

Stabilization of Periodic Stokesian Hele–Shaw Flows of Ferrofluids

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The Hele–Shaw Cell

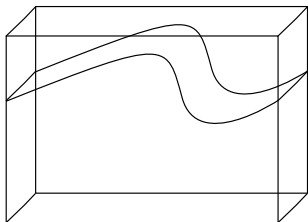


Figure: A vertical Hele–Shaw cell with a fluid's interface.

The Hele–Shaw Cell

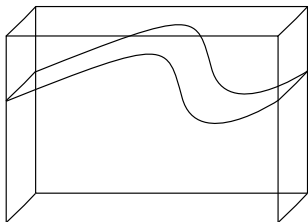


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3-D model
Navier–Stokes equations

The Hele–Shaw Cell

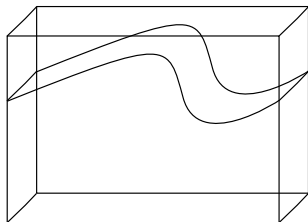


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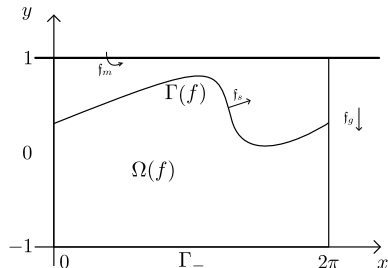


Figure: 2-dimensional profile of the Hele-Shaw cell.

3-D model
 Navier–Stokes equations

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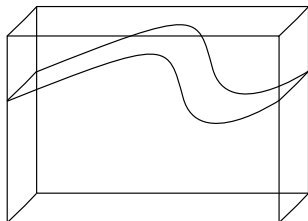


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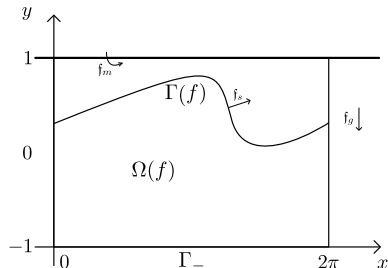


Figure: 2-dimensional profile of the Hele-Shaw cell.

2-D, gap-averaged model
Darcy's law
Moving boundary problem

The Moving Boundary Problem

$$\begin{aligned}
 Qu &:= -\operatorname{div} \frac{Du}{\bar{\mu}(|Du|^2)} = 0 && \text{in } \Omega(f) \\
 u &= b(f) && \text{on } \Gamma_- \\
 u &= -\gamma\kappa_f - \frac{\iota^2}{(1-f)^2} + g\rho f && \text{on } \Gamma(f) \\
 \partial_t f &= -\frac{\sqrt{1+f'^2}}{\bar{\mu}(|Du|^2)} \partial_\nu u && \text{on } \Gamma(f) \\
 f(0) &= f_0 && \text{on } \mathbb{S}
 \end{aligned}
 \tag{P}$$



Little Hölder Spaces

For $k \in \mathbb{N}$, $\alpha \in (0, 1)$ and $U \subset \mathbb{R}^2$ open



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Goal of this choice: Use of strongly continuous analytic semigroups and abstract parabolic theory



Classical Hölder Solutions

Let

$$\mathcal{V} := \{f \in h^{4+\alpha}(\mathbb{S}) : \|f\|_{\infty} < 1\}.$$

We seek (u, f) satisfying

$$\begin{aligned} f &\in C([0, T], \mathcal{V}) \cap C^1([0, T], h^{1+\alpha}(\mathbb{S})), \\ u(\cdot, t) &\in \text{buc}^{2+\alpha}(\Omega(f(t))), \quad 0 \leq t \leq T \end{aligned}$$

that fulfill (P) pointwise.



The Wellposedness Result

Theorem

Assume

$$\begin{aligned} 0 < c \leq \mu(r) \leq C & \quad \text{for all } r \geq 0, \\ 0 < c \leq \mu(r) + 2r\mu'(r) \leq C & \quad \text{for all } r \geq 0 \end{aligned}$$

hold and let $|c| < 1$. There is an open neighborhood \mathcal{O} of c in $h^{4+\alpha}(\mathbb{S})$ such that for all $f_0 \in \mathcal{O}$ problem (P) has a unique, maximal defined classical Hölder solution in \mathcal{O} .



Sketch of the Proof

Transformation on a fixed reference domain Ω .

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Solve the first three equations of the transformed system.

Plug this solution in the fourth equation.

Study the linearization of the evolution operator.



The Transformation

The Diffeomorphism

$$\phi_f(x, y) = (x, y + (1 + y)f(x)) \quad \text{for} \quad (x, y) \in \Omega = \mathbb{S} \times (-1, 0)$$

straightens the boundary:

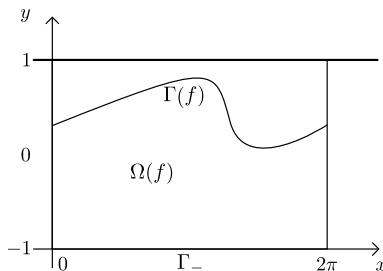


Figure: Original, time-dependent geometry.



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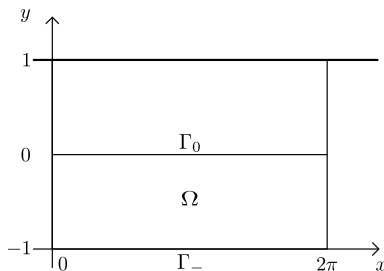


Figure: Transformed, fixed geometry.

The Transformation

Push forward and pull back operators

$$\phi_*^f : \text{buc}^{2+\alpha}(\Omega) \rightarrow \text{buc}^{2+\alpha}(\Omega(f)), \quad v \mapsto v \circ \phi_f^{-1}$$

$$\phi_f^* : \text{buc}^{2+\alpha}(\Omega(f)) \rightarrow \text{buc}^{2+\alpha}(\Omega), \quad u \mapsto u \circ \phi_f$$



The Transformation

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Transformed operators

$$\mathcal{A}(f) = \phi_f^* \circ \mathcal{Q} \circ \phi_*^f : \text{buc}^{2+\alpha}(\Omega) \rightarrow \text{buc}^\alpha(\Omega)$$

$$\mathcal{B}(f, \cdot) = -\text{tr}_0 \phi_f^* \left\langle \frac{D(\phi_*^f \cdot)}{\bar{\mu}(|D(\phi_*^f \cdot)|^2)}, n \right\rangle : \mathcal{V} \times \text{buc}^{2+\alpha}(\Omega) \rightarrow h^{1+\alpha}(\mathbb{S})$$



The Transformed System

System (P) is equivalent to the transformed system

$$\begin{aligned}
 \mathcal{A}(f)v &= 0 && \text{in } \Omega \\
 v &= b(f) && \text{on } \Gamma_- \\
 v &= -\gamma\kappa_f - \frac{\iota^2}{(1-f)^2} + g\rho f && \text{on } \Gamma_0 \\
 \partial_t f &= \mathcal{B}(f, v) && \text{on } \Gamma_0 \\
 f(0) &= f_0 && \text{on } \mathbb{S}
 \end{aligned}$$



A first Existence and Uniqueness Result

Theorem

Let $f \in \mathcal{V}$. There is a unique solution $\mathcal{T}(f) \in \text{buc}^{2+\alpha}(\Omega)$ of the quasilinear Dirichlet problem

$$\begin{aligned} \mathcal{A}(f)v &= 0 && \text{in } \Omega, \\ v &= b(f) && \text{on } \Gamma_-, \\ v &= -\gamma\kappa_{\Gamma(f)} - \frac{\iota^2}{(1-f)^2} + g\rho f && \text{on } \Gamma_0. \end{aligned}$$

The mapping $\mathcal{V} \ni f \mapsto \mathcal{T}(f) \in \text{buc}^{2+\alpha}(\Omega)$ is smooth.



The Evolution Equation

Advection equation on variable domain:

$$\partial_t f = -\frac{\sqrt{1+f'^2}}{\bar{\mu}(|Du|^2)} \partial_\nu u, \quad f(0) = f_0.$$

Evolution equation on fixed domain:

$$\partial_t f = \Phi(f), \quad f(0) = f_0$$

for the non-linear operator $\Phi(\cdot) = \mathcal{B}(\cdot, \mathcal{T}(\cdot))$.



The Generation Result

Theorem

(The complexification of) $\partial\Phi(c)$ generates a strongly continuous analytic semigroup in $\mathcal{L}(h^{1+\alpha}(\mathbb{S}))$, i.e.,

$$-\partial\Phi(c) \in \mathcal{H}(h^{4+\alpha}(\mathbb{S}), h^{1+\alpha}(\mathbb{S})).$$



Sketch of the Proof

Equivalent characterization:

$$\lambda - \partial\Phi(c) \in \mathcal{L}is(h^{4+\alpha}(\mathbb{S}), h^{1+\alpha}(\mathbb{S})),$$
$$|\lambda| \|R(\lambda, \partial\Phi(c))\|_{\mathcal{L}(h^{1+\alpha}(\mathbb{S}))} \leq \chi$$

for $h^{4+\alpha}(\mathbb{S}) \xrightarrow{d} h^{1+\alpha}(\mathbb{S})$, some $\chi, \omega > 0$, and all $\operatorname{Re} \lambda \geq \omega$



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Transfer the result to little Hölder spaces with a density argument.



Proof of the Well-Posedness Result

Apply a perturbation theorem for the class $\mathcal{H}(h^{4+\beta}(\mathbb{S}), h^{1+\beta}(\mathbb{S}))$
with $0 < \beta < \alpha$.



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The generation result holds of all f in a neighborhood $\mathcal{O}_\beta \subset h^{4+\beta}(\mathbb{S})$ of c .



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Use interpolation property of the little Hölder spaces

$$(h^{\theta_1}(\mathbb{S}), h^{\theta_2}(\mathbb{S}))_\sigma = h^{\theta_1 + \sigma(\theta_2 - \theta_1)}(\mathbb{S})$$

for $0 < \sigma < 1$ and $\theta_1 + \sigma(\theta_2 - \theta_1) \notin \mathbb{N}$.



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Putting $\sigma := (\alpha - \beta)/3$ turns the generation result in a well-posedness result for $f \in \mathcal{O} := \mathcal{O}_\beta \cap h^{4+\alpha}(\mathbb{S})$ (cf. Lunardi, 1995).



The Linearization

$$\partial\Phi(c)\left[\sum_{k\in\mathbb{Z}}c_ke^{ikx}\right]=\sum_{k\in\mathbb{Z}}\lambda_kc_ke^{ikx},$$



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$$\lambda_k=\Gamma_{\bar{\mu},c}\left[-\gamma\coth((1+c)k)k^3+\left(b'(c)\frac{1}{\operatorname{sech}((1+c)k)}-G_c\coth((1+c)k)\right)k\right],\quad k\neq 0,$$

$$\lambda_0=\Gamma_{\bar{\mu},c}\frac{b'(c)-G_c}{1+c},\quad G_c=g\rho-2\frac{\iota^2}{(1-c)^2}-\frac{\theta_c}{1+c},$$

$$\theta_c=\partial_y\mathcal{T}(c),\quad \Gamma_{\bar{\mu},c}=\frac{1}{\bar{\mu}((\frac{\theta_c}{1+c})^2)}+2\frac{\theta_c^2}{(1+c)^2}\left(\frac{1}{\bar{\mu}}\right)'((\frac{\theta_c}{1+c})^2)$$



Stability Conditions

Stability of the flat interface $f = c$ under the condition

$$\begin{aligned} 0 \leq b'(c) &< -\frac{2\ell^2}{(1-c)^2} + g\rho \quad \text{or} \\ 0 > b'(c), \quad \max\{b'(c), -I\} &< -\frac{2\ell^2}{(1-c)^2} + g\rho, \end{aligned} \tag{1}$$

where $I = \inf_{k \geq 1} (\gamma k^2 - b'(c) \operatorname{sech}((1+c)k))$



Stability Conditions

Instability of the flat interface $f = c$ if the former condition is violated such that

$$\begin{aligned} 0 \leq b'(c), \quad b'(c) > -\frac{2\iota^2}{(1-c)^2} + g\rho \quad \text{or} \\ 0 > b'(c), \quad \max\{b'(c), -I\} > -\frac{2\iota^2}{(1-c)^2} + g\rho \end{aligned} \tag{2}$$



The Main Result

Theorem

Let $|c| < 1$ and $\omega_0 := -\sup \sigma(\partial\Phi(c))$.

- (i) *If (1) holds then the solution to (P) is exponentially stable. More precisely, given $\omega \in (0, \omega_0)$, there exist positive constants M and δ such that for all $f_0 \in h^{4+\alpha}(\mathbb{S})$ with $\|f_0 - c\|_{C^{4+\alpha}(\mathbb{S})} \leq \delta$ the solution to (P) corresponding to f_0 exists in the large and for all $t \geq 0$ it holds that*

$$\|f(t) - c\|_{C^{4+\alpha}(\mathbb{S})} + \|f'(t)\|_{C^{1+\alpha}(\mathbb{S})} \leq Me^{-\omega t} \|f_0 - c\|_{C^{4+\alpha}(\mathbb{S})}.$$

- (ii) *If (2) holds then the flat solution $f = c$ is unstable.*



The Case $b'(c) > 0$

Stability condition

$$b'(c) < -\frac{2\iota^2}{(1-c)^2} + g\rho,$$

which means:



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which means:

- ▶ $b'(c) < g\rho$,
- ▶ the larger c the lower ι ,
- ▶ critical maximum value $\iota_* := \frac{|1-c|}{2} \sqrt{2(g\rho - b'(c))}$

