) : see D. \& Sanz-Solé, Memoirs AMS 2015, lower bound is less sharp.

\section*{Other nonlinear systems of spde's}

Let \(u=\left\{u(t, x),(t, x) \in \mathbb{R}_{+} \times \mathbb{R}^{k}\right\}\) be an \(\mathbb{R}^{d}\)-valued continuous process that solves a system of nonlinear heat equations \((k \geqslant 1)\) driven by \(\dot{W}\).

When \(k=1, \dot{W}\) can be space-time white noise: \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s) \delta(x, y)\) When \(k>1, \dot{W}\) is spatially homogeneous: \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}\)

\section*{Theorem 5 (D., Khoshnevisan \& Nualart, 2007, 2013)}

Fix \(\eta>0\). Then
\[
c_{\eta} \operatorname{Cap}_{d-Q+\eta}(A) \leqslant P\{u(I \times J) \cap A \neq \emptyset\} \leqslant C_{\eta} \mathcal{H}_{d-Q-\eta}(A)
\]

Remarks. (a) This is similar to the result of Biermé, Lacaux and Xiao (2007). (b) In the critical dimension \(d=Q\left(=\frac{4+2 k}{2-\beta}\right)\), this is not informative!
(c) For wave equations \((k \in\{1,2,3\})\) : see D. \& Sanz-Solé, Memoirs AMS 2015, lower bound is less sharp.

\section*{Polarity of points in dimensions \(>\) the critical dimension}

Case \(k=1, d \geqslant 3\) : let \(\left(W(t), t \in \mathbb{R}_{+}\right)\)be a standard Brownian motion with values in \(\mathbb{R}^{3}\). Want to explain why it does not hit points.



We covered \(W([1,2])\) using a uniform partition of the parameter space \([1,2]\)

\section*{Polarity of points in dimensions \(>\) the critical dimension}

Case \(k=1, d \geqslant 3\) : let \(\left(W(t), t \in \mathbb{R}_{+}\right)\)be a standard Brownian motion with values in \(\mathbb{R}^{3}\). Want to explain why it does not hit points.
Explanation. A.a. points are polar \(\longleftrightarrow \lambda_{d}(W([1,2]))=0\) (Fubini) Let \(t_{k}=1+k 2^{-2 n}\). Then
\[
W([1,2]) \subset \bigcup_{k=1}^{2^{2 n}} B\left(W\left(t_{k}\right), \sup _{\left|t-t_{k}\right| \leqslant 2-2 n}\left|W(t)-W\left(t_{k}\right)\right|\right)
\]
so
\[
\begin{aligned}
\lambda_{d}(W([1,2])) & \leqslant \sum_{k=1}^{2^{2 n}} \lambda_{d}\left(B\left(W\left(t_{k}\right), \sup _{\left|t-t_{k}\right| \leqslant 2^{-2 n}}\left|W(t)-W\left(t_{k}\right)\right|\right)\right) \\
& =\sum_{k=1}^{2^{2 n}}\left[\sup _{\left|t-t_{k}\right| \leqslant 2^{-2 n}}\left|W(t)-W\left(t_{k}\right)\right|\right]^{d} \\
& \leqslant \sum_{k=1}^{2^{2 n}} c\left[n 2^{-n}\right]^{d}=c n^{d} 2^{(2-d) n} \rightarrow 0 \quad \text { a.s. as } n \rightarrow+\infty(\text { because } d \geqslant 3)
\end{aligned}
\]

We covered \(W([1,2])\) using a uniform partition of the parameter space \([1,2]\).

\section*{Polarity of points in dimensions \(>\) the critical dimension}

Case \(k=1, d \geqslant 3\) : let \(\left(W(t), t \in \mathbb{R}_{+}\right)\)be a standard Brownian motion with values in \(\mathbb{R}^{3}\). Want to explain why it does not hit points.
Explanation. A.a. points are polar \(\longleftrightarrow \lambda_{d}(W([1,2]))=0\) (Fubini) Let \(t_{k}=1+k 2^{-2 n}\). Then
\[
W([1,2]) \subset \bigcup_{k=1}^{2^{2 n}} B\left(W\left(t_{k}\right), \sup _{\left|t-t_{k}\right| \leqslant 2^{-2 n}}\left|W(t)-W\left(t_{k}\right)\right|\right)
\]
so
\[
\begin{aligned}
\lambda_{d}(W([1,2])) & \leqslant \sum_{k=1}^{2^{2 n}} \lambda_{d}\left(B\left(W\left(t_{k}\right), \sup _{\left|t-t_{k}\right| \leqslant 2^{-2 n}}\left|W(t)-W\left(t_{k}\right)\right|\right)\right) \\
& =\sum_{k=1}^{2^{2 n}}\left[\sup _{\left|t-t_{k}\right| \leqslant 2^{-2 n}}\left|W(t)-W\left(t_{k}\right)\right|\right]^{d} \\
& \leqslant \sum_{k=1}^{2^{2 n}} c\left[n 2^{-n}\right]^{d}=c n^{d} 2^{(2-d) n} \rightarrow 0 \quad \text { a.s. as } n \rightarrow+\infty(\text { because } d \geqslant 3)
\end{aligned}
\]

We covered \(W([1,2])\) using a uniform partition of the parameter space [1, 2].

\section*{A non-uniform partition}

Let \(X=\left\{X(t), t \in \mathbb{R}^{k}\right\}\), be an \(\mathbb{R}^{d}\)-valued fractional Brownian motion: \(E\left[|X(t)-X(s)|^{2}\right]=d \cdot|t-s|^{2 \alpha}\), where \(0<\alpha<1\).

\section*{Theorem 6 (Talagrand, 1998)}

There are constants \(\delta>0\) and \(K<\infty\) with the following property: Given \(r_{0} \leqslant \delta\) and \(t_{0} \in \mathbb{R}^{k}\), we have


Interpretation. It is quite likely that there will be an \(r>0\) such that increments of \(X\) in the ball centered at \(t_{0}\) of radius \(r\) are smaller than is typical.

Utilization. Many points \(t_{0}\) will have this property, so if \(d=Q(k)(=k / \alpha)\),
then he can use a non-uniform partition and smaller balls to create a covering
\(\rightsquigarrow\) the \(d\)-dimensional Hausdorff measure of the range of \(t \mapsto X(t)\) is 0 .

\section*{A non-uniform partition}

Let \(X=\left\{X(t), t \in \mathbb{R}^{k}\right\}\), be an \(\mathbb{R}^{d}\)-valued fractional Brownian motion: \(E\left[|X(t)-X(s)|^{2}\right]=d \cdot|t-s|^{2 \alpha}\), where \(0<\alpha<1\).

\section*{Theorem 6 (Talagrand, 1998)}

There are constants \(\delta>0\) and \(K<\infty\) with the following property: Given \(r_{0} \leqslant \delta\) and \(t_{0} \in \mathbb{R}^{k}\), we have
\(P\left\{\exists r \in\left[r_{0}^{2}, r_{0}\right]: \sup _{t:\left|t-t_{0}\right| \leqslant r}\left|X(t)-X\left(t_{0}\right)\right| \leqslant K \frac{r^{\alpha}}{\left[\log \log \frac{1}{r}\right]^{\frac{\alpha}{k}}}\right\} \geqslant 1-\exp \left[-\left[\log \frac{1}{r_{0}}\right]^{\frac{1}{2}}\right]\)

Interpretation. It is quite likely that there will be an \(r>0\) such that increments of \(X\) in the ball centered at \(t_{0}\) of radius \(r\) are smaller than is typical.

Utilization. Many points \(t_{0}\) will have this property, so if \(d=Q(k)(=k / \alpha)\), then he can use a non-uniform partition and smaller balls to create a covering \(\rightsquigarrow\) the \(d\)-dimensional Hausdorff measure of the range of \(t \mapsto X(t)\) is 0 .

\section*{A non-uniform partition}

Let \(X=\left\{X(t), t \in \mathbb{R}^{k}\right\}\), be an \(\mathbb{R}^{d}\)-valued fractional Brownian motion: \(E\left[|X(t)-X(s)|^{2}\right]=d \cdot|t-s|^{2 \alpha}\), where \(0<\alpha<1\).

\section*{Theorem 6 (Talagrand, 1998)}

There are constants \(\delta>0\) and \(K<\infty\) with the following property: Given \(r_{0} \leqslant \delta\) and \(t_{0} \in \mathbb{R}^{k}\), we have
\(P\left\{\exists r \in\left[r_{0}^{2}, r_{0}\right]: \sup _{t:\left|t-t_{0}\right| \leqslant r}\left|X(t)-X\left(t_{0}\right)\right| \leqslant K \frac{r^{\alpha}}{\left[\log \log \frac{1}{r}\right]^{\frac{\alpha}{k}}}\right\} \geqslant 1-\exp \left[-\left[\log \frac{1}{r_{0}}\right]^{\frac{1}{2}}\right]\)

Interpretation. It is quite likely that there will be an \(r>0\) such that increments of \(X\) in the ball centered at \(t_{0}\) of radius \(r\) are smaller than is typical.

Utilization. Many points \(t_{0}\) will have this property, so if \(d=Q(k)(=k / \alpha)\), then he can use a non-uniform partition and smaller balls to create a covering \(\rightsquigarrow\) the \(d\)-dimensional Hausdorff measure of the range of \(t \mapsto X(t)\) is 0 .

\section*{Harmonizable representation of fBM}

Talagrand makes essential use of:
Fact. Let \(\dot{W}_{1}\) and \(\dot{W}_{2}\) be independent white noises on \(\mathbb{R}^{k}\). Then
\[
Y(t)=\int_{\mathbb{R}^{k}} \frac{1-\cos \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{1}(d \xi)+\int_{\mathbb{R}^{k}} \frac{\sin \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{2}(d \xi)
\]
is an fBM. (The \(\xi\) plays the role of a frequency.)
Another representation (that looks more like a solution of an spde), such as:


Passing from one to the other: set \(f_{t}(x):=|t-x|^{\alpha-\frac{k}{2}}-|x|^{\alpha-\frac{k}{2}}\), so \(Y(t)=\left\langle\dot{W}, f_{t}\right\rangle=\left\langle\mathcal{F} \dot{W}, \mathcal{F} f_{t}^{v}\right\rangle \stackrel{\operatorname{law}}{=}\left\langle\dot{W}, \mathcal{F} f_{t}^{V}\right\rangle\) and \(\mathcal{F} f_{t}^{\vee}(\xi)=\frac{\exp (i\langle t, \xi\rangle)-1}{|\xi|^{+k}}\). Then take real parts.

\section*{Harmonizable representation of fBM}

Talagrand makes essential use of:
Fact. Let \(\dot{W}_{1}\) and \(\dot{W}_{2}\) be independent white noises on \(\mathbb{R}^{k}\). Then
\[
Y(t)=\int_{\mathbb{R}^{k}} \frac{1-\cos \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{1}(d \xi)+\int_{\mathbb{R}^{k}} \frac{\sin \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{2}(d \xi)
\]
is an fBM. (The \(\xi\) plays the role of a frequency.)
Another representation (that looks more like a solution of an spde), such as:
\[
Y(t):=\int_{\mathbb{R}^{k}}\left(|t-x|^{\alpha-\frac{k}{2}}-|x|^{\alpha-\frac{k}{2}}\right) \dot{W}(d x)
\]

Passing from one to the other: set \(f_{t}(x):=|t-x|^{\alpha-\frac{k}{2}}-|x|^{\alpha-\frac{k}{2}}\), so \(Y(t)=\left\langle\dot{W}, f_{t}\right\rangle=\left\langle\mathcal{W}, \mathcal{W}, \mathcal{F} f_{t}\right\rangle{ }^{\operatorname{lan}}\left\langle\dot{W}, \mathcal{W} f_{t}^{\vee}\right\rangle\) and \(\mathcal{F} f_{t}^{\vee}(\xi)=\frac{\exp (i\langle t, \xi\rangle)-1}{\mid \text { Then take real parts. }}\)

\section*{Harmonizable representation of fBM}

Talagrand makes essential use of:
Fact. Let \(\dot{W}_{1}\) and \(\dot{W}_{2}\) be independent white noises on \(\mathbb{R}^{k}\). Then
\[
Y(t)=\int_{\mathbb{R}^{k}} \frac{1-\cos \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{1}(d \xi)+\int_{\mathbb{R}^{k}} \frac{\sin \langle t, \xi\rangle}{|\xi|^{\alpha+\frac{k}{2}}} \dot{W}_{2}(d \xi)
\]
is an fBM. (The \(\xi\) plays the role of a frequency.)
Another representation (that looks more like a solution of an spde), such as:
\[
Y(t):=\int_{\mathbb{R}^{k}}\left(|t-x|^{\alpha-\frac{k}{2}}-|x|^{\alpha-\frac{k}{2}}\right) \dot{W}(d x)
\]

Passing from one to the other: set \(f_{t}(x):=|t-x|^{\alpha-\frac{k}{2}}-|x|^{\alpha-\frac{k}{2}}\), so
\[
Y(t)=\left\langle\dot{W}, f_{t}\right\rangle=\left\langle\mathcal{F} \dot{W}, \mathcal{F} f_{t}^{\vee}\right\rangle \stackrel{\text { law }}{=}\left\langle\dot{W}, \mathcal{F} f_{t}^{\vee}\right\rangle
\]
and \(\mathcal{F} f_{t}^{\vee}(\xi)=\frac{\exp (i\langle t, \xi\rangle)-1}{|\xi|^{\alpha+\frac{k}{2}}}\). Then take real parts.

\section*{Use of the harmonizable representation}

It has the form
\[
Y(t)=\int_{\mathbb{R}^{k}} F_{t}(\xi) \dot{W}(d \xi),
\]
where \(\xi \mapsto F_{t}(\xi)\) has a specified decay as \(\xi \rightarrow \infty\).
Define a white noise:
\[
A \mapsto Y(A, t):=\int_{A} F_{t}(\xi) \dot{W}(d \xi)
\]

When \(F_{t}(\xi)\) is smooth and has appropriate decay as \(\xi \rightarrow \infty\), it can happen that \(|t-s| \sim 2^{-n / \beta} \Rightarrow Y(t)-Y(s) \sim Y\left(\left[2^{n}, 2^{n+1}[, t)-Y\left(\left[2^{n}, 2^{n+1}[, s)\right.\right.\right.\right.\) "most of the increment of \(Y\) over an interval of length \(2^{-n / \beta}\) comes from the contribution of \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\).

Further, for distinct \(n\), the \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\) are independent!

\section*{Use of the harmonizable representation}

It has the form
\[
Y(t)=\int_{\mathbb{R}^{k}} F_{t}(\xi) \dot{W}(d \xi)
\]
where \(\xi \mapsto F_{t}(\xi)\) has a specified decay as \(\xi \rightarrow \infty\).
Define a white noise:
\[
A \mapsto Y(A, t):=\int_{A} F_{t}(\xi) \dot{W}(d \xi)
\]

When \(F_{t}(\xi)\) is smooth and has appropriate decay as \(\xi \rightarrow \infty\), it can happen that
\[
|t-s| \sim 2^{-n / \beta} \Rightarrow Y(t)-Y(s) \sim Y\left(\left[2^{n}, 2^{n+1}[, t)-Y\left(\left[2^{n}, 2^{n+1}[, s)\right.\right.\right.\right.
\]
"most of the increment of \(Y\) over an interval of length \(2^{-n / \beta}\) comes from the contribution of \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\).

Further, for distinct \(n\), the \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\) are independent!

\section*{Use of the harmonizable representation}

It has the form
\[
Y(t)=\int_{\mathbb{R}^{k}} F_{t}(\xi) \dot{W}(d \xi)
\]
where \(\xi \mapsto F_{t}(\xi)\) has a specified decay as \(\xi \rightarrow \infty\).
Define a white noise:
\[
A \mapsto Y(A, t):=\int_{A} F_{t}(\xi) \dot{W}(d \xi)
\]

When \(F_{t}(\xi)\) is smooth and has appropriate decay as \(\xi \rightarrow \infty\), it can happen that
\[
|t-s| \sim 2^{-n / \beta} \Rightarrow Y(t)-Y(s) \sim Y\left(\left[2^{n}, 2^{n+1}[, t)-Y\left(\left[2^{n}, 2^{n+1}[, s)\right.\right.\right.\right.
\]
"most of the increment of \(Y\) over an interval of length \(2^{-n / \beta}\) comes from the contribution of \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\).

Further, for distinct \(n\), the \(Y\left(\left[2^{n}, 2^{n+1}[, t)\right.\right.\) are independent!

\section*{Extension to a wide class of anisotropic Gaussian processes}

Suppose that
\[
\|v(x)-v(y)\|_{L^{2}} \leqslant C \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}}=: \Delta(x, y)
\]
(the \(\alpha_{j}\) bound the Hölder-exponents of \(x \mapsto v(x)\) )
+ Additional Assumptions (that include a kind of harmonizable representation).
Proposition (D., Mueller \& Xiao)
Let

Under the above assumptions,


\section*{Extension to a wide class of anisotropic Gaussian processes}

Suppose that
\[
\|v(x)-v(y)\|_{L^{2}} \leqslant C \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}}=: \Delta(x, y)
\]
(the \(\alpha_{j}\) bound the Hölder-exponents of \(x \mapsto v(x)\) )
+ Additional Assumptions (that include a kind of harmonizable representation).

\section*{Proposition (D., Mueller \& Xiao)}

Let
\[
Q=\sum_{j=1}^{k} \frac{1}{\alpha_{j}} .
\]

Under the above assumptions,
\[
P\left\{\exists r \in\left[r_{0}^{2}, r_{0}\right]: \sup _{y: \Delta\left(y, x_{0}\right)<r}\left|v(y)-v\left(x_{0}\right)\right| \leqslant \tilde{K} \frac{r}{\left(\log \log \frac{1}{r}\right)^{1 / Q}}\right\} \geqslant 1-\exp \left[-\left[\log \frac{1}{r_{0}}\right]^{\frac{1}{2}}\right]
\]

\section*{Main abstract result}

Let \(v=\left(v(x), x \in \mathbb{R}^{k}\right)\) be a centered continuous \(\mathbb{R}^{d}\)-valued Gaussian random field with i.i.d. components: \(v(x)=\left(v_{1}(x), \ldots, v_{d}(x)\right)\).
Suppose in particular that
\[
c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}} \leqslant\|v(x)-v(y)\|_{L^{2}} \leqslant C \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}}
\]
+ Additional Assumptions.
Recall that the critical dimension is:
\[
Q=\sum_{j=1}^{k} \frac{1}{\alpha_{j}}
\]

\section*{Theorem 1 (D., Mueller \& Xiao)}

Assume that \(Q-d\). Then for any closed box \(J\) and for all \(z \in \mathbb{R}^{Q}\)
\[
P\{\exists x \in J: v(x)=z\}=0 .
\]
(Points are polar for v)

\section*{Main abstract result}

Let \(v=\left(v(x), x \in \mathbb{R}^{k}\right)\) be a centered continuous \(\mathbb{R}^{d}\)-valued Gaussian random field with i.i.d. components: \(v(x)=\left(v_{1}(x), \ldots, v_{d}(x)\right)\).
Suppose in particular that
\[
c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}} \leqslant\|v(x)-v(y)\|_{L^{2}} \leqslant C \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{\alpha_{j}}
\]
+ Additional Assumptions.
Recall that the critical dimension is:
\[
Q=\sum_{j=1}^{k} \frac{1}{\alpha_{j}}
\]

\section*{Theorem 1 (D., Mueller \& Xiao)}

Assume that \(Q=d\). Then for any closed box \(J\) and for all \(z \in \mathbb{R}^{Q}\),
\[
P\{\exists x \in J: v(x)=z\}=0
\]
(Points are polar for \(v\) )

Heat equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{align*}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d  \tag{1}\\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{align*}\right.
\]

Here, \(\hat{v}(t, x)=\left(\hat{v}_{1}(t, x), \ldots, \hat{v}_{d}(t, x)\right)\)
Corollary 1
Suppose \(d=6\) (critical dimension). Then points are polar for \(\hat{v}\)

Proof. Check the Assumptions, using the harmonizable representation

(This representation also appears in R. Balan, 2012). Method also works with smooth deterministic non-constant coefficients.

\section*{Linear systems of stochastic p.d.e.'s}

Heat equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{align*}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d  \tag{1}\\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{align*}\right.
\]

Here, \(\hat{v}(t, x)=\left(\hat{v}_{1}(t, x), \ldots, \hat{v}_{d}(t, x)\right)\)

\section*{Corollary 1}

Suppose \(d=6\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check the Assumptions, using the harmonizable representation

(This representation also appears in R. Balan, 2012). Method also works with smooth deterministic non-constant coefficients.

\section*{Linear systems of stochastic p.d.e.'s}

Heat equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{align*}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d  \tag{1}\\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{align*}\right.
\]

Here, \(\hat{v}(t, x)=\left(\hat{v}_{1}(t, x), \ldots, \hat{v}_{d}(t, x)\right)\)

\section*{Corollary 1}

Suppose \(d=6\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check the Assumptions, using the harmonizable representation
\[
v(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}} e^{-i \xi \cdot x} \frac{e^{-i \tau t}-e^{-t|\xi|^{2}}}{|\xi|^{2}-i \tau} W(d \tau, d \xi)
\]
(This representation also appears in R. Balan, 2012). Method also works with smooth deterministic non-constant coefficients.

\section*{Explanation}

Let \(G(s, y)=(4 \pi t)^{-1 / 2} \exp \left[-y^{2} /(4 t)\right]\), so that
\[
\hat{v}(t, x)=\int_{[0, t] \times \mathbb{R}} G(t-s, x-y) \hat{W}(d s, d y)
\]

\section*{Then}
where

\section*{Explanation}

Let \(G(s, y)=(4 \pi t)^{-1 / 2} \exp \left[-y^{2} /(4 t)\right]\), so that
\[
\hat{v}(t, x)=\int_{[0, t] \times \mathbb{R}} G(t-s, x-y) \hat{W}(d s, d y)
\]

Then
\[
\hat{v}(t, x)=\langle\dot{\hat{W}}, G(t-\cdot, x-\cdot)\rangle=\left\langle\mathcal{F} \dot{\hat{W}}, \mathcal{F} G^{\vee}(t-\cdot, x-\cdot)\right\rangle=\left\langle\text { white noise, } F_{(t, x)}\right\rangle
\]
where
\[
F_{(t, x)}(\tau, \xi)=\mathcal{F}_{s, y} G^{\vee}(t-\cdot, x-\cdot)(\tau, \xi)=e^{-i \xi x} \frac{e^{-i \tau t}-e^{-t|\xi|^{2}}}{|\xi|^{2}-i \tau}
\]

\section*{Checking the Assumptions}

For \(A \subset \mathbb{R}\), set
\[
v(A, t, x):=\iint_{\max \left(|\tau|^{\frac{1}{4}},|\xi|^{\frac{1}{2}}\right) \in A} e^{-i \xi x} \frac{e^{-i \tau t}-e^{-t \xi^{2}}}{\xi^{2}-i \tau} W(d \tau, d \xi),
\]

Need to check:
\[
\| v\left(\left[0, a^{2}, t, x\right)-v\left(\left[0, a[, s, y) \|_{L^{2}} \leqslant c_{0}\left[a^{3}|t-s|+a|x-y|\right]\right.\right.\right.
\]
where \(3=\left(\frac{1}{4}\right)^{-1}-1\) and \(1=\left(\frac{1}{2}\right)^{-1}-1\), and
\[
\| v\left(\left[b, \infty[, t, x)-v\left(\left[b, \infty[, s, y) \|_{L^{2}} \leqslant c_{0} b^{-1}\right.\right.\right.\right.
\]

Proving the inequality requires estimating double integrals.

\section*{Checking the Assumptions}

For \(A \subset \mathbb{R}\), set
\[
v(A, t, x):=\iint_{\max \left(|\tau|^{\frac{1}{4}},|\xi|^{\frac{1}{2}}\right) \in A} e^{-i \xi x} \frac{e^{-i \tau t}-e^{-t \xi^{2}}}{\xi^{2}-i \tau} W(d \tau, d \xi)
\]

Need to check:
\[
\| v\left(\left[0, a[, t, x)-v\left(\left[0, a[, s, y) \|_{L^{2}} \leqslant c_{0}\left[a^{3}|t-s|+a|x-y|\right]\right.\right.\right.\right.
\]
where \(3=\left(\frac{1}{4}\right)^{-1}-1\) and \(1=\left(\frac{1}{2}\right)^{-1}-1\), and
\[
\| v\left(\left[b, \infty[, t, x)-v\left(\left[b, \infty[, s, y) \|_{L^{2}} \leqslant c_{0} b^{-1}\right.\right.\right.\right.
\]

Proving the inequality requires estimating double integrals.

Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}^{k}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\sigma_{j}(t, x) \dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d \\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{aligned}\right.
\]

The harmonizable representation is:
\[
v_{j}(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}^{k}} W_{j}(d \tau, d \xi)\left(\mathcal{F}_{s, y} \tilde{G}_{t, x} * \mathcal{F}_{s, y} \sigma_{j}\right)(\tau, \xi) .
\]

Assumption. \(\mathcal{F}_{s, y} \sigma_{j}\) is a measure \(\mu_{j}\) with compact support (i.e. \(\sigma\) is much smoother than the noise)

\section*{Linear systems of stochastic heat equations with nonconstant coefficients}

Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}^{k}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\sigma_{j}(t, x) \dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d \\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{aligned}\right.
\]

The harmonizable representation is:
\[
v_{j}(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}^{k}} W_{j}(d \tau, d \xi)\left(\mathcal{F}_{s, y} \tilde{G}_{t, x} * \mathcal{F}_{s, y} \sigma_{j}\right)(\tau, \xi)
\]

Assumption. \(\mathcal{F}_{s, y} \sigma_{j}\) is a measure \(\mu_{j}\) with compact support (i.e. \(\sigma\) is much smoother than the noise).

\section*{Linear systems of stochastic p.d.e.'s (2)}

Heat equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise:
\(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2 \wedge k)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}^{k}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d \\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{aligned}\right.
\]

Corollary 2
Sunnose \(d=\frac{4+2 k}{2-8}\) (critical dimension). Then points are polar for \(\hat{v}\)

Proof. Check Assumptions, using the harmonizable representation


\section*{Linear systems of stochastic p.d.e.'s (2)}

Heat equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise:
\(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2 \wedge k)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}^{k}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d \\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{aligned}\right.
\]

\section*{Corollary 2}

Suppose \(d=\frac{4+2 k}{2-\beta}\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check Assumptions, using the harmonizable representation


\section*{Linear systems of stochastic p.d.e.'s (2)}

Heat equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise:
\(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2 \wedge k)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}^{k}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial}{\partial t} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), \quad j=1, \ldots, d \\
v(0, x) & =0, \quad x \in \mathbb{R}^{k}
\end{aligned}\right.
\]

\section*{Corollary 2}

Suppose \(d=\frac{4+2 k}{2-\beta}\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check Assumptions, using the harmonizable representation
\[
v(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}^{k}} e^{-i \xi \cdot x} \frac{e^{-i \tau t}-e^{-t|\xi|^{2}}}{|\xi|^{2}-i \tau}|\xi|^{(\beta-k) / 2} W(d \tau, d \xi)
\]

Wave equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}
\end{aligned}\right.
\]

\section*{Corollary 3}

Sunnose \(d=4\) (critical dimension). Then points are polar for \(\hat{v}\)

Proof. Check Assumptions, using the harmonizable representation

(This representation also appears in R. Balan, 2012)

Wave equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}
\end{aligned}\right.
\]

\section*{Corollary 3}

Suppose \(d=4\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check Assumptions, using the harmonizable representation

(This representation also appears in R. Balan, 2012).

Wave equations, spatial dimension 1, space-time white noise
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{aligned}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\frac{\partial^{2}}{\partial x^{2}} \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}
\end{aligned}\right.
\]

\section*{Corollary 3}

Suppose \(d=4\) (critical dimension). Then points are polar for \(\hat{v}\).

Proof. Check Assumptions, using the harmonizable representation
\[
v(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}} \frac{e^{-i \xi \cdot x-i \tau t}}{2|\xi|}\left[\frac{1-e^{i t(\tau+|\xi|)}}{\tau+|\xi|}-\frac{1-e^{i t(\tau-|\xi|)}}{\tau-|\xi|}\right] W(d \tau, d \xi)
\]
(This representation also appears in R. Balan, 2012).

Wave equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{array}{rlrl}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}^{k}
\end{array}\right.
\]

\section*{Corollary 4}

Suppose
polar for \(\hat{v}\)

\section*{and \(d=\frac{2(k+1)}{2-\beta}\) (critical dimension). Then points are}

Proof. Check Assumptions, using the harmonizable representation


\section*{Linear systems of stochastic p.d.e.'s (4)}

Wave equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{array}{rlrl}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}^{k}
\end{array}\right.
\]

\section*{Corollary 4}

Suppose \(1<\beta<k \wedge 2\), and \(d=\frac{2(k+1)}{2-\beta}\) (critical dimension). Then points are polar for \(\hat{v}\),

Proof. Check Assumptions, using the harmonizable representation


\section*{Linear systems of stochastic p.d.e.'s (4)}

Wave equations, spatial dimension \(k \geqslant 1\), spatially homogeneous noise \(E[\dot{W}(t, x) \dot{W}(s, y)]=\delta(t-s)\|x-y\|^{-\beta}(0<\beta<2)\)
Let \(\hat{v}=\left(\hat{v}(t, x), t \in \mathbb{R}_{+}, x \in \mathbb{R}\right)\) solve
\[
\left\{\begin{array}{rlrl}
\frac{\partial^{2}}{\partial t^{2}} \hat{v}_{j}(t, x) & =\Delta \hat{v}_{j}(t, x)+\dot{\hat{W}}_{j}(t, x), & & j=1, \ldots, d \\
\hat{v}(0, x) & =0, \quad \frac{\partial}{\partial t} \hat{v}(0, x)=0, & x \in \mathbb{R}^{k}
\end{array}\right.
\]

\section*{Corollary 4}

Suppose \(1<\beta<k \wedge 2\), and \(d=\frac{2(k+1)}{2-\beta}\) (critical dimension). Then points are polar for \(\hat{v}\),

Proof. Check Assumptions, using the harmonizable representation
\[
v(t, x)=\int_{\mathbb{R}} \int_{\mathbb{R}} \frac{e^{-i \xi \cdot x-i \tau t}}{2|\xi|}\left[\frac{1-e^{i t(\tau+|\xi|)}}{\tau+|\xi|}-\frac{1-e^{i t(\tau-|\xi|)}}{\tau-|\xi|}\right]|\xi|^{(\beta-k) / 2} W(d \tau, d \xi)
\]

\section*{Reference and ongoing work}

\section*{References.}

Dalang, R.C., Khoshnevisan, D. and Nualart, E., Hitting probabilities for systems of non-linear stochastic heat equations in spatial dimension \(k \geqslant 1\). Journal of SPDE's: Analysis and Computations 1-1 (2013), 94-151.

Dalang, R.C. and Sanz-Solé, Hitting probabilities for non-linear systems of stochastic waves. Memoirs of the American Math. Soc. 237 no. 1120 (2015), 1-75.

Dalang, R.C., Mueller, C. \& Xiao, Y. Polarity of points for Gaussian random fields (Preprint 2015). ArXiv 1505.05417.

Talagrand, M. Multiple points of trajectories of multiparameter fractional Brownian motion. Probab. Theory Related Fields 112-4 (1998), 545-563.

Ongoing:
Multiple points in critical dimensions (linear systems of spde's)

Polarity of points in critical dimensions for nonlinear systems of spde's.

\section*{Reference and ongoing work}

\section*{References.}

Dalang, R.C., Khoshnevisan, D. and Nualart, E., Hitting probabilities for systems of non-linear stochastic heat equations in spatial dimension \(k \geqslant 1\). Journal of SPDE's: Analysis and Computations 1-1 (2013), 94-151.
Dalang, R.C. and Sanz-Solé, Hitting probabilities for non-linear systems of stochastic waves. Memoirs of the American Math. Soc. 237 no. 1120 (2015), 1-75.

Dalang, R.C., Mueller, C. \& Xiao, Y. Polarity of points for Gaussian random fields (Preprint 2015). ArXiv 1505.05417.

Talagrand, M. Multiple points of trajectories of multiparameter fractional Brownian motion. Probab. Theory Related Fields 112-4 (1998), 545-563.

\section*{Ongoing:}

Multiple points in critical dimensions (linear systems of spde's).
Polarity of points in critical dimensions for nonlinear systems of spde's.```

