A geometric approach to q-Painlevé equations and their hypergeometric solutions

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Topic of this talk:

- Painlevé and discrete Painlevé equations
- Affine Weyl group symmetries
- Formulations of discrete Painlevé equations: Point configuration space and geometry of plane curves on \mathbb{P}^2
- Hypergeometric solutions: beyond the Gauss hypergeometric function?

Painlevé and Discrete Painlevé Equations (1)

List of Painlevé Equations

$$(P_{\rm I}) \quad y'' = 6y^2 + t,$$

$$(P_{II}) \quad y'' = 2y^3 + ty + \alpha,$$

(P_{III})
$$y'' = \frac{1}{y}(y')^2 - \frac{1}{t}y' + \frac{1}{t}(\alpha y^2 + \beta) + \gamma y^3 + \frac{\delta}{y}$$

(P_{IV})
$$y'' = \frac{1}{2y}(y')^2 + \frac{3}{2}y^3 + 4ty^2 + 2(t^2 - \alpha)y + \frac{\beta}{y}$$

$$(P_{V}) \quad y'' = \left(\frac{1}{2y} + \frac{1}{y-1}\right)(y')^{2} - \frac{1}{t}y' + \frac{(y-1)^{2}}{t^{2}}\left(\alpha y + \frac{\beta}{y}\right) + \gamma \frac{y}{t} + \delta \frac{y(y+1)}{y-1},$$

$$(P_{VI}) \quad y'' = \frac{1}{2} \left(\frac{1}{y} + \frac{1}{y-1} + \frac{1}{y-t} \right) (y')^2 - \left(\frac{1}{t} + \frac{1}{t-1} + \frac{1}{y-t} \right) y' + \frac{y(y-1)(y-t)}{t^2(t-1)^2} \left[\alpha + \beta \frac{t}{y^2} + \gamma \frac{t-1}{(y-1)^2} + \delta \frac{t(t-1)}{(y-t)^2} \right].$$

Painlevé and Discrete Painlevé Equations (2)

Painlevé Equations:

- ✓ 2nd order nonlinear ODE with the "Painlevé property"
 - No movavle branch points(6(8) equations)
- ✓ "Space of initial values" : defining manifold (Okamoto, Takano) \leftarrow blow-up of \mathbb{P}^2
- ✓ Symmetries:
 Affine Weyl group = reflection + translation
- ✓ Solutions:
 - Transcendental in general(Nishioka, Umemura, Noumi, Okamoto,...)
 - Particular solutions for special values of parameters
 - (1) <u>Hypergeometric solutions</u> (classification finished: Okamoto, Umemura, Noumi, Watanabe)
 - (2) <u>Algebraic solutions</u> (most cases rational solutions) (classification finished except for P_{VI} : Murata, Umemura, Kitaev, Watanabe, Dubrovin-Mazocco)

Painlevé and Discrete Painlevé Equations (3)

List of Some Discrete Painlevé Equations:

dP_I:
$$x_{n+1} + x_n + x_{n-1} = \frac{an+b}{x_n} + c$$

 $x_{n+1}x_n^{\sigma}x_{n-1} = aq^nx_n + b, \quad \sigma = 0, 1, 2$

dP_{II}:
$$x_{n+1} + x_{n-1} = \frac{(an+b)x_n + c}{1 - x_n^2}$$
$$(x_{n+1}x_n - 1)(x_n x_{n-1} - 1) = \frac{aq^{2n}x_n}{x_n + q^n}$$

$$dP_{III}: x_{n+1}x_{n-1} = \frac{ab(x_n + cq^n)(x_n + dq^n)}{(x_n + a)(x_n + b)}$$

Type $E_7^{(1)}$

$$\begin{cases}
\frac{(\overline{g}f - t\overline{t})(gf - t^2)}{(\overline{g}f - 1)(gf - 1)} = \frac{(f - b_1t)(f - b_2t)(f - b_3t)(f - b_4t)}{(f - b_5)(f - b_6)(f - b_7)(f - b_8)}, \\
\frac{(gf - t^2)(g\underline{f} - \underline{t}t)}{(gf - 1)(g\underline{f} - 1)} = \frac{(g - t/b_1)(g - t/b_2)(g - t/b_3)(g - t/b_4)}{(g - 1/b_5)(g - 1/b_6)(g - 1/b_7)(g - 1/b_8)}, \\
\overline{t} = qt, \quad b_1b_2b_3b_4 = q, \quad b_5b_6b_7b_8 = 1.
\end{cases}$$

Type $E_6^{(1)}$:

$$\begin{cases} (\overline{g}f - 1)(gf - 1) = t\overline{t} \frac{(f - b_1)(f - b_2)(f - b_3)(f - b_4)}{(f - b_5 t)(f - t/b_5)}, \\ (gf - 1)(g\underline{f} - 1) = t^2 \frac{(g - 1/b_1)(g - 1/b_2)(g - 1/b_3)(g - 1/b_4)}{(g - b_6 t)(g - t/b_6)}, \end{cases}$$

$$\begin{cases} \overline{g}gf = b_0 \, \frac{1 + a_0 t f}{a_0 t + f}, \\ gf\underline{f} = b_0 \, \frac{a_1/t + g}{1 + g a_1/t}, \end{cases} \quad \overline{t} = qt.$$

Painlevé and Discrete Painlevé Equations (4)

Discrete Painlevé Equations:

- ✓ 2nd order nonlinear ordinary DIFFERENCE equations with the "singularity confinement property" (MANY equations)
- ✓ Space of initial values": defining manifold (Sakai) \leftarrow blow-up of \mathbb{P}^2
- ✓ Symmetries:
 Affine Weyl group = reflection + translation
- ✓ Solutions:
 - Transcendence?
 - Particular solutions for special values of parameters
 - (1) Hypergeometric solutions
 - (2) Algebraic solutions: almost nothing has been done

Particular solutions: hypergeometric solutions

P_{II}:
$$\frac{d^2y}{dt^2} = 2y^3 + ty + \alpha$$
$$dP_{II}: x_{n+1} + x_{n-1} = \frac{(\alpha n + \beta)x_n + \gamma}{1 - x_n^2}$$

Hypergeometric solution (Riccati solution)

Riccati equation --- linearization

$$y' = a(t)y^{2} + b(t)y + c(t)$$

$$\frac{dy}{dt} = -y^{2} + \frac{t}{2} \longrightarrow \alpha = -\frac{1}{2}$$

$$\Downarrow$$

$$y = \frac{d}{dt} \log f, \quad \frac{d^{2}f}{dt^{2}} = -\frac{t}{2}f$$

$$x_{n+1} = \frac{a_n x_n + b_n}{c_n x_n + d_n}$$

$$\downarrow \downarrow$$

$$x_{n+1} = \frac{x_n - (pn+q)}{1 + x_n} \longrightarrow \alpha = 2p, \quad \beta = -p + 2q + 2, \quad \gamma = -p$$

$$\downarrow \downarrow$$

$$x_n = \frac{g_{n+1} - g_n}{g_n}, \quad g_{n+2} - 2g_{n+1} + g_n = -(pn+q)g_n$$

Affine Weyl group symmetry: P_{IV}

$$P_{IV}: y'' = \frac{y'^2}{2y} + \frac{3}{2}y^3 - 2ty + \left(\frac{t^2}{2} - \alpha_0 + \alpha_2\right)y - \frac{\alpha_1^2}{2y}$$



"symmetric form" of $P_{\rm IV}$ (Noumi-Yamada, 1998)

$$\varphi_0' = \varphi_0(\varphi_1 - \varphi_2) + \alpha_0$$

$$\varphi_1' = \varphi_1(\varphi_2 - \varphi_0) + \alpha_1$$

$$\varphi_2' = \varphi_2(\varphi_0 - \varphi_1) + \alpha_2$$

 $y=\varphi_1$, normalization: $\alpha_0+\alpha_1+\alpha_2=1$, $\varphi_0+\varphi_1+\varphi_2=t$

Bäcklund transformations s_0 , s_1 , s_2 , π

$$s_0(\alpha_0) = -\alpha_0$$
 $s_0(\alpha_1) = \alpha_1 + \alpha_0$ $s_0(\alpha_2) = \alpha_2 + \alpha_0$
 $s_1(\alpha_0) = \alpha_0 + \alpha_1$ $s_1(\alpha_1) = -\alpha_1$ $s_1(\alpha_2) = \alpha_2 - \alpha_1$
 $s_2(\alpha_0) = \alpha_0 + \alpha_2$ $s_2(\alpha_1) = \alpha_1 + \alpha_2$ $s_2(\alpha_2) = -\alpha_2$

$$s_0(\varphi_0) = \varphi_0 \qquad s_0(\varphi_1) = \varphi_1 - \frac{\alpha_0}{\varphi_0} \quad s_0(\varphi_2) = \varphi_2 + \frac{\alpha_0}{\varphi_0}$$

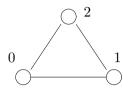
$$s_1(\varphi_0) = \varphi_0 + \frac{\alpha_1}{\varphi_1} \quad s_1(\varphi_1) = \varphi_1 \qquad s_1(\varphi_2) = \varphi_2 - \frac{\alpha_0}{\varphi_0}$$

$$s_2(\varphi_0) = \varphi_0 - \frac{\alpha_2}{\varphi_2} \quad s_1(\varphi_1) = \varphi_1 + \frac{\alpha_2}{\varphi_1} \quad s_2(\varphi_2) = \varphi_2$$

$$\pi(\varphi_i) = \varphi_{i+1}, \quad \pi(\alpha_i) = \alpha_{i+1}, \quad i \in \mathbb{Z}/3\mathbb{Z}$$

\mathscr{A} Affine Weyl group: $\langle s_0, s_1, s_2, \pi \rangle = \widetilde{W}(A_2^{(1)})$

$$s_i^2 = 1,$$
 $s_i s_j = s_j s_i,$ $s_i s_j s_i = s_j s_i s_j,$ $s_i s_j s_i = s_j s_i s_j,$ $s_i s_j s_j = 1,$ $s_{i+1} \pi = \pi s_i$



Translations in the parameter space:

$$T_1 = \pi s_1 s_2, \quad T_2 = s_1 \pi s_2, \quad T_0 = s_1 s_2 \pi \rightarrow T_i T_j = T_j T_i, \ T_0 T_1 T_2 = 1$$

$$T_1(\{\alpha_0, \alpha_1, \alpha_2\}) = \{\alpha_0 + 1, \alpha_1 - 1, \alpha_2\}$$

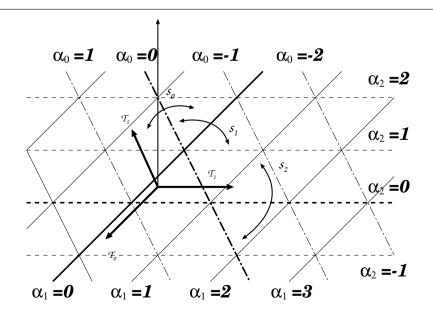
$$T_2(\{\alpha_0, \alpha_1, \alpha_2\}) = \{\alpha_0, \alpha_1 + 1, \alpha_2 - 1\}$$

$$T_0(\{\alpha_0, \alpha_1, \alpha_2\}) = \{\alpha_0 - 1, \alpha_1, \alpha_2 + 1\}$$

A discrete Painlevé II $(T_1^n(\varphi_i) = \varphi_i(n))$

$$\varphi_{1}(n+1) = t - \varphi_{0}(n) - \varphi_{1}(n) - \frac{\alpha_{0} + n}{\varphi_{0}(n)}$$

$$\varphi_{0}(n+1) = t - \varphi_{0}(n) - \varphi_{1}(n+1) + \frac{\alpha_{1} - n - 1}{\varphi_{1}(n+1)}$$



Sakai's Theory (2001):

Algebro-geometric theory of Painlevé and discrete Painlevé equations:

- ${\mathscr D}$ Defining manifold of discrete Painlevé equations: Family of rational surfaces obtained by blow-up of ${\mathbb P}^2$ at 9 points.
- Action of affine Weyl group: interchange of points and Cremona transformations
- Classification of surfaces:22 cases obtained by degeneration of points
- 8 cases admit continuous flows → Painlevé equations
 Continuous flows come from continuous limit of discrete evolutions on "higher" surfaces.

Degeneration diagram of surfaces:

$$E_{8}^{(1)} \rightarrow E_{7}^{(1)} \rightarrow E_{6}^{(1)} \rightarrow \frac{D_{5}^{(1)}}{(q^{P_{VI}})} \rightarrow \frac{A_{4}^{(1)}}{(q^{P_{IV}})} \rightarrow \frac{(A_{2} + A_{1})^{(1)}}{(q^{P_{IV}})} \rightarrow \frac{(A_{1} + \frac{A_{1}}{|\alpha|^{2} = 14})^{(1)}}{(q^{P_{II}})} \rightarrow A_{1}^{(1)} \rightarrow A_{0}^{(1)}$$

$$D_{4}^{(1)} \rightarrow A_{3}^{(1)} \rightarrow \frac{(2A_{1})^{(1)}}{(p^{P_{III}})} \rightarrow \frac{A_{1}^{(1)}}{(p^{P_{III}})} \rightarrow A_{0}^{(1)} \rightarrow A_{0}^{(1)}$$

$$A_{2}^{(1)} \rightarrow A_{1}^{(1)} \rightarrow A_{0}^{(1)} \rightarrow A_{0}^{(1)}$$

$$A_{2}^{(1)} \rightarrow A_{1}^{(1)} \rightarrow A_{0}^{(1)}$$

$$A_{2}^{(1)} \rightarrow A_{1}^{(1)} \rightarrow A_{0}^{(1)}$$

Type of time evolution (action of Weyl group):

 $\ \ \,$ Elliptic: $E_8^{(1)}$ (1) \rightarrow Elliptic Painlevé equation

riangleq Multiplicative: $E_8^{(1)} \cdots A_0^{(1)}$ (10) ightarrow q-Painlevé equations

 $Additive: E_8^{(1)}, E_7^{(1)}, E_6^{(1)} + \text{inside the box (11)}$

Hypergeometric Solutions:

Coalescence cascade

Series of *q*-Painlevé equations:

$$E_8^{(1)} \rightarrow E_7^{(1)} \rightarrow E_6^{(1)} \rightarrow D_5^{(1)} \rightarrow A_4^{(1)} \rightarrow (A_2 + A_1)^{(1)} \rightarrow (A_1 + \frac{A_1}{|\alpha|^2 = 14})^{(1)}$$

✓ What kind of hypergeometric functions appear for q-Painlevé equations, in particular for $E_6^{(1)}$, $E_7^{(8)}$, $E_8^{(1)}$? (beyond the Gauss hypergeometric function!)

Basic hypergeometric series:

$$r\varphi_{s}\left(\begin{array}{c}a_{1},\ldots,a_{r}\\b_{1},\ldots,b_{s}\end{array};q,z\right) = \sum_{n=0}^{\infty} \frac{(a_{1},\cdots a_{r};q)_{n}}{(b_{1},\cdots,b_{s};q)_{n}(q;q)_{n}} \left[(-1)^{n}q^{\binom{n}{2}}\right]^{1+s-r} z^{n},$$

$$(a_{1},\ldots,a_{r};q)_{n} = (a_{1};q)_{n}\cdots(a_{r};q)_{n},$$

$$(a;q)_{n} = \underbrace{(1-a)(1-qa)\cdots(1-q^{n-1}a)}_{n}$$

 \checkmark balanced: $qa_1a_2\cdots a_{r+1}=b_1b_2\cdots b_r,\quad z=q$

✓ well-poised: $qa_1 = a_2b_1 = \cdots = a_{r+1}b_r$

 \checkmark very-well-poised: well-poised + $a_2 = qa_1^{\frac{1}{2}}, \quad a_3 = -qa_1^{\frac{1}{2}}$

Very-well-poised basic hypergeometric series $_{r+1}W_r$:

$${}_{r+1}W_r(a_1; a_4, \dots, a_{r+1}; q, z) = {}_{r+1}\varphi_r \left(\begin{array}{c} a_1, q a_1^{\frac{1}{2}}, -q a_1^{\frac{1}{2}}, a_4 \dots, a_{r+1} \\ a_1^{\frac{1}{2}}, -a_1^{\frac{1}{2}}, q a_1/a_4, \dots, q a_1/a_{r+1} \end{array}; q, z \right)$$

Formulation of discrete Painlevé equations (1)

"Configuration space of points" on \mathbb{P}^2 :

(x:y:z): homogeneous coordinate of \mathbb{P}^2

$$\mathcal{M}_{3,n} = GL(3) \setminus \left\{ \begin{bmatrix} x_1 & x_2 & x_3 & \cdots & x_n \\ y_1 & y_2 & y_3 & \cdots & y_n \\ z_1 & z_2 & z_3 & \cdots & z_n \end{bmatrix} \right\} / (\mathbb{C}^{\times})^n.$$

Birational transformations on $\mathcal{M}_{3,n}$:

- 1. s_i (i = 1, ..., n 1): interchanging P_i and P_{i+1}
- 2. s_0 : standard Cremona transformation with base points $P_1(1:0:0)$, $P_2(0:1:0)$, $P_3(0:0:1)$

$$s_0: (x:y:z) \mapsto (\frac{1}{x}, \frac{1}{y}, \frac{1}{z}).$$

$$\langle s_0, s_1, \dots, s_n \rangle = W(E_n)$$
: (A. Coble, 1922)

$$E_n$$
: 0
1 2 3 4 5 6 7 ... $n-1$
 $s_i^2 = 1$, $s_i s_j = s_j s_i$, $s_i s_j s_i = s_j s_i s_j$,

$$n = 10$$
 $\mathbb{Z}^8 \subset \langle s_0, s_1, \dots, s_9 \rangle = W(E_9) = W(E_8^{(1)}) \subset W(E_{10})$

action of translation subgroup $\mathbb{Z}^8 = \text{Elliptic Painlev\'e}$ equation 9 points $P_1, \dots, P_9 = \text{parameters}$ 10th point $P_{10} = \text{dependent variable}$

Formulation with the pencil of cubic curves (1)

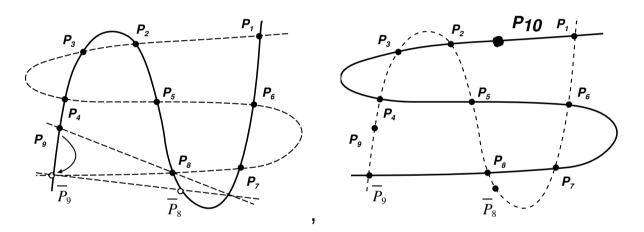
Translation = Addtion on moving cubic curve

Example: T_{89} , C_0 : Cubic curve passing $P_1, \ldots P_9$

lacktriangle Determine new points \overline{P}_8 , \overline{P}_9 by using the addition on C_0 :

$$\overline{P}_i = P_i, (i \neq 8, 9), \quad P_1 + \dots + P_8 + \overline{P}_9 = O, \quad P_8 + P_9 = \overline{P}_8 + \overline{P}_9$$

Let C_0 : F=0 and let the cubic pencil be $\lambda F + \mu G=0$. Choose λ , μ so that the pencil passes P_{10} . Denote this new cubic curve passing through P_1,\ldots,P_8 , \overline{P}_9 and P_{10} as C.



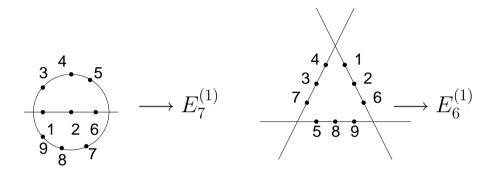
lacktriangle Determine new point \overline{P}_{10} by using the addition on C as

$$P_3$$
 P_2
 P_4
 P_5
 P_6
 P_8

 $P_{10} + P_8 = \overline{P}_{10} + \overline{P}_9$

Comments:

- - riangleq 9 points on nodal cubic curve: q-Painlevé of type $E_8^{(1)}$



- The same procedure for the stationary cubic gives QRT system (Tsuda)

Description of hypergeometric solution (1)

- ✓ Three points among the nine points in the cubic are colinear.
- ✓ A point is infinitesimally near to another point (The second case is essential only for much degenerate cases)

Example: P_5 , P_6 , P_7 are colinear

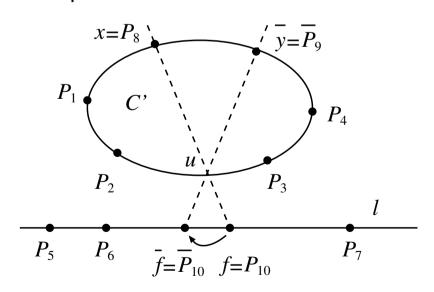
Cubic C is decomposed into a line $\ell(P_5, P_6, P_7)$ and a conic $C'(P_2, \ldots, P_4, P_8, \overline{P}_9)$.

$$P_1 + \cdots + P_8 + \overline{P}_9 = O, \quad P_5 + P_6 + P_7 = O \rightarrow P_1 + \cdots + P_4 + P_8 + \overline{P}_9 = O.$$

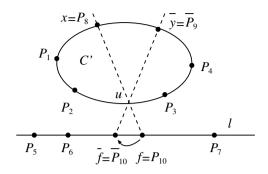
 $\downarrow \downarrow$

$$P_{10} \in \ell \rightarrow \overline{P}_{10} \in \ell \quad \ell$$
 is an "invariant divisor"

 \checkmark In this case, discrete time evolution of f can be described in terms of linear equation.



Description of hypergeometric solution (2)



Choose coordinate such that

 $P_1(1:0:0)$, $P_2(0:1:0)$, $P_3(0:0:1)$, and denote:

$$P_{10} = f = (f_1 : f_2 : f_3), \ \overline{P}_{10} = \overline{f} = (\overline{f}_1 : \overline{f}_2 : \overline{f}_3),$$

$$P_8 = x = (x_1 : x_2 : x_3), \ P_9 = \overline{y} = (\overline{y}_1 : \overline{y}_2 : \overline{y}_3),$$

$$\ell: (a,f) = a_1 f_1 + a_2 f_2 + a_3 f_3 = 0, (a,\overline{f}) = a_1 \overline{f}_1 + a_2 \overline{f}_2 + a_3 \overline{f}_3 = 0$$

Linear equation for f:

$$\begin{split} \lambda \overline{f} &= (a, \overline{y}) D f - (a, D f) \overline{y}, \\ \mu f &= (a, x) D^{-1} \overline{f} - (a, D^{-1} \overline{f}) x, \end{split}$$

$$D &= \operatorname{diag} \left(\frac{x_2 x_3}{\overline{y}_2 \overline{y}_3}, \frac{x_3 x_1}{\overline{y}_3 \overline{y}_1}, \frac{x_1 x_2}{\overline{y}_1 \overline{y}_2} \right), \quad \lambda = (a, x), \quad \mu = (a, \overline{y}). \end{split}$$

$$GL(3) \text{-invariant linear equation: } d_{ijk} = \det[P_i, P_j, P_k]$$

$$\frac{d_{239}d_{12\overline{9}}d_{568}d_{318}}{d_{18\overline{9}}} \left(\frac{d_{31\overline{9}}}{d_{318}} \right] - \left[d_{23 \ 10}\right]$$

$$+ \frac{d_{238}d_{12\underline{8}}d_{569}d_{319}}{d_{1\underline{8}9}} \left(\frac{d_{31\underline{8}}}{d_{319}} \right] - \left[d_{23 \ 10}\right] - \left[d_{23 \ 10}\right]$$

$$= d_{562}d_{389}d_{123} \left[d_{23 \ 10}\right]$$

Description of hypergeometric solution (3): Case of $E_7^{(1)}$

$$\begin{cases}
\frac{(\overline{g}f - t\overline{t})(gf - t^2)}{(\overline{g}f - 1)(gf - 1)} = \frac{(f - b_1t)(f - b_2t)(f - b_3t)(f - b_4t)}{(f - b_5)(f - b_6)(f - b_7)(f - b_8)}, \\
\frac{(gf - t^2)(g\underline{f} - \underline{t}t)}{(gf - 1)(g\underline{f} - 1)} = \frac{(g - t/b_1)(g - t/b_2)(g - t/b_3)(g - t/b_4)}{(g - 1/b_5)(g - 1/b_6)(g - 1/b_7)(g - 1/b_8)}, \\
\overline{t} = qt, \quad b_1b_2b_3b_4 = q, \quad b_5b_6b_7b_8 = 1.
\end{cases}$$

$$z = \frac{1 - b_3/b_1}{1 - b_3/b_5t} \frac{{}_{8}W_7(a;qb,c,d,e,f;q,qa^2/bcdef)}{{}_{8}W_7(a;b,c,d,e,f;q,q^2a^2/bcdef)}, \quad z = \frac{g - t/b_1}{g - 1/b_5}$$

where

$$a = b_1b_8/b_3b_5$$
, $b = b_8/b_5$, $c = b_2/b_3$, $d = b_1t/b_5$, $e = b_1/b_5t$, $f = b_4/b_3$.

gives a solution of the q-Painlevé equation of type $E_7^{(1)}$ with

$$b_1b_3 = b_5b_7 \quad (b_2b_4 = qb_6b_8).$$

Comments:

- ✓ In the terminating case, i.e. $f = b_4/b_3 = q^{-n}$, $n \in \mathbb{Z}_{>0}$, the solution is expressed by *terminating balanced* $_4\varphi_3$ (*Askey-Wilson Polynomials*)
- ✓ In the elliptic case, the solution is expressible in terms of the terminating balanced very-well-poised elliptic hypergeometric series

$${}_{10}E_{9}(u_{0}, u_{1}, \dots, u_{7}) = \sum_{n=0}^{\infty} \frac{[u_{0} + 2n\delta]}{[u_{0}]} \prod_{r=0}^{7} \frac{[u_{r}]_{n}}{[u_{0} - u_{r} + \delta]_{n}},$$
$$[z]_{n} = [z][z + \delta] \cdots [z + (n-1)\delta],$$
$$2\delta + 3u_{0} - \sum_{n=0}^{7} u_{i} = 0.$$

Summary

- Addition on moving cubic curve: discrete Painlevé equations
- Diagram of hypergeometric functions:

$$E_{8}^{(1)}(e.) \downarrow \\ E_{8}^{(1)}(q) \rightarrow E_{7}^{(1)} \rightarrow E_{6}^{(1)} \rightarrow D_{5}^{(1)} \rightarrow A_{4}^{(1)} \rightarrow (A_{2} + A_{1})^{(1)} \rightarrow (A_{1} + \frac{A_{1}}{|\alpha|^{2} = 14})^{(1)}$$
balanced
$${}_{10}E_{9} \downarrow \\ \downarrow \\ balanced \\ {}_{10}W_{9} \rightarrow {}_{8}W_{7} \rightarrow \begin{array}{c} balanced \\ {}_{3}\phi_{2} \end{array} \rightarrow {}_{2}\phi_{1} \rightarrow {}_{1}\phi_{1} \rightarrow \begin{array}{c} {}_{1}\phi_{1} \begin{pmatrix} a \\ 0 \\ ; q, z \end{pmatrix} \\ {}_{1}\phi_{1} \begin{pmatrix} 0 \\ b \\ ; q, z \end{pmatrix} \rightarrow {}_{1}\phi_{1} \begin{pmatrix} 0 \\ -q \\ ; q, z \end{pmatrix}$$

- Things to be done: Many things! Only the formulations and simplest solutions have been presented.
 - Lax pair

 - Asymptotics
 - \mathcal{J} τ functions
 - Relation to other fields (random matrices, geometry,)

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