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The Effect of Gaussian White Noise on Dynamical Systems: Bifurcations in Slow–Fast Systems

Barbara Gentz

University of Bielefeld, Germany

Barbara Gentz

gentz@math.uni-bielefeld.de

http://www.math.uni-bielefeld.de/~gentz

Slowly driven systems in dimension n = 1

Bifurcations in Slow-Fast Systems

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Saddle-nod

MMOs

Slowly driven systems

Recall from yesterday's lecture

Parameter dependent ODE, perturbed by Gaussian white noise

$$dx_s = \tilde{f}(x_s, \lambda) ds + \sigma dW_s \qquad (x_s \in \mathbb{R}^1)$$

Assume parameter varies slowly in time: $\lambda = \lambda(\varepsilon s)$

$$\mathrm{d} x_s = ilde{f}(x_s,\lambda(arepsilon s))\,\mathrm{d} s + \sigma\,\mathrm{d} W_s$$

Rewrite in slow time $t = \varepsilon s$

$$\mathsf{d} \mathsf{x}_t = rac{1}{arepsilon} f(\mathsf{x}_t, t) \, \mathsf{d} t + rac{\sigma}{\sqrt{arepsilon}} \, \mathsf{d} W_t$$

Assumptions yesterday

Existence of a uniformly asymptotically stable equilibrium branch $x^{\star}(t)$

$$\exists ! \, x^\star : I
ightarrow \mathbb{R}$$
 s.t. $f(x^\star(t), t) = 0$

and

$$a^{\star}(t) = \partial_{x}f(x^{\star}(t), t) \leqslant -a_{0} < 0$$

Then there exists an adiabatic solution $\bar{x}(t,\varepsilon)$

$$\bar{x}(t,\varepsilon) = x^{\star}(t) + \mathcal{O}(\varepsilon)$$

and $\bar{x}(t,\varepsilon)$ attracts nearby solutions exp. fast



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Defining the strip describing the typical spreading

- ▷ Let v(t) be the variance of the solution z(t) of the linearized SDE for the deviation $x_t \bar{x}(t, \varepsilon)$
- $\triangleright v(t)/\sigma^2$ is solution of a deterministic slowly driven system admitting a uniformly asymptotically stable equilibrium branch
- ▷ Let $\zeta(t)$ be the adiabatic solution of this system
- $\triangleright \ \zeta(t) \approx 1/|a(t)|, \text{ where } a(t) = \partial_x f(\bar{x}(t,\varepsilon),t) \leq -a_0/2 < 0$

Define a strip $\mathcal{B}(h)$ around $\bar{x}(t,\varepsilon)$ of width $\simeq h\sqrt{\zeta(t)}$ and the first-exit time $\tau_{\mathcal{B}(h)}$

$$\mathcal{B}(h) = \{(x, t) \colon |x - \bar{x}(t, \varepsilon)| < h\sqrt{\zeta(t)}\}$$

$$\tau_{\mathcal{B}(h)} = \inf\{t > 0 \colon (x_t, t) \notin \mathcal{B}(h)\}$$

Concentration of sample paths



Theorem [Berglund & G '02, '05]

$$\mathbb{P}\big\{\tau_{\mathcal{B}(h)} < t\big\} \leq \textit{const}\,\frac{1}{\varepsilon}\Big|\int_0^t \mathsf{a}(s)\,\mathsf{d}s\Big|\,\,\frac{h}{\sigma}\,\,\mathsf{e}^{-h^2[1-\mathcal{O}(\varepsilon)-\mathcal{O}(h)]/2\sigma^2}$$

Avoided bifurcation: Stochastic Resonance

Overdamped motion of a Brownian particle in a periodically modulated potential

$$egin{aligned} & \mathsf{d} \mathsf{x}_t = -rac{1}{arepsilon} rac{\partial}{\partial \mathsf{x}} \mathsf{V}(\mathsf{x}_t,t) \; \mathsf{d} \mathsf{s} + rac{\sigma}{\sqrt{arepsilon}} \, \mathsf{d} \mathsf{W}_t \ & \mathsf{V}(\mathsf{x},t) = -rac{1}{2} \mathsf{x}^2 + rac{1}{4} \mathsf{x}^4 + (\lambda_\mathrm{c} - \mathsf{a}_0) \cos(2\pi t) \mathsf{x} \end{aligned}$$



Saddle-node

Sample paths

Amplitude of modulation $A = \lambda_c - a_0$ Speed of modulation ε Noise intensity σ



$$A=$$
 0.00, $\sigma=$ 0.30, $arepsilon=$ 0.001



A= 0.10, $\sigma=$ 0.27, arepsilon= 0.001





Different parameter regimes and stochastic resonance

Synchronisation I

- ▷ For matching time scales: $2\pi/\varepsilon = T_{\text{forcing}} = 2 T_{\text{Kramers}} \asymp e^{2H/\sigma^2}$
- Quasistatic approach: Transitions twice per period likely (physics' literature; [Freidlin '00], [Imkeller *et al*, since '02])
- Requires exponentially long forcing periods

Synchronisation II

- ▷ For intermediate forcing periods: $T_{\text{relax}} \ll T_{\text{forcing}} \ll T_{\text{Kramers}}$ and close-to-critical forcing amplitude: $A \approx A_{c}$
- Transitions twice per period with high probability
- Subtle dynamical effects: Effective barrier heights [Berglund & G '02]

SR outside synchronisation regimes

- Only occasional transitions
- But transition times localised within forcing periods

Synchronisation regime II

Characterised by 3 small parameters: $0 < \sigma \ll 1$, $0 < \varepsilon \ll 1$, $0 < a_0 \ll 1$



Seeds

Effective barrier heights and scaling of small parameters

Theorem [Berglund & G '02] (informal version; exact formulation uses first-exit times)

 \exists threshold value $\sigma_{
m c} = (a_0 \lor arepsilon)^{3/4}$

Below: $\sigma \leq \sigma_{\rm c}$

- Transitions unlikely; sample paths concentrated in one well
- $\label{eq:typical spreading} \succ \begin{array}{l} \text{Typical spreading} \end{array} \asymp \begin{array}{l} \frac{\sigma}{\left(|t|^2 \lor a_0 \lor \varepsilon\right)^{1/4}} \asymp \begin{array}{l} \frac{\sigma}{\left(\text{curvature}\right)^{1/2}} \\ \end{array}$ $\label{eq:typical spreading} \label{eq:typical spreading} \begin{tabular}{l} \text{Probability to observe a transition} \\ \leq e^{-const} \sigma_c^2 / \sigma^2 \end{array}$

Above: $\sigma \gg \sigma_{\rm c}$

- 2 transitions per period likely (back and forth)
- $\,\triangleright\,$ with probability $\,\geq 1 {
 m e}^{- {\it const}}\, \sigma^{4/3}/ \varepsilon |{
 m log}\,\sigma|$
- $\,\,
 m \sim\,$ Transitions occur near instants of minimal barrier height; window $\,\,pprox\,\sigma^{2/3}$

Deterministic dynamics



- ▷ For $t \le -const$: x_{+}^{det} reaches ε -nbhd of $x_{+}^{*}(t)$
 - in time $\approx \varepsilon |\log \varepsilon|$ (Tihonov '52)
- $\label{eq:formula} \begin{array}{l} \triangleright \ \ \mathsf{For} \ -const \ \leq t \leq -(a_0 \lor \varepsilon)^{1/2} : \\ x_t^{\mathsf{det}} x_+^\star(t) \asymp \varepsilon/|t| \end{array}$
- ▷ For $|t| \le (a_0 \lor \varepsilon)^{1/2}$: $x_t^{\text{det}} - x_0^*(t) ≍ (a_0 \lor \varepsilon)^{1/2} \ge \sqrt{\varepsilon}$ (effective barrier height)
- $\begin{tabular}{l} & \mathsf{For} \; (a_0 \lor \varepsilon)^{1/2} \le t \le + const : \\ & x_t^{\mathsf{det}} x_+^*(t) \asymp \varepsilon / |t| \end{tabular}$
- $\begin{tabular}{l} \begin{tabular}{l} \begin{tab$

Below threshold: $\sigma \leq \sigma_{\rm c} = (a_0 \lor \varepsilon)^{3/4}$



$$v(t) \sim rac{\sigma^2}{ ext{curvature}} \sim rac{\sigma^2}{(|t|^2 \lor a_0 \lor arepsilon)^{1/2}}$$

Approach for stable case can still be used

$$C(h/\sigma,t,\varepsilon)\,\mathrm{e}^{-\boldsymbol{\kappa}_{-}\,h^{2}/2\sigma^{2}} \leq \mathbb{P}\big\{\tau_{\mathcal{B}(h)} < t\big\} \leq C(h/\sigma,t,\varepsilon)\,\mathrm{e}^{-\boldsymbol{\kappa}_{+}\,h^{2}/2\sigma^{2}}$$

with $\kappa_+ = 1 - \mathcal{O}(\varepsilon) - \mathcal{O}(h)$, $\kappa_- = 1 + \mathcal{O}(\varepsilon) + \mathcal{O}(h) + \mathcal{O}(e^{-c_2 t/\varepsilon})$

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Above threshold: $\sigma \gg \sigma_{\rm c} = (a_0 \vee \varepsilon)^{3/4}$



- ▷ Typical paths stay below $x_t^{det} + h\sqrt{\zeta(t)}$
- \triangleright For $t \ll -\sigma^{2/3}$:

Transitions unlikely; as below threshold

- ▷ At time $t = -\sigma^{2/3}$: Typical spreading is $\sigma^{2/3} \gg x_t^{det} - x_0^{\star}(t)$ Transitions become likely
- ▷ Near saddle:

Diffusion dominated dynamics

- $\triangleright \ \delta_1 > \delta_0$ with f symp -1 ;
 - δ_0 in domain of attraction of $x_-^{\star}(t)$

Drift dominated dynamics

 \triangleright Below δ_0 : behaviour as for small σ

Above threshold: $\sigma \gg \sigma_{\rm c} = (a_0 \vee \varepsilon)^{3/4}$



Idea of the proof

With probability $\geq \delta >$ 0, in time $\asymp \varepsilon |{\log \sigma}|/{\sigma^{2/3}}$, the path reaches

- $\triangleright x_t^{det}$ if above
- then the saddle
- \triangleright finally the level δ_1

In time $\sigma^{2/3}$ there are $\frac{\sigma^{4/3}}{\varepsilon |\log \sigma|}$ attempts possible During a subsequent timespan of length ε , level δ_0 is reached (with probability $\geq \delta$)

Finally, the path reaches the new well

Result

 $\mathbb{P}\big\{x_s > \delta_0 \quad \forall s \in [-\sigma^{2/3}, t]\big\} \le e^{-const |\sigma^{4/3}/\varepsilon|\log \sigma|} \quad (t \ge -\gamma \sigma^{2/3}, \gamma \text{ small})$

Space-time sets for stochastic resonance



Below threshold



Above threshold

Saddle-node bifurcation

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Saddle–node bifurcation (e.g. $f(x, t) = -t - x^2$)

$$\sigma \ll \sigma_{\rm c} = \varepsilon^{1/2}$$

$$\sigma \gg \sigma_{\rm c} = \varepsilon^{1/2}$$



 $\sigma=$ 0: Solutions stay at distance $\varepsilon^{1/3}$ above bif. point until time $\varepsilon^{2/3}$ after bif. Theorem

- ▷ If $\sigma \ll \sigma_c$: Paths likely to stay in $\mathcal{B}(h)$ until time $\varepsilon^{2/3}$ after bifurcation; maximal spreading $\sigma/\varepsilon^{1/6}$.
- ▷ If $\sigma \gg \sigma_c$: Transition typically for $t \asymp -\sigma^{4/3}$; transition probability $\ge 1 - e^{-c\sigma^2/\varepsilon |\log \sigma|}$

Mixed-mode oscillations

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Saddle-node

Mixed-Mode Oscillations (MMOs)

Belousov–Zhabotinsky reaction



Recording from bromide ion electrode; T= 25° C; flow rate = 3.99 ml/min; Ce⁺³ catalyst [Hudson, Hart, Marinko '79]

Saddle-nod

MMOs

MMOs in Biology

Layer II Stellate Cells



D: subthreshold membrane potential oscillations (1 and 2) and spike clustering (3) develop at increasingly depolarized membrane potential levels positive to about -55 mV. Autocorrelation function (*inset* in 1) demonstrates the rhythmicity of the subthreshold oscillations [Dickson *et al* '00]

Questions: Origin of small-amplitude oscillations? Source of irregularity in pattern?

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MMOs & Slow–Fast Systems

Observation

MMOs can be observed in slow-fast systems undergoing a folded-node bifurcation (1 fast, 2 slow variables)

Normal form of folded-node (bif) [Benoît, Lobry '82; Szmolyan, Wechselberger '01]

$$\begin{aligned} \epsilon \dot{x} &= y - x^2 \\ \dot{y} &= -(\mu + 1)x - z \\ \dot{z} &= \frac{\mu}{2} \end{aligned}$$

Questions:Dynamics for small $\varepsilon > 0$?Effect of noise?

MMOs & Slow–Fast Systems

Observation

MMOs can be observed in slow-fast systems undergoing a folded-node bifurcation (1 fast, 2 slow variables)

Normal form of folded-node (bif) [Benoît, Lobry '82; Szmolyan, Wechselberger '01]

$$\begin{aligned} \epsilon \dot{x} &= y - x^2 + \text{noise} \\ \dot{y} &= -(\mu + 1)x - z + \text{noise} \\ \dot{z} &= \frac{\mu}{2} \end{aligned}$$

Questions:Dynamics for small $\varepsilon > 0$?Effect of noise?

Folded-Node Bifurcation: Slow Manifold

 $\begin{aligned} \epsilon \dot{x} &= y - x^2 \\ \dot{y} &= -(\mu + 1)x - z \\ \dot{z} &= \frac{\mu}{2} \end{aligned}$



Slow manifold has a decomposition

$$\mathcal{C}_0 = \{(x, y, z) \in \mathbb{R}^3 \colon y = x^2\} = \mathcal{C}_0^a \cup L \cup \mathcal{C}_0^r$$

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Folded-Node: Adiabatic Manifolds and Canard Solutions



Assume

- $\triangleright \ \varepsilon$ sufficiently small
- $\triangleright \ \mu \in (0,1) \text{, } \mu^{-1} \not \in \mathbb{N}$

Theorem [Benoît, Lobry '82; Szmolyan, Wechselberger '01; Wechselberger '05; Brøns, Krupa, Wechselberger '06]

Bifurcations in Slow-Fast Systems

Folded-Node: Adiabatic Manifolds and Canard Solutions



Assume

- $\triangleright \ \varepsilon$ sufficiently small
- $\triangleright \ \mu \in (0,1)$, $\mu^{-1}
 ot\in \mathbb{N}$

Theorem

- $\stackrel{\scriptstyle \triangleright}{} \mbox{ Existence of strong and} \\ \mbox{ weak (maximal) canard } \gamma_{\varepsilon}^{\rm s,w}$
- $\stackrel{\triangleright}{\exists} \frac{2k+1}{k} < \mu^{-1} < 2k+3:$ $\frac{\exists}{k} \text{ secondary canards } \gamma_{\varepsilon}^{j}$
- $\stackrel{\scriptstyle \triangleright}{} \gamma_{\varepsilon}^{j} \text{ makes } (2j+1)/2 \\ \text{ oscillations around } \gamma_{\varepsilon}^{\mathrm{w}}$

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Folded-Node: Canard Spacing



Lemma For z = 0: Distance between canards γ_{ε}^{k} and $\gamma_{\varepsilon}^{k+1}$ is $\mathcal{O}(e^{-c_{0}(2k+1)^{2}\mu})$

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Stochastic Folded Nodes: Concentration of Sample Paths

Theorem [Berglund, G & Kuehn, JDE '12]

$$\mathbb{P}\big\{\tau_{\mathcal{B}(h)} < z\big\} \leqslant C(z_0, z) \exp\bigg\{-\kappa \frac{h^2}{2\sigma^2}\bigg\} \qquad \forall z \in [z_0, \sqrt{\mu}]$$

For z = 0:

- ▷ Distance between canards γ_{ε}^{k} and $\gamma_{\varepsilon}^{k+1}$ is $\mathcal{O}(e^{-c_{0}(2k+1)^{2}\mu})$
- ▷ Section of $\mathcal{B}(h)$ is close to circular with radius $\mu^{-1/4}h$
- \triangleright Noisy canards become indistinguishable when typical radius $\mu^{-1/4}\sigma\approx$ distance



Canards or Pasta ...?



Noisy Small-Amplitude Oscillations

Theorem

Canards with $\frac{2k+1}{2}$ oscillations become indistinguishable from noisy fluctuations for

 $\sigma > \sigma_k(\mu) = \mu^{1/4} e^{-(2k+1)^2 \mu}$



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(a)

0.5

(b)

Early Escape



-0.005

0.015

Mixed-Mode Oscillations in the Presence of Noise



Observations

- Noise smears out small-amplitude oscillations
- Early transitions modify the mixed-mode pattern

Stochastic resonance

Saddle-node

MMOs



Nils Berglund, Orléans

Christian Kuehn, Vienna

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Saddle-nod

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MMOs

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