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Barbara Gentz

Noise-Induced Phenomena in Slow–Fast Dynamical Systems

Joint work with Nils Berglund (CPT-CNRS Marseille)



WIAS Berlin, Germany

Introduction: Small random perturbations of ODEs



Questions

▷ Transition times? Where do transitions typically occur?

Answers

- Mean first-exit times and locations can be obtained exactly from PDEs (via infinitesimal generators of the diffusion)
- > Exponential asymptotics provided by Wentzell–Freidlin theory (via variational principle)
- ▷ Rigorous proof of subexponential asymptotics for reversible diffusions is recent (n > 1)[Bovier, Eckhoff, Gayrard & Klein, 2004/05]

Fully coupled stochastic differential equations on two well-separated time scales

$$\begin{cases} dx_t = \frac{1}{\varepsilon} f(x_t, y_t) dt + \frac{\sigma}{\sqrt{\varepsilon}} F(x_t, y_t) dW_t & \text{(fast variables } \in \mathbb{R}^n\text{)} \\ dy_t = g(x_t, y_t) dt + \sigma' G(x_t, y_t) dW_t & \text{(slow variables } \in \mathbb{R}^m\text{)} \end{cases}$$

where

 $\triangleright \{W_t\}_{t \ge 0}$ k-dimensional standard Brownian motion

 $\triangleright \ \mathcal{D} \subset \mathbb{R}^{n} \times \mathbb{R}^{m}$

 $\triangleright f: \mathcal{D} \to \mathbb{R}^n, \qquad g: \mathcal{D} \to \mathbb{R}^m \quad \text{ drift coefficients, } \in \mathcal{C}^2$

 $\triangleright F: \mathcal{D} \to \mathbb{R}^{n \times k}, \ G: \mathcal{D} \to \mathbb{R}^{m \times k} \text{ diffusion coefficients, } \in \mathcal{C}^1$

Note diffusive scaling: $\operatorname{Var}\left(\frac{\sigma}{\sqrt{\varepsilon}}\int_{0}^{t}F(x_{s},y_{s}) \,\mathrm{d}W_{s}\right) = \frac{\sigma^{2}}{\varepsilon}\int_{0}^{t}\mathbb{E}\left(F(x_{s},y_{s})^{2}\right) \,\mathrm{d}s$ (for k=n=1)

Small parameters

 $\varepsilon > 0 \quad \text{adiabatic parameter (no quasistatic approach)}$ $\varepsilon ~ \sigma, \sigma' \ge 0 \quad \text{noise intensities; may depend on } \varepsilon : \quad \sigma = \sigma(\varepsilon), \quad \sigma' = \sigma'(\varepsilon) \quad \text{and } \sigma'(\varepsilon) / \sigma(\varepsilon) = \varrho(\varepsilon) \leqslant 1$

Time scales

▷ Aiming at regime
$$T_{\text{relax}} = \mathcal{O}(\varepsilon) \ll T_{\text{driving}} = 1 \ll T_{\text{Kramers}} = \varepsilon e^{\overline{V}/\sigma^2}$$
 (in slow time)

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Existence of a slow manifold

 $\exists \mathcal{D}_0 \subset \mathbb{R}^m \quad \exists x^\star : \mathcal{D}_0 \to \mathbb{R}^n \qquad \text{s.t.} \qquad (x^\star(y), y) \in \mathcal{D} \quad \text{and} \quad f(x^\star(y), y) = 0 \qquad \text{on} \ \mathcal{D}_0$

Slow manifold is attracting

Eigenvalues of $A^{\star}(y) \coloneqq \partial_x f(x^{\star}(y), y)$ satisfy $\operatorname{Re} \lambda_i(y) \leqslant -a_0 < 0$, uniformly on \mathcal{D}_0

Theorem [Tihonov 1952, Fenichel 1979]

There exists an *adiabatic manifold* : $\exists \bar{x}(y, \varepsilon)$ s.t.

- $\triangleright \ \bar{x}(y,\varepsilon) \$ is an invariant manifold for the deterministic flow
- $\triangleright \ \bar{x}(y,\varepsilon) \ \ \text{attracts nearby (deterministic) solutions}$

$$\triangleright \ \bar{x}(y,0) = x^\star(y) \ \text{ and } \ \bar{x}(y,\varepsilon) = x^\star(y) + \mathcal{O}(\varepsilon)$$

Consider now *stochastic* system under these assumptions



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Noisy slow-fast systems: Defining typical neighbourhoods of adiabatic manifolds

- \triangleright Consider deterministic process $(x_t^{det} = \bar{x}(y_t^{det}, \varepsilon), y_t^{det})$ on (invariant) adiabatic manifold
- \triangleright Deviation $\xi_t \coloneqq x_t x_t^{det}$ of random fast variables from adiabatic manifold
- \triangleright Linearize SDE for ξ_t
- \triangleright Resulting process ξ_t^0 is Gaussian

Key observation

 $\frac{1}{\sigma^2}$ Cov ξ_t^0 is a particular solution of the deterministic slow–fast system

$$\begin{cases} \varepsilon \dot{X}(t) = A(y_t^{\text{det}})X(t) + X(t)A(y^{\text{det}})^T + F_0(y^{\text{det}})F_0(y^{\text{det}})^T \\ \dot{y}_t^{\text{det}} = g(\bar{x}(y_t^{\text{det}},\varepsilon), y_t^{\text{det}}) \end{cases}$$

where $A(y) = \partial_x f(\bar{x}(y,\varepsilon),y)$ and F_0 is zeroth-order approximation to F

 $\triangleright\,$ System admits an adiabatic manifold $\,\overline{X}(y,\varepsilon)$

Typical neighbourhoods

$$\mathcal{B}(h) \coloneqq \left\{ (x, y) \colon \left\langle \left[x - \bar{x}(y, \varepsilon) \right], \overline{X}(y, \varepsilon)^{-1} \left[x - \bar{x}(y, \varepsilon) \right] \right\rangle < h^2 \right\}$$

Noisy slow-fast systems: Concentration of sample paths near adiabatic manifolds

Define (random) first-exit times

 $\tau_{\mathcal{D}_0} := \inf\{s > 0 \colon y_s \notin \mathcal{D}_0\} \\ \tau_{\mathcal{B}(h)} := \inf\{s > 0 \colon (x_s, y_s) \notin \mathcal{B}(h)\}$



Theorem [Berglund & G, J. Differential Equations, 2003] Assume: $\|\overline{X}(y,\varepsilon)\|$, $\|\overline{X}(y,\varepsilon)^{-1}\|$ are uniformly bounded in \mathcal{D}_0 Then: $\exists \varepsilon_0 > 0 \quad \exists h_0 > 0 \quad \forall \varepsilon \leqslant \varepsilon_0 \quad \forall h \leqslant h_0$

$$\mathbb{P}\left\{\tau_{\mathcal{B}(h)} < \min(t, \tau_{\mathcal{D}_0})\right\} \leqslant C_{n,m}(t) \exp\left\{-\frac{h^2}{2\sigma^2} \left[1 - \mathcal{O}(h) - \mathcal{O}(\varepsilon)\right]\right\}$$

where $C_{n,m}(t) = \left[C^m + h^{-n}\right] \left(1 + \frac{t}{\varepsilon^2}\right)$

Remarks

- Bound is sharp: Lower bound similar
- \triangleright If initial condition not on $\bar{x}(y, \varepsilon)$: additional transitional phase
- ▷ On longer time scales: Behaviour of slow variables becomes crucial (Assumptions on g)

Question

What happens if (x_t, y_t) approaches a bifurcation point (\hat{x}, \hat{y}) for the deterministic dynamics?

Example: Saddle-node bifurcation



General approach

- Apply centre-manifold theorem
- Concentration results for deviation from centre manifold [Berglund & G, 2003]
- Consider reduced dynamics on centre manifold
- Concentration results for deviation of reduced system from original variables [Berglund & G, 2003]

Interesting phenomena for one-dimensional reduced dynamics

- Reduction of bifurcation delay due to noise
- Stochastic resonance
- Effect of noise on the size of hysteresis cycles

Overdamped motion of a Brownian particle in a periodically modulated double-well potential

$$dx_t = -\frac{1}{\varepsilon} \frac{\partial}{\partial x} V(x_t, t) dt + \frac{\sigma}{\sqrt{\varepsilon}} dW_t \quad \text{with} \quad V(x, t) = \frac{1}{4} x^4 - \frac{1}{2} x^2 - A\cos(t)x \quad \text{(where } A < A_c\text{)}$$

Simulations



Sample paths behaviour for stochastic resonance



Theorem [Berglund & G, 2002]

There exists a threshold value $\sigma_c = (a_0 \vee \varepsilon)^{3/4}$ s.t.

Below threshold $\sigma \ll \sigma_{\rm c} = (a_0 \vee \varepsilon)^{3/4}$:

- \triangleright Transitions unlikely, probability for transition $\leq e^{-const \sigma_c^2/\sigma^2}$
- > Sample paths concentrated near bottom of well; typical spreading depends on local curvature

Above threshold $\sigma \gg \sigma_{\rm c} = (a_0 \vee \varepsilon)^{3/4}$:

- \triangleright 2 transitions per period likely (back and forth) with probability $\ge 1 e^{-const} \sigma^{4/3} / \epsilon |\log \sigma|$
- \triangleright Transitions likely when barrier low; transition window has width $\simeq \sigma^{2/3}$

References

General results on sample-path behaviour in slow-fast systems

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Case studies: Bifurcations in slowly driven systems

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Passage through an unstable periodic orbit

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Probability and Its Applications

Nils Berglund Barbara Gentz

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A Sample-Paths Approach

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