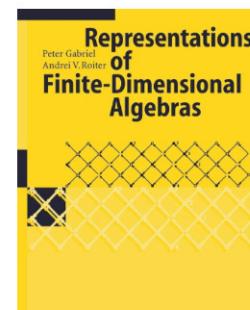
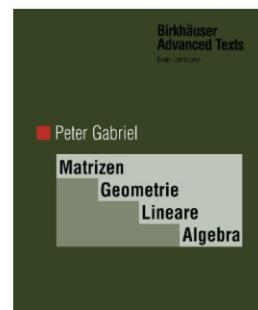
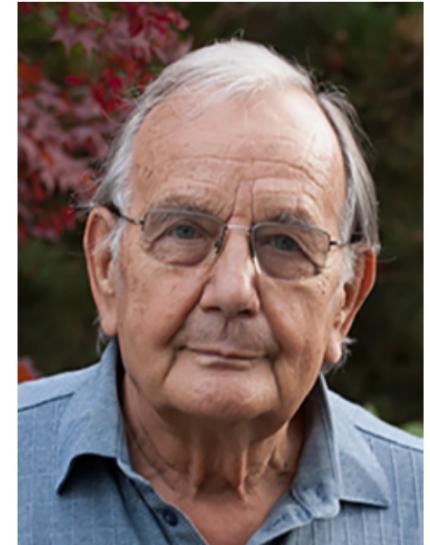




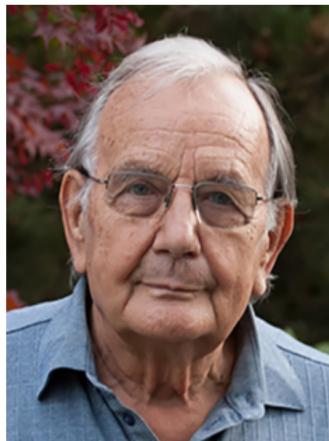
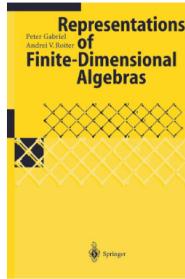
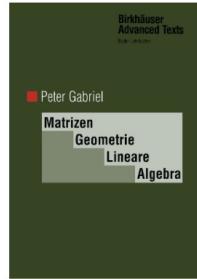
The Legacy of Peter Gabriel - Conference



Matrix Problems

Thomas Brüstle

We present matrix problems which are introduced prominently as the opening chapter in the book *Representations of Finite-Dimensional Algebras* by Gabriel and Roiter. Building on this, we will focus on one-sided matrix problems and present key results by Gabriel and his collaborators concerning the classification into finite, tame, and wild types.



The monograph would not have been completed without the assistance of L.A. Nazarova, with whom all points have been discussed. For comments and corrections we are also indebted to T. Brüstle, Deng Bangming, E. Dieterich, T. Guidon, E. Gut, U. Hassler, H.J. von Höhne, B. Keller, J.A. de la Peña, V.V. Sergejchuk and D. Vossieck. Finally, we like to thank Mrs. I. Verdier, whose endurance and unselfish motivation brought the work to its logistic conclusion.



Bangming Deng **1993**

Professor of Department of
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Research Field: Algebraic
Representation Theory



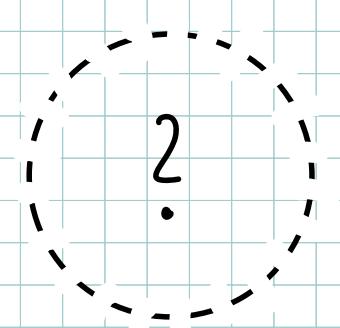
1996

Thomas Guidon
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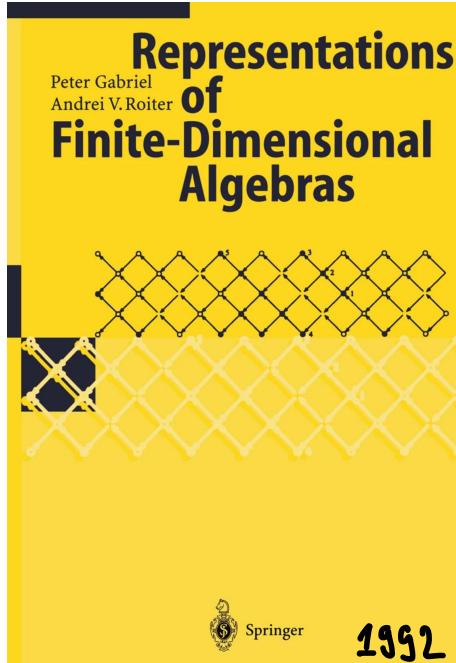


Thomas Brüstle
UDS Université de
Sherbrooke

1995



Urs Hassler
1996



1. Matrix Problems

In the present section, k denotes an algebraically closed field.

1.1. Since (finite) matrices describe linear maps between the spaces k^n , $n \in \mathbb{N}$, we admit matrices with no row or no column.¹ By $k^{m \times n}$ we denote the space of

1.10. Remarks and References

1. In our terminology, a matrix A is defined by two numbers $m, n \in \mathbb{N}$ and a family of entries A_{ij} , $1 \leq i \leq m$, $1 \leq j \leq n$.

$$0 \times 1 - \text{matrix} : \vdash$$

$$1 \times 0 - \text{matrix} : \vdash$$

$GL_m \times GL_n$ acts on $K^{m \times n}$ (space of $m \times n$ -matrices)

$$(X, Y)$$

$$A \xrightarrow{\psi} XAY^{-1} \sim A$$

Same orbit

$$A \sim \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix} = \boxed{I^r} \oplus \boxed{I^s} \oplus \boxed{I^t}$$

$r = \text{rk } A$

$$s = n - r, \quad t = m - r$$

$$l = n + u : G \leq GL_e$$

1.4 Def: Matrix problem of size $m \times n$ is

(G, \mathcal{M}) where $G \leq \underset{\text{Subgroup}}{GL_m} \times \underset{\text{Subgroup}}{GL_n}$, $\mathcal{M} \subseteq K^{m \times n}$

$$\text{s.t. } XAY^{-1} \in \mathcal{M} \quad \forall (x, y) \in G, A \in \mathcal{M}$$

Problem: classify orbits!

Often: $G = \text{Aut } R$, $R \subseteq K^{m \times m} \times K^{n \times n}$ (linear matrix problem)

$\mathcal{M} = v + U$ for $v \in K^{m \times n}$, $U \subseteq K^{m \times n}$ lin. subspace

affine subspace

Example 1: $\mathcal{A} = KQ/I$ f.d. algebra, $M \in \text{mod } \mathcal{A}$

[Drozd '79]

$$P_i \xrightarrow{A} P_0 \xrightarrow{f_0} M \rightarrow 0 \quad \text{projective resolution}$$

$$A \in \text{Hom}_{\mathcal{A}}(P_i, P_0) =: \mathcal{M} \subseteq \text{Hom}_K(P_i, P_0)$$

\mathfrak{U} action linear subspace

$$\text{Aut}_{\mathcal{A}}(P_i) \times \text{Aut}_{\mathcal{A}}(P_0) =: G \quad \text{not reductive}$$

G -orbits on \mathcal{M} = isoclasses of \mathcal{A} -modules $[M = \text{coker}(P_i \xrightarrow{A} P_0)]$

$$\dim M = (d_1, \dots, d_t) : M \in \prod_{i=1}^t K^{d_j \times d_i} / \langle I \rangle \subseteq \prod_{i=1}^t K^{d_j \times d_i}$$

quiver
representation \mathfrak{U} action algebraic var.

use GIT

$$\text{reductive group } \prod_{1 \leq i \leq t} GL_{d_i} = G^1 \quad \text{orbits} = \text{isoclasses of } \mathcal{A}\text{-modules}$$

Example 2: category Mat \mathcal{B}

\mathcal{C} k-category

$$\mathcal{B}: \mathcal{C} \times \mathcal{C} \longrightarrow \text{mod } k$$

k-linear bifunctor

$$\text{Obj Mat } \mathcal{B} = \{ (C, m) \mid C \in \mathcal{C}, m \in \mathcal{B}(C, C) \}$$

$\downarrow \gamma: C \rightarrow C' \text{ s.t. } \gamma m = m' \gamma$

(C', m')

↑
in $\mathcal{B}(C, C')$

$$(C, m) \cong (C', m') \Leftrightarrow m' = \gamma m \gamma^{-1} \text{ some } \gamma \in \text{Aut}(\mathcal{C}(C, C)) =: G$$

orbits =
isoclasses

Exact structure on Mat \mathcal{B} :

$$\{ 0 \rightarrow (C', m') \rightarrow (C, m) \rightarrow (C'', m'') \rightarrow 0 \mid 0 \rightarrow C' \rightarrow C \rightarrow C'' \rightarrow 0 \text{ splits} \}$$

Example: $\mathcal{B} = \text{Hom}_\mathcal{A}(-, -)$ for $\mathcal{C} = \text{proj-}\mathcal{A} \rightarrow (\text{Ex. 1})$

Example 3:

$P = \text{poset } 1 \rightarrow 2$

$$\text{rep } P = \left\{ m \begin{array}{|c|c|} \hline A_1 & A_2 \\ \hline u_1 & u_2 \\ \hline \end{array} \right\}$$

any poset \rightsquigarrow

$$M = K^{m \times n}$$

$$u = u_1 + u_2$$

$$G = GL_m \times \left\{ \begin{array}{|c|c|} \hline u_1 & u_2 \\ \hline Y_1 & Z \\ \hline 0 & Y_2 \\ \hline \end{array} \right\}^{u_1, u_2}$$

Y_1, Y_2
invertible

one-sided
matrix problem

Matrix Reduction:

$$m \begin{array}{|c|c|} \hline A_1 & A_2 \\ \hline u_1 & u_2 \\ \hline \end{array} \sim \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} \sim \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} = \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} = \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} + \begin{array}{|c|c|} \hline 0 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array}$$

Reduced Matrix Problem:

$$M = u + V, \quad u =$$

$$\begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array},$$

$$V = \left\{ \begin{array}{|c|c|} \hline 0 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} \right\}$$

Example 3: $P = \text{poset } 1 \overset{\leftarrow}{\rightarrow} 2$

$\text{rep } P = \text{Mat } \mathcal{B}$, \mathcal{B} bimodule over $kP \times k$

Matrix Reduction:

$$\text{in } \begin{array}{|c|c|} \hline A_1 & A_2 \\ \hline u_1 & u_2 \\ \hline \end{array} \sim \begin{array}{|c|c|} \hline 1 & 0 & 0 \\ \hline 0 & 0 & B_2 \\ \hline u_1 & u_2 \\ \hline \end{array}$$

$$\begin{aligned} \mathcal{B}(e_1, e_3) &= a, \\ \mathcal{B}(e_2, e_3) &= a_2 \end{aligned} \quad a, a_2 = a_2$$

Reduced Matrix Problem:

$$M' = u + V, \quad u = \begin{array}{|c|c|} \hline 1 & 0 & 0 \\ \hline 0 & 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array}, \quad V = \left\{ \begin{array}{|c|c|} \hline 0 & 0 \\ \hline 0 & 0 \\ \hline u_1 & u_2 \\ \hline \end{array} \right\}$$

$$G' = \text{Stab } u \leq G$$

CompSci: Reduction Algorithm (store u , compute $\text{stab } u$, continue)

Math (category): need more input than $\text{Mat } \mathcal{B}$

$\rightsquigarrow \text{BOCS}$

(not \mathfrak{su})

1.2

Example 4:
 $Q = \text{quiver } 1 \rightarrow 3 \leftarrow 2$

$\text{rep } Q = \left\{ m \begin{array}{|c|c|} \hline 1 & 2 \\ \hline A_1 & A_2 \\ \hline u_1 & u_2 \\ \hline \end{array} \right. \left. 3 \right\}$

$M = K^{m \times n}$

$u = u_1 + u_2$

$G = GL_m \times \left\{ \begin{array}{|c|c|} \hline u_1 & u_2 \\ \hline Y_1 & 0 \\ \hline 0 & Y_2 \\ \hline \end{array} \right. \left. \begin{array}{l} u_1 \\ u_2 \\ \uparrow \\ \text{one-sided} \\ \text{matrix problem} \\ \text{invertible} \end{array} \right\}$

Reduction:

$m \begin{array}{|c|c|} \hline A_1 & A_2 \\ \hline u_1 & u_2 \\ \hline \end{array} \sim$

$\bar{A} = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Representations
 Peter Gabriel
 Andrei V. Roiter
of
Finite-Dimensional
Algebras

Fig. 3

$\bar{A} \in K^{4 \times 6} \Rightarrow$

 $\text{Stab } \bar{A} = \text{Auslander algebra of } KQ$

1.8

Example 5: [L. Kronecker, 1890]

$Q = \text{quiver } | \xrightarrow[\alpha_2]{\alpha_1} 2$

$$\text{rep } Q = \left\{ \begin{matrix} m & \\ A_1 & A_2 \\ n & n \end{matrix} \right\}$$

$$\mathcal{M} = K^{m \times 2n}$$

$$G = GL_m \times \left\{ \begin{array}{|c|c|} \hline & u & \\ \hline y & 0 & u \\ \hline 0 & y & u \\ \hline \end{array} \right\}$$

y invertible

Reduction:

$$m \begin{array}{|c|} \hline A_1 \\ \hline n \\ \hline \end{array} \quad \begin{array}{|c|} \hline A_2 \\ \hline n \\ \hline \end{array} \sim$$

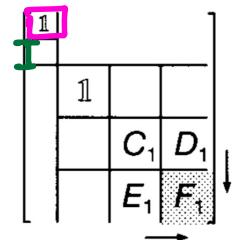


Fig. 13

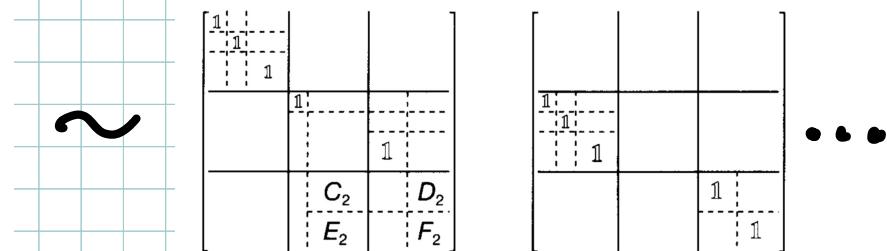


Fig. 14

1.8

Example 5: [L. Kronecker, 1890] $Q = \text{quiver } 1 \xrightarrow{\alpha_1} 2$

(generic) Reduction Algorithm never stops,

splitting off summands :

$$K \xrightarrow{\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}} K, \quad 0 \xrightarrow{\begin{smallmatrix} I \\ I \end{smallmatrix}} K, \quad K \xrightarrow{\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}} K^2, \quad K^2 \xrightarrow{\begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 1 & 0 \end{bmatrix}} K^2, \quad \dots$$

(preprojective and
some regular
indecomposables)

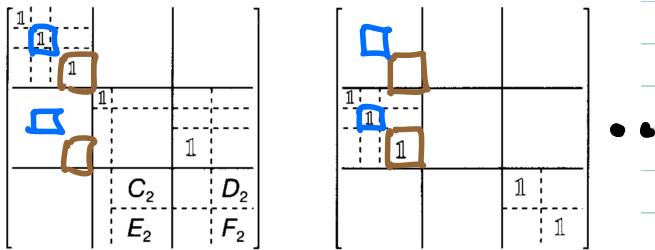


Fig. 14

generic reduction algorithm:

keep matrix sizes variable, work within category $\text{Mat } \mathcal{B}$

If $\text{Mat } \mathcal{B}$ is of finite type, algorithm stops with output:

- all indecomposables (given by 0,1-matrices)
- $\text{End}(\bigoplus_{U \text{ indec}} U)$

If $\text{Mat } \mathcal{B}$ is of infinite type, algorithm never stops !

Apply Bongartz' criterion when $\text{Mat } \mathcal{B} \cong \text{mod } kQ / I$:

Stop when pointwise dimension of an indecomposable is > 12

1.8

Example 5: [L. Kronecker, 1890] $Q = \text{quiver } 1 \xrightarrow{\alpha_1} 2$

Reduction Algorithm applied to one AE will always stop,
eventually leads to :

$$\text{in } \begin{matrix} A_1 & A_2 \\ u & u \end{matrix} \sim \begin{matrix} \mathbb{1}_n & A'_2 \\ u & u \end{matrix} \xrightarrow{X} \text{ with } \text{Stab } \begin{bmatrix} \mathbb{1}_n \end{bmatrix} = \left\{ \begin{bmatrix} X \\ X \end{bmatrix}, \begin{bmatrix} X & 0 \\ 0 & X \end{bmatrix} \right\},$$

so the reduced problem on A'_2 is $A'_2 \sim XA_2'X^{-1}$ matrix conjugation

\leadsto ∞ family of indecomposables

$$\boxed{\begin{smallmatrix} X \\ \diagup \diagdown \\ X \end{smallmatrix}} X \text{ is a minimal } \infty \text{ box, reduce it to } \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

A matrix problem is tame if after appearance of the first
minimal ∞ box, everything reduces to $0,1$ -matrices,
for all $\lambda \in K \setminus \{\lambda_1, \dots, \lambda_r\}$. "punched line"

$$\{\text{orbits}\} = \bigcup \text{discrete } 0,1\text{-matrices} \bigcup \text{punched lines}.$$

Theorem [Drozd '79; Crawley-Boevey '88]

Every finite-dimensional algebra is either tame or wild

Proof uses boxes.

"if a second α box appears in the reduction, have to show that leads to a functor $\text{mod } k\langle s, t \rangle \rightarrow \text{Mat } B$ preserving indecomposability"

This is highly non-trivial!

Example: Matrices $A_{s,t} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & s & t \end{bmatrix}$ acted upon by $\text{Aut } R$ where
 $s, t \in k$

R generated by $1,$ $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix}$

Then $A_{s,t} \sim A_{s',t'} \Leftrightarrow s=s' \text{ and } t=t',$

but replacing scalars s, t by matrices S, T fails to produce the desired functor $\text{mod } k\langle s, t \rangle \rightarrow \text{Mat } B$

Theorem [B, Sergeichuk '02]

If kQ/I is a tame fin.dim'l algebra

$$\text{Then } f(d) \leq \binom{d+r}{r} 4^{d^2 \sum s_i^2}$$

$\left(\forall d \geq 0 \exists f(d) \in \mathbb{N} : \right)$
all indecomposable \mathcal{L} -modules of
dimension d appear in at most
 $f(d)$ 0 or 1-parameter families

where $r = \# \text{ vertices of } Q$, $s_i = \dim P(i)$

Proof is based on:

[Gabriel, Nazarova, Roiter, Sergeichuk, Vossieck '93]

4.1

Def : Subspace Problem

$M : \mathcal{A} \rightarrow \text{mod } k$ functor (pfld module)

as Knoll-Schmidt (aggregate)

$$\begin{aligned} \text{Sub } M &= \{ (V, f, X) \mid V \in \text{mod } k, X \in \mathcal{A}, f: V \rightarrow M(X) \} \\ &\quad \varphi \downarrow \quad \downarrow \psi \quad \text{s.t. } f' \circ \varphi = M(\psi) \circ f \quad \text{\scriptsize k-linear} \\ &\quad (V', f', X') \end{aligned}$$

$\text{Sub } M = \text{Mat } \mathcal{B}$ where $\mathcal{B} : \text{mod } k \times \mathcal{A} \rightarrow \text{mod } k$



$$(V, X) \longmapsto \text{Hom}_k(V, M(X))$$

\uparrow

one-sided matrix problem

One-point extension: $\mathcal{L} = \begin{bmatrix} \mathcal{L}_0 & R \\ 0 & K \end{bmatrix}$



$$\text{mod } \mathcal{L} \cong \left\{ (V_x, f, X_0) \mid V_x \in \text{mod } K, X_0 \in \text{mod } \mathcal{L}_0, \right. \\ \left. f: V_x \rightarrow \text{Hom}_{\mathcal{L}_0}(R, X_0) \right\}$$

Construct \mathcal{L} -modules inductively from subspace categories over smaller algebra \mathcal{L}_0 .

4.3

\mathcal{L} fund.in'l, \exists functor $\text{mod } \mathcal{L} \rightarrow \text{Sub } M$
inducing bijection on isoclasses,

where $M = \text{Ext}_{\mathcal{L}}^1(S, -): \text{mod } \mathcal{L}_0 \rightarrow \text{mod } K$,

$\mathcal{L}_0 = \mathcal{L}/J$, S some simple \mathcal{L} -module.

4.4

Reduction Algorithm for Subspace Problems:

Given submodule $N \subseteq M: A \rightarrow \text{mod } K$,

define $\widehat{A}^1 = \text{Sub } N \supseteq A = \{(0, 0, X) \mid X \in A\}$

$$\widehat{M}: \widehat{A}^1 \rightarrow \text{mod } K, (V, f, X) \mapsto M(X)/f(V)$$

Proposition: The reduction functor

$F: \text{Sub } M \rightarrow \text{Sub } \widehat{M}_N^1$ \leftarrow assume $f''(N(X)) = 0$

$(V, f, X) \mapsto (V_{V'}, f'', X)$ with $V' = f^{-1}(N(X))$

induces bijection on iso classes

4.4

Reduction Algorithm for Subspace Problems:

Example:

$$A = \begin{bmatrix} A_1 & A_2 & A_3 & A_4 \end{bmatrix} \sim \text{sub } M$$

$\overset{N}{\curvearrowleft}$

$\boxed{B_1, B_2}$ row-linear independent

$$\begin{bmatrix} B_1 & B_2 & B_3 & B_4 \\ 0 & 0 & C_3 & C_4 \end{bmatrix} \sim \begin{bmatrix} B_1 & B_2 & B'_3 & B'_4 \\ 1 & 1 & 1 & 1 \end{bmatrix} \sim$$

Fig. 1 Fig. 2

4. Finitely Spaced Modules

$$\sim \begin{bmatrix} B_1 & B_2 & D & E & F \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} B_1 & B_2 & D & E & F \\ \longrightarrow & \longleftarrow & & & \end{bmatrix}$$

$$\text{sub } \tilde{M}_{\tilde{N}}$$

Sub N "known" by induction,

reduction as new subspace problem

(stay within same class, no need for Sopers)

4.5

Theorem. Let M be a pointwise finite left module over an aggregate \mathcal{A} and $b \in \mathbb{N}$ a number such that, for each $X \in \mathcal{A}$ satisfying $\dim M(X) \geq b$, there are only finitely many isoclasses of indecomposable M -spaces avoiding \mathcal{L} of the form (V, f, X) . Then the same conclusion holds if $\dim M(X) < b$.

Corollary.⁵ Let A be a finite-dimensional algebra such that the dimensions of the indecomposable A -modules are bounded. Then A admits only finitely many isoclasses of indecomposable modules.

(Brauer – Thrall I)

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TAME AND WILD SUBSPACE PROBLEMS

РУЧНІ ТА ДИКІ ЗАДАЧІ ПРО ПІДПРОСТОРИ

Second main theorem. *If M is not \mathcal{L} -wild, there is a locally finite set \mathcal{P} of \mathcal{L} -reliable punched lines such that:*

- a) *for each $X \in \mathcal{A}$, the set of isoclasses of indecomposable M -spaces (V, f, X) which avoid \mathcal{L} and are not produced by a punched line of \mathcal{P} is finite;*
- b) *distinct punched lines of \mathcal{P} produce non-isomorphic M -spaces.*

(tame subspace problem)

Third main theorem. *If B is a finite-dimensional k -algebra, one and only one of the following two statements holds:*

- a) *B is wild, i. e. there exists a B -reliable plane;*
- b) *There exists a family of B -reliable punched lines $S_i \setminus E_i \subset \text{Hom}_k(V_i \otimes_k B, V_i)$, $i \in I$, with the following properties: For each $d \in \mathbb{N}$, the number of $i \in I$ satisfying $d = \dim V_i$ is finite, and almost all isoclasses of indecomposable B -modules of dimension d consist of modules produced by the $S_i \setminus E_i$; furthermore, if $i \neq j$, no indecomposable produced by $S_i \setminus E_i$ can be produced by $S_j \setminus E_j$.*

