# TAMED 3D NAVIER-STOKES EQUATION: EXISTENCE, UNIQUENESS AND REGULARITY 

MICHAEL RÖCKNER, XICHENG ZHANG<br>Fakultät für Mathematik, Universität Bielefeld<br>Postfach 100131, D-33501 Bielefeld, Germany<br>M. Röckner: roeckner@math.uni-bielefeld.de<br>X. Zhang: xzhang@math.uni-bielefeld.de


#### Abstract

In this paper, we prove the existence and uniqueness of a smooth solution to a tamed 3D Navier-Stokes equation in the whole space. In particular, if there exists a bounded smooth solution to the classical 3D Navier-Stokes equation, then this solution satisfies our tamed equation. Moreover, using this renomalized equation we can give a new construction for a suitable weak solution of the classical 3D Navier-Stokes equation introduced in [13] and [2].


## 1. Introduction and Main Results

Let $\mathbf{u}(t, x)=\left(u^{1}(t, x), u^{2}(t, x), u^{3}(t, x)\right)$ be a row vector valued function on $[0, \infty) \times \mathbb{R}^{3}$. The following notations will be used throughout this paper:

$$
\begin{gathered}
|\mathbf{u}|^{2}:=\sum_{i=1}^{3}\left|u^{i}\right|^{2}, \quad \partial_{t} u^{j}:=\frac{\partial u^{j}}{\partial t}, \quad \partial_{i} u^{j}:=\frac{\partial u^{j}}{\partial x_{i}}, \quad i, j=1,2,3 \\
\nabla u^{j}(t):=\left(\partial_{1} u^{j}(t), \partial_{2} u^{j}(t), \partial_{3} u^{j}(t)\right), \quad \Delta u^{j}(t):=\sum_{i=1}^{3} \partial_{i}^{2} u^{j}(t), \quad j=1,2,3 \\
\operatorname{div}(\mathbf{u}(t)):=\sum_{i=1}^{3} \partial_{i} u^{i}(t), \quad(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t):=\sum_{i=1}^{3} u^{i}(t) \partial_{i} \mathbf{u}(t) .
\end{gathered}
$$

Consider the following Navier-Stokes equation in $\mathbb{R}^{3}$

$$
\begin{equation*}
\partial_{t} \mathbf{u}(t)=\nu \Delta \mathbf{u}(t)-(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t)+\nabla p(t)+\mathbf{f}(t), \tag{1}
\end{equation*}
$$

subject to the incompressible condition:

$$
\begin{equation*}
\operatorname{div}(\mathbf{u}(t))=0 \tag{2}
\end{equation*}
$$

and initial conditions:

$$
\begin{equation*}
\mathbf{u}(0, x)=\mathbf{u}_{0}(x), \quad \operatorname{div}\left(\mathbf{u}_{0}\right)=0 \tag{3}
\end{equation*}
$$

Here $\mathbf{u}(t, x)$ represents the velocity field, $\nu>0$ is the viscosity constant, the pressure $p(t, x)$ is an unknown scalar function, and the external force $\mathbf{f}$ is a known vector valued function.

The concepts of weak solutions of (1)-(3) and their regularities were already introduced in the fundamental paper of Leray [10]. Pioneering work of Leray [10] and Hopf [7] showed that for any $\mathbf{u}_{0} \in L^{2}\left(\mathbb{R}^{3}\right)$ and $\mathbf{f} \in L^{2}\left([0, T] \times \mathbb{R}^{3} ; \mathbb{R}^{3}\right)$, there exist functions $\mathbf{u}$ and $p$ such that
(i) $\mathbf{u} \in L^{\infty}\left([0, T] ; L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right) \cap L^{2}\left([0, T] ; \mathbb{H}^{1}\right) ;$
(ii) the equation (1) holds for $\mathbf{u}, p$ in the sense of distribution;
(iii) for almost all $t \in[0, T]$, the following energy inequality holds

$$
\|\mathbf{u}(t)\|_{L^{2}}^{2}+2 \nu \int_{0}^{t}\|\mathbf{u}(s)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s \leqslant\left\|\mathbf{u}_{0}\right\|_{L^{2}}^{2}+2 \int_{0}^{t}\langle\mathbf{f}(s), \mathbf{u}(s)\rangle_{L^{2}} \mathrm{~d} s
$$

(iv) $\lim _{t \downarrow 0}\left\|\mathbf{u}(t)-\mathbf{u}_{0}\right\|_{L^{2}}=0$.

Here $\mathbb{H}^{1}$ stands for the Sobolev space of order one in $L^{2}$ of divergence free vector fields on $\mathbb{R}^{3}$.

It is well known that such $\mathbf{u}$ is unique for the 2 D Navier-Stokes equation. However, in the case of three dimensions, the uniqueness is only proved for small initial data $\mathbf{u}_{0}$ and $\mathbf{f}$ or for large enough $\nu$. On the other hand, for any $\nu$ and $\mathbf{u}_{0}, \mathbf{f}$, Fabes-Jones-Rivière [1](see also [5]) proved that for some small $T_{*}\left(\right.$ depending on $\nu$ and $\left.\mathbf{u}_{0}, \mathbf{f}\right)$, there exists a unique smooth solution to (1)-(3) on the time interval $\left[0, T_{*}\right)$. To compensate for the non-linear term $(\mathbf{u} \cdot \nabla) \mathbf{u}$, let us consider the following tamed Navier-Stokes equation in $\mathbb{R}^{3}$ :

$$
\begin{equation*}
\partial_{t} \mathbf{u}(t)=\nu \Delta \mathbf{u}(t)-(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t)+\nabla p(t)-g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)+\mathbf{f}(t) \tag{4}
\end{equation*}
$$

subject to the incompressibility condition:

$$
\begin{equation*}
\operatorname{div}(\mathbf{u}(t))=0 \tag{5}
\end{equation*}
$$

and initial conditions:

$$
\begin{equation*}
\mathbf{u}(0, x)=\mathbf{u}_{0}(x), \quad \operatorname{div}\left(\mathbf{u}_{0}\right)=0 \tag{6}
\end{equation*}
$$

where $N>0$ and $g_{N}: \mathbb{R}^{+} \mapsto \mathbb{R}^{+}$is a smooth function such that

$$
\left\{\begin{array}{l}
g_{N}(r):=0, \quad r \in[0, N]  \tag{7}\\
g_{N}(r):=r-N-\frac{1}{2} \\
0 \leqslant g_{N}^{\prime}(r) \leqslant C_{\nu}, \quad r \geqslant N+1 \\
\left|g_{N}^{(k)}(r)\right| \leqslant C_{\nu, k}, \quad r \geqslant 0, k \in \mathbb{N}
\end{array}\right.
$$

that is, $g_{N}$ qualitatively looks as follows for $\nu<1$ :


Figure: taming function: $r \mapsto g_{N}(r)$
Here and below we shall use the following convention: The letter $C$ with subscripts will denote a constant depending only on its subscripts. The letter $C$ without subscripts will denote an absolute constant, i.e., its value does not depend on any data. All the constants may have different values in different places.

Let us say some words about the tamed function $g_{N}$. From the construction of $g_{N}$, one sees that if $\mathbf{u}(t, x)$ is a bounded smooth solution of (1)-(3) (say bounded by $\sqrt{N}$ ), then $\mathbf{u}(t, x)$ also satisfies (4)-(6). Intuitively, when the velocity of the fluid is larger than $\sqrt{N}$, the dissipative term $g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)$ (regarded as some extra force) will enter into the equation and restrain the flux of the liquid. In this sense, the value of $N$ plays the role of a valve. As stated in [3], the velocities observed in turbulent flows on earth are bounded. If one accepts this as a physical assumption, and if the system (1)-(3) precisely describes the physical phenomenon, the solution of (1)-(3) should be bounded. Thus, the tamed
system (4)-(6) may serve as a substitute of (1)-(3). Moreover, when we realize Eq. (4)-(6) on a computer, the value of $N$ can be reset as an arbitrarily large number along with the process of calculations as long as there is no explosion. So, the term involving $g_{N}$ serves as some kind of adjustment.

Our main aim in the present paper is to prove the following:
Theorem 1.1. Assume $\nu=1$. Let $\mathbf{u}_{0} \in \mathbb{H}^{\infty}:=\cap_{m \in \mathbb{N}} \mathbb{H}^{m}$ and $[0, \infty) \ni t \mapsto \mathbf{f}(t) \in \mathbb{H}^{m}$ be smooth for any $m \in \mathbb{N}$. Then there exist a unique smooth velocity field

$$
\mathbf{u}_{N} \in C^{\infty}\left([0, \infty) \times \mathbb{R}^{3} ; \mathbb{R}^{3}\right) \cap C\left([0, \infty) ; \mathbb{H}^{1}\right)
$$

and a pressure function(defined up to a time dependent constant)

$$
p_{N} \in C^{\infty}\left([0, \infty) \times \mathbb{R}^{3} ; \mathbb{R}\right)
$$

solving (4)-(6). Here the divergence free Sobolev spaces $\mathbb{H}^{m}$ are defined by (13) below.
Moreover, we have the following:
( $1^{\circ}$ ) For any $T>0$

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{2}+\int_{0}^{T}\left\|\mathbf{u}_{N}(s)\right\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s \leqslant C\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{0}}^{2}+\left[\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}} \mathrm{~d} s\right]^{2}\right) \tag{8}
\end{equation*}
$$

(2 $2^{\circ}$ ) For some absolute constant $C>0$ and any $T, N>0$

$$
\begin{gather*}
\sup _{t \in[0, T]}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{T}\left\|\mathbf{u}_{N}(s)\right\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}} \cdot(1+N),  \tag{9}\\
\sup _{t \in[0, T]}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{2}}^{2} \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}}^{\prime}+C_{T, \mathbf{u}_{0}, \mathbf{f}} \cdot\left(1+N^{2}\right), \tag{10}
\end{gather*}
$$

where

$$
\begin{aligned}
C_{T, \mathbf{u}_{0}, \mathbf{f}} & :=C(T+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{4}+\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) \\
C_{T, \mathbf{u}_{0}, \mathbf{f}}^{\prime} & :=C\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{2}}^{6}+\sup _{t \in[0, T]}\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2}+\int_{0}^{T}\left\|\partial_{s} \mathbf{f}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) .
\end{aligned}
$$

$\left(3^{\circ}\right)$ Let $(\mathbf{u}, p)$ be any Leray-Hopf solution of (1)-(3) on $[0, T]$. If either

$$
\mathbf{u} \in L^{\infty}\left([0, T] ; L^{3}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)
$$

or

$$
\mathbf{u} \in L^{q}\left([0, T] ; L^{r}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right), \quad \frac{3}{r}+\frac{2}{q}=1
$$

holds, then for any bounded domain $\Omega$

$$
\lim _{N \rightarrow \infty} \int_{0}^{T} \int_{\Omega}\left|\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t=0
$$

Remark 1.2. By an inequality of Xie [17](see [6, Theorem 2.1]) we know that

$$
\begin{equation*}
\sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right|^{2} \leqslant \frac{1}{2 \pi}\left\|\Delta \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}} \cdot\left\|\nabla \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}} \tag{11}
\end{equation*}
$$

Hence (9) and (10) imply that if $\mathbf{u}_{0}$ has small enough $\mathbb{H}^{3}$-norm and if $\mathbf{f}$ and $\partial_{s} f$ have small enough $\mathbb{H}^{0}$-norm, then

$$
\sup _{t \in[0, T]} \sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right| \leqslant \sqrt{N}
$$

and (4)-(6) reduces to (1)-(3), that is, $\mathbf{u}_{N}$ solves (1)-(3). Moreover, define for any $T, N>$ 0

$$
A_{T, N}:=\left\{t \in[0, T]: \sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right| \geqslant \sqrt{N}\right\}
$$

By (11) (8) and (9), we have

$$
\begin{aligned}
\lambda\left(A_{T, N}\right) & \leqslant \frac{1}{N} \int_{0}^{T} \sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right|^{2} \mathrm{~d} t \\
& \leqslant \frac{1}{2 \pi N} \int_{0}^{T}\left\|\Delta \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}} \cdot\left\|\nabla \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}} \mathrm{~d} t \\
& \leqslant \frac{1}{2 \pi N}\left(\int_{0}^{T}\left\|\Delta \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} t\right)^{1 / 2}\left(\int_{0}^{T}\left\|\nabla \mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} t\right)^{1 / 2} \\
& \leqslant \frac{C_{T, \mathbf{u}_{0}, \mathbf{f}} \cdot(1+N)^{1 / 2}}{2 \pi N}
\end{aligned}
$$

where $\lambda\left(A_{T, N}\right)$ denotes the Lebesgue measure of $A_{T, N}$. In particular,

$$
\lim _{N \rightarrow \infty} \lambda\left(A_{T, N}\right)=0
$$

which shows that as $N$ tends to infinity, the solution of (4)-(6) satisfies (1)-(3) at "almost all" times. Note that the following interpolation inequality(see (12) below)

$$
\sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right|^{2} \leqslant C\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{2}}^{3 / 2} \cdot\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{1 / 2}
$$

For solving (1)-(3), an open question is to find an $\alpha<4 / 3$ such that for any $N>0$

$$
\sup _{t \in[0, T]}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{2}}^{2} \leqslant C_{T, \mathbf{u}_{0}, f}\left(1+N^{\alpha}\right)
$$

Remark 1.3. Define

$$
\tau_{N}:=\inf \left\{t>0: \sup _{x \in \mathbb{R}^{3}}\left|\mathbf{u}_{N}(t, x)\right| \geqslant N\right\} .
$$

Clearly, $\mathbf{u}_{N}\left(t \wedge \tau_{N}, x\right)$ together with some pressure function $p_{N}$ solves (1)-(3). By the uniqueness of solutions to (4)-(6), we have

$$
\mathbf{u}_{N+1}(t, x)=\mathbf{u}_{N}(t, x), \quad \forall(t, x) \in\left[0, \tau_{N}\right) \times \mathbb{R}^{3}
$$

and

$$
\tau_{N} \leqslant \tau_{N+1} .
$$

Define

$$
\tau_{\infty}:=\lim _{N \rightarrow \infty} \tau_{N}
$$

and for all $(t, x) \in\left[0, \tau_{N}\right) \times \mathbb{R}^{3}$

$$
\mathbf{u}(t, x):=\mathbf{u}_{N}(t, x)
$$

Then $\mathbf{u}$ together with some pressure function $p$ satisfies (1)-(3) on $\left[0, \tau_{\infty}\right) \times \mathbb{R}^{3}$. In particular, $\tau_{\infty}$ is the first epoch of irregularity of $\mathbf{u}($ see $[10,4])$.
Remark 1.4. Our tamed scheme also works for the periodic case as can be seen from the proof below.

The approach of proving this theorem is the classical Galerkin's approximation. Instead of working on $\mathbb{H}^{0}$, we shall take $\mathbb{H}^{1}$ as our basic space. The special form of the taming function $g_{N}$ plays a crucial role. As explained above, (4)-(6) may serve as an approximation of (1)-(3). In fact, in Section 4 we shall present a new construction for the "suitable weak solution" introduced in [13] and [2] by using $\mathbf{u}_{N}$. This notion was used to obtain partial regularity of such type of solutions(cf. [2] [11]). We note that it is not at all clear if weak solutions obtained by the well known Galerkin approximation procedure(see [15]) are "suitable weak solution".

This paper is organized as follows: in Section 2, some preliminary lemmas are proved. In Section 3, we prove the existence and uniqueness of weak solution to system (4)-(6). In Section 4, a suitable weak solution of (1)-(3) is constructed. Finally, in Section 5 our main Theorem 1.1 is proved.

## 2. Preliminaries

Let $C_{0}^{\infty}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ denote the set of smooth functions from $\mathbb{R}^{3}$ to $\mathbb{R}^{3}$ with compact supports. For $p \geqslant 1$, let $L^{p}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ be the vector valued $L^{p}$-space in which the norm is denoted by $\|\cdot\|_{L^{p}}$. For $m \in \mathbb{N}_{0}:=\mathbb{N} \cup\{0\}$, let $W^{m, p}$ be the usual Sobolev space on $\mathbb{R}^{3}$ with values in $\mathbb{R}^{3}$, i.e., the closure of $C_{0}^{\infty}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ with respect to the norm:

$$
\|\mathbf{u}\|_{m, p}=\left(\int_{\mathbb{R}^{3}}\left|(I-\Delta)^{m / 2} \mathbf{u}\right|^{p} \mathrm{~d} x\right)^{1 / p}
$$

Here as usual $(I-\Delta)^{m / 2}$ is defined by Fourier's transformation. This norm is equivalent to the norm given by

$$
\|\mathbf{u}\|_{m, p}:=\sum_{j=0}^{m}\left(\int_{\mathbb{R}^{3}}\left|\nabla^{j} \mathbf{u}\right|^{p} \mathrm{~d} x\right)^{1 / p}
$$

where $\nabla^{j} \mathbf{u}$ denotes the total derivative of $\mathbf{u}$ of order $j$.
The following Sobolev type interpolation inequality will be used frequently and play an essential role in the study of Navier-Stokes equation(cf. [16, Theorem 2.15]). Let $p, q, r \geqslant 1$ and $0 \leqslant j<m$. If $m-j-3 / p$ is not a non-negative integer and

$$
\frac{1}{r}=\frac{j}{3}+\alpha\left(\frac{1}{p}-\frac{m}{3}\right)+\frac{1-\alpha}{q}, \quad \frac{j}{m} \leqslant \alpha \leqslant 1,
$$

then for any $\mathbf{u} \in W^{m, p} \cap L^{q}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$

$$
\begin{equation*}
\left\|\nabla^{j} \mathbf{u}\right\|_{L^{r}} \leqslant C_{m, j, p, q, r}\|\mathbf{u}\|_{m, p}^{\alpha}\|\mathbf{u}\|_{L^{q}}^{1-\alpha} . \tag{12}
\end{equation*}
$$

Set

$$
\begin{equation*}
\mathbb{H}^{m}:=\left\{\mathbf{u} \in W^{m, 2}: \operatorname{div}(\mathbf{u})=0\right\} \tag{13}
\end{equation*}
$$

where div is taken in the sense of Schwartz distributions. Then $\left(\mathbb{H}^{m},\|\cdot\|_{m, 2}\right)$ is a separable Hilbert space. We shall denote the norm $\|\cdot\|_{m, 2}$ in $\mathbb{H}^{m}$ by $\|\cdot\|_{\mathbb{H}^{m}}$. We remark that $\mathbb{H}^{0}$ is a closed linear subspace of the Hilbert space $L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ and that by [16, Theorem 2.21] we have both $\mathbb{H}^{1} \subset L^{r}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right)$ and $\mathbb{H}^{2} \subset W^{1, r} \cap L^{q}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right)$ continuously if $r \in[2,6]$, $q \in[2, \infty)$.

Let $R_{j}$ be the $j$-th Riesz transform(cf. [14]), i.e., for $f \in L^{1}\left(\mathbb{R}^{3}\right)$

$$
R_{j}(f)(x):=\lim _{\epsilon \rightarrow 0} c_{3} \int_{|y| \geqslant \epsilon} \frac{y_{j}}{|y|^{4}} f(x-y) \mathrm{d} y, \quad j=1,2,3,
$$

where $c_{3}:=\Gamma(2) / \pi^{2}$. Let $P$ be the orthogonal projection operator from $L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ to $\mathbb{H}^{0}$. Then $P$ can be expressed by $R_{j}$ as(cf. [1] [12])

$$
P(\mathbf{f})=\mathbf{f}+\sum_{j=1}^{3} \mathbf{R} R_{j}\left(f^{j}\right),
$$

where $\mathbf{R}:=R_{1} \otimes R_{2} \otimes R_{3}$. It is well known that $P$ can be restricted to a bounded linear operator from $W^{m, 2}$ to $\mathbb{H}^{m}$, and that $P$ commutes with the derivative operators. For any $\mathbf{u} \in \mathbb{H}^{0}$ and $\mathbf{v} \in L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$, we have

$$
\langle\mathbf{u}, \mathbf{v}\rangle_{\mathbb{H}^{0}}:=\langle\mathbf{u}, P \mathbf{v}\rangle_{\mathbb{H}^{0}}=\langle\mathbf{u}, \mathbf{v}\rangle_{L^{2}} .
$$

Let $\mathcal{V}$ be defined by

$$
\mathcal{V}:=\left\{\mathbf{u}: \mathbf{u} \in C_{0}^{\infty}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right), \operatorname{div}(\mathbf{u})=0\right\} .
$$

We have the following density result.
Lemma 2.1. $\mathcal{V}$ is dense in $\mathbb{H}^{m}$ for any $m \in \mathbb{N}$.
Proof. For $\rho>0$, let $\omega_{\rho}$ be a mollifier, i.e., positive smooth function on $\mathbb{R}^{3}$ with support in $\left\{x \in \mathbb{R}^{3}:|x| \leqslant \rho\right\}$ and $\int_{\mathbb{R}^{3}} \omega_{\rho}(x) \mathrm{d} x=1$. For $\mathbf{u} \in \mathbb{H}^{m}$, set $\mathbf{u}_{\rho}(x):=\int_{\mathbb{R}^{3}} \mathbf{u}(y) \omega_{\rho}(x-y) \mathrm{d} y$, then $\mathbf{u}_{\rho} \in \cap_{k \in \mathbb{N}} \mathbb{H}^{k}$. For proving the density of $\mathcal{V}$ in $\mathbb{H}^{m}$, it suffices to prove that $\langle\mathbf{u}, \mathbf{v}\rangle_{\mathbb{H}^{m}}=$ 0 for any $\mathbf{v} \in \mathcal{V}$ implies that $\mathbf{u}=0$. Noting that $\mathbf{v}_{\rho} \in \mathcal{V}$ if $\mathbf{v} \in \mathcal{V}$, we have

$$
\begin{aligned}
0=\left\langle\mathbf{u}, \mathbf{v}_{\rho}\right\rangle_{\mathbb{H}^{m}} & =\left\langle\mathbf{u},(I-\Delta)^{m} \mathbf{v}_{\rho}\right\rangle_{\mathbb{H}^{0}} \\
& =\left\langle\mathbf{u},\left((I-\Delta)^{m} \mathbf{v}\right)_{\rho}\right\rangle_{\mathbb{H}^{0}} \\
& =\left\langle\mathbf{u}_{\rho},(I-\Delta)^{m} \mathbf{v}\right\rangle_{\mathbb{H}^{0}} \\
& =\left\langle(I-\Delta)^{m} \mathbf{u}_{\rho}, \mathbf{v}\right\rangle_{\mathbb{H}^{0}} .
\end{aligned}
$$

Hence, by [15, Proposition 1.1] there exists a function $p$ such that

$$
(I-\Delta)^{m} \mathbf{u}_{\rho}=\nabla p
$$

which leads to

$$
\int_{\mathbb{R}^{3}}\left|(I-\Delta)^{m} \mathbf{u}_{\rho}\right|^{2} \mathrm{~d} x=\int_{\mathbb{R}^{3}}(I-\Delta)^{m} \mathbf{u}_{\rho} \cdot \nabla p \mathrm{~d} x=0 .
$$

Therefore, $\mathbf{u}_{\rho}=0$ for any $\rho>0$. By taking the limits $\rho \downarrow 0$, we obtain $\mathbf{u}=0$. The proof is thus complete.

In the following, for the sake of simplicity, we assume that $\nu=1$. For $\mathbf{u} \in \mathbb{H}^{1}$ and $\mathbf{v} \in \mathcal{V}$, define

$$
\llbracket A(\mathbf{u}), \mathbf{v} \rrbracket_{0}:=\langle\mathbf{u}, \Delta \mathbf{v}\rangle_{\mathbb{H}^{0}}-\langle(\mathbf{u} \cdot \nabla) \mathbf{u}, \mathbf{v}\rangle_{\mathbb{H}^{0}}-\left\langle g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u}, \mathbf{v}\right\rangle_{\mathbb{H}^{0}},
$$

and

$$
\begin{align*}
\llbracket A(\mathbf{u}), \mathbf{v} \rrbracket & :=\llbracket A(\mathbf{u}),(I-\Delta) \mathbf{v} \rrbracket_{0}  \tag{14}\\
& =: A_{1}(\mathbf{u}, \mathbf{v})+A_{2}(\mathbf{u}, \mathbf{v})+A_{3}(\mathbf{u}, \mathbf{v}),
\end{align*}
$$

where

$$
\begin{aligned}
A_{1}(\mathbf{u}, \mathbf{v}) & :=\langle\mathbf{u}, \Delta \mathbf{v}\rangle_{\mathbb{H}^{1}} \\
A_{2}(\mathbf{u}, \mathbf{v}) & :=-\langle(\mathbf{u} \cdot \nabla) \mathbf{u},(I-\Delta) \mathbf{v}\rangle_{\mathbb{H}^{0}} \\
A_{3}(\mathbf{u}, \mathbf{v}) & :=-\left\langle g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u},(I-\Delta) \mathbf{v}\right\rangle_{\mathbb{H}^{0}} .
\end{aligned}
$$

Obviously, if $\mathbf{u} \in \mathbb{H}^{2}$ the functional $\mathbf{v} \mapsto \llbracket A(\mathbf{u}), \mathbf{v} \rrbracket_{0}$ can be identified with the function

$$
\Delta \mathbf{u}-\left(\mathbf{u} \cdot \nabla \underset{6}{\mathbf{u}}-g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u}\right.
$$

which is in $\mathbb{H}^{0}$ since by (12) for $\mathbf{u} \in \mathbb{H}^{2}, \mathbf{u} \in L^{r}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right)$ for all $r \geqslant 2$ and $\nabla \mathbf{u} \in L^{6}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right)$.
We now prepare two lemmas for later use.
Lemma 2.2. For any $\mathbf{u} \in \mathbb{H}^{1}$ and $\mathbf{v} \in \mathcal{V}$

$$
|\llbracket A(\mathbf{u}), \mathbf{v} \rrbracket| \leqslant C\left(1+\|\mathbf{u}\|_{\mathbb{H}^{1}}^{3}\right)\|\mathbf{v}\|_{\mathbb{H}^{3}} .
$$

So, by Lemma 2.1, $\llbracket A(\mathbf{u}), \cdot \rrbracket$ can be considered as an element in $\left(\mathbb{H}^{3}\right)^{\prime}$ with norm bounded by $C\left(1+\|\mathbf{u}\|_{\mathbb{H}^{1}}^{3}\right)$. Furthermore, if $\mathbf{u} \in \mathbb{H}^{1}$, then

$$
\begin{equation*}
\llbracket A(\mathbf{u}), \mathbf{u} \rrbracket_{0}=-\|\nabla \mathbf{u}\|_{\mathbb{H}^{0}}^{2}-\left\|\sqrt{g_{N}\left(|\mathbf{u}|^{2}\right)} \cdot|\mathbf{u}|\right\|_{L^{2}}^{2} \tag{15}
\end{equation*}
$$

and if $\mathbf{u} \in \mathbb{H}^{2}$, then

$$
\begin{equation*}
\llbracket A(\mathbf{u}), \mathbf{u} \rrbracket \leqslant-\frac{1}{2}\|\mathbf{u}\|_{\mathbb{H}^{2}}^{2}-\frac{1}{2}\||\mathbf{u}| \cdot \mid \nabla \mathbf{u}\|_{L^{2}}^{2}+\left(\frac{3}{2}+N\right)\|\nabla \mathbf{u}\|_{\mathbb{H}^{0}}^{2}+\|\mathbf{u}\|_{\mathbb{H}^{0}}^{2} \tag{16}
\end{equation*}
$$

Proof. First of all, it is clear that

$$
A_{1}(\mathbf{u}, \mathbf{v})=\left\langle(I-\Delta)^{1 / 2} \mathbf{u},(I-\Delta)^{1 / 2} \Delta \mathbf{v}\right\rangle_{\mathbb{H}^{0}} \leqslant C\|\mathbf{u}\|_{\mathbb{H}^{1}}\|\mathbf{v}\|_{\mathbb{H}^{3}} .
$$

By the Sobolev inequality (12), we have

$$
A_{2}(\mathbf{u}, \mathbf{v})=\left\langle\mathbf{u}^{*} \cdot \mathbf{u}, \nabla(I-\Delta) \mathbf{v}\right\rangle_{\mathbb{H}^{0}} \leqslant\left\|\mathbf{u}^{*} \cdot \mathbf{u}\right\|_{\mathbb{H}^{0}} \cdot\|\nabla(I-\Delta) \mathbf{v}\|_{\mathbb{H}^{0}} \leqslant C\|\mathbf{u}\|_{\mathbb{H}^{1}}^{2} \cdot\|\mathbf{v}\|_{\mathbb{H}^{3}},
$$

where $\mathbf{u}^{*}$ denotes the transposition of the row vector $\mathbf{u}$, and

$$
A_{3}(\mathbf{u}, \mathbf{v}) \leqslant\|\mathbf{u}\|_{L^{6}}^{3} \cdot\|(I-\Delta) \mathbf{v}\|_{\mathbb{H}^{0}} \leqslant C\|\mathbf{u}\|_{\mathbb{H}^{1}}^{3} \cdot\|\mathbf{v}\|_{\mathbb{H}^{2}} .
$$

Hence

$$
|\llbracket A(\mathbf{u}), \mathbf{v} \rrbracket| \leqslant C\left(\|\mathbf{u}\|_{\mathbb{H}^{1}}+\|\mathbf{u}\|_{\mathbb{H}^{1}}^{2}+\|\mathbf{u}\|_{\mathbb{H}^{1}}^{3}\right)\|\mathbf{v}\|_{\mathbb{H}^{3}}
$$

which gives the first assertion.
The equality (15) clearly follows from

$$
\langle(\mathbf{u} \cdot \nabla) \mathbf{u}, \mathbf{u}\rangle_{\mathbb{H}^{0}}=0 .
$$

For the inequality (16), we have

$$
\begin{aligned}
A_{1}(\mathbf{u}, \mathbf{u}) & =-\|(I-\Delta) \mathbf{u}\|_{\mathbb{H}^{0}}^{2}+\langle\mathbf{u},(I-\Delta) \mathbf{u}\rangle_{\mathbb{H}^{0}} \\
& =-\|\mathbf{u}\|_{\mathbb{H}^{2}}^{2}+\|\nabla \mathbf{u}\|_{\mathbb{H}^{0}}^{2}+\|\mathbf{u}\|_{\mathbb{H}^{0}}^{2},
\end{aligned}
$$

and by Young's inequality

$$
\begin{aligned}
A_{2}(\mathbf{u}, \mathbf{u}) & \leqslant \frac{1}{2}\|(I-\Delta) \mathbf{u}\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2}\|(\mathbf{u} \cdot \nabla) \mathbf{u}\|_{\mathbb{H}^{0}}^{2} \\
& \leqslant \frac{1}{2}\|\mathbf{u}\|_{\mathbb{H}^{2}}^{2}+\frac{1}{2}\||\mathbf{u}| \cdot \mid \nabla \mathbf{u}\|_{\mathbb{H}^{0}}^{2},
\end{aligned}
$$

where

$$
|\mathbf{u}|^{2}=\sum_{k=1}^{3}\left|v^{k}\right|^{2}, \quad|\nabla \mathbf{u}|^{2}=\sum_{k, i=1}^{3}\left|\partial_{i} v^{k}\right|^{2} .
$$

Noting that

$$
\begin{equation*}
g_{N}\left(|\mathbf{u}|^{2}\right) \geqslant|\mathbf{u}|^{2}-(N+1 / 2) \quad \text { and } \quad g_{N}^{\prime}\left(|\mathbf{u}|^{2}\right) \geqslant 0 \tag{17}
\end{equation*}
$$

we have

$$
\begin{aligned}
A_{3}(\mathbf{u}, \mathbf{u}) & =-\left\langle\nabla\left(g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u}\right), \nabla \mathbf{u}\right\rangle_{\mathbb{H}^{0}}-\left\langle g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u}, \mathbf{u}\right\rangle_{\mathbb{H}^{0}} \\
& =-\sum_{k, i=1}^{3} \int_{\mathbb{R}^{3}} \partial_{i} u^{k} \cdot \partial_{i}\left(g_{N}\left(|\mathbf{u}|^{2}\right) u^{k}\right) \mathrm{d} x-\int_{\mathbb{R}^{3}}|\mathbf{u}|^{2} \cdot g_{N}\left(|\mathbf{u}|^{2}\right) \mathrm{d} x
\end{aligned}
$$

$$
\begin{aligned}
& \leqslant-\sum_{k, i=1}^{3} \int_{\mathbb{R}^{3}} \partial_{i} u^{k} \cdot\left(g_{N}\left(|\mathbf{u}|^{2}\right) \cdot \partial_{i} u^{k}-g_{N}^{\prime}\left(|\mathbf{u}|^{2}\right) \partial_{i}|\mathbf{u}|^{2} \cdot u^{k}\right) \mathrm{d} x \\
& =-\int_{\mathbb{R}^{3}}|\nabla \mathbf{u}|^{2} \cdot g_{N}\left(|\mathbf{u}|^{2}\right) \mathrm{d} x-\left.\left.\frac{1}{2} \int_{\mathbb{R}^{3}} g_{N}^{\prime}\left(|\mathbf{u}|^{2}\right)|\nabla| \mathbf{u}\right|^{2}\right|^{2} \mathrm{~d} x \\
& \leqslant-\int_{\mathbb{R}^{3}}|\nabla \mathbf{u}|^{2} \cdot|\mathbf{u}|^{2} \mathrm{~d} x+(N+1 / 2)\|\nabla \mathbf{u}\|_{\mathbb{H}^{0}}^{2} .
\end{aligned}
$$

Combining the above calculations yields (16).
Lemma 2.3. Let $\mathbf{u}_{n}, \mathbf{v} \in \mathcal{V}$ and $\mathbf{u} \in \mathbb{H}^{1}$. Let $\Omega:=\operatorname{supp} \mathbf{v}$ and assume that

$$
\sup _{n}\left\|\mathbf{u}_{n}\right\|_{\mathbb{H}^{1}}<+\infty \text { and } \lim _{n \rightarrow \infty}\left\|\left(\mathbf{u}_{n}-\mathbf{u}\right) \cdot 1_{\Omega}\right\|_{L^{2}}=0
$$

Then

$$
\lim _{n \rightarrow \infty} \llbracket A\left(\mathbf{u}_{n}\right), \mathbf{v} \rrbracket=\llbracket A(\mathbf{u}), \mathbf{v} \rrbracket .
$$

Proof. For $A_{1}$, we clearly have

$$
\lim _{n \rightarrow \infty}\left|A_{1}\left(\mathbf{u}_{n}, \mathbf{v}\right)-A_{1}(\mathbf{u}, \mathbf{v})\right|=\lim _{n \rightarrow \infty}\left|\left\langle\left(\mathbf{u}_{n}-\mathbf{u}\right) \cdot 1_{\Omega},(I-\Delta) \Delta \mathbf{v}\right\rangle_{\mathbb{H}^{0}}\right|=0
$$

For $A_{2}$, obviously

$$
\begin{aligned}
& \lim _{n \rightarrow \infty}\left|A_{2}\left(\mathbf{u}_{n}, \mathbf{v}\right)-A_{2}(\mathbf{u}, \mathbf{v})\right| \\
= & \lim _{n \rightarrow \infty}\left|\left\langle\mathbf{u}_{n}^{*} \cdot \mathbf{u}_{n}-\mathbf{u}^{*} \cdot \mathbf{u}, \nabla(I-\Delta) \mathbf{v}\right\rangle_{\mathbb{H}^{0}}\right|=0
\end{aligned}
$$

For $A_{3}$, we have because $\left|g_{N}^{\prime}\right| \leqslant C$ and by (12)

$$
\begin{aligned}
& \lim _{n \rightarrow \infty}\left|A_{3}\left(\mathbf{u}_{n}, \mathbf{v}\right)-A_{3}(\mathbf{u}, \mathbf{v})\right| \\
\leqslant & C \sup _{x \in \mathbb{R}^{3}}|(I-\Delta) \mathbf{v}(x)| \cdot \lim _{n \rightarrow \infty}\left(\left\|\mathbf{u}_{n}\right\|_{\mathbb{H}^{1}}^{2} \cdot\left\|\left(\mathbf{u}_{n}-\mathbf{u}\right) \cdot 1_{\Omega}\right\|_{L^{2}}\right)=0 .
\end{aligned}
$$

The proof is complete.

## 3. Existence and Uniqueness of Weak Solution

We first give the following definition of a generalized solution to (4)-(6) according to [8].
Definition 3.1. Let $T>0, \mathbf{u}_{0} \in \mathbb{H}^{0}$ and $\mathbf{f} \in L^{2}\left([0, T] ; \mathbb{H}^{0}\right)$. A measurable vector field $\mathbf{u}$ on $[0, T] \times \mathbb{R}^{3}$ is called a generalized solution of (4)-(6) if
$\left(1^{o}\right) \mathbf{u} \in L^{\infty}\left([0, T] ; L^{4}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right) \cap L^{2}\left([0, T] ; \mathbb{H}^{1}\right)$;
( $2^{\circ}$ ) for any $\mathbf{v} \in \mathcal{V}$ and $t \in[0, T]$,

$$
\begin{align*}
\langle\mathbf{u}(t), \mathbf{v}\rangle_{\mathbb{H}^{0}}= & \left\langle\mathbf{u}_{0}, \mathbf{v}\right\rangle_{\mathbb{H}^{0}}-\int_{0}^{t}\langle\nabla \mathbf{u}(s), \nabla \mathbf{v}\rangle_{\mathbb{H}^{0}} \mathrm{~d} s-\int_{0}^{t}\langle(\mathbf{u}(s) \cdot \nabla) \mathbf{u}(s), \mathbf{v}\rangle_{\mathbb{H}^{0}} \mathrm{~d} s \\
& -\int_{0}^{t}\left\langle g_{N}\left(|\mathbf{u}(s)|^{2}\right) \mathbf{u}(s), \mathbf{v}\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} s+\int_{0}^{t}\langle\mathbf{f}(s), \mathbf{v}\rangle_{\mathbb{H}^{0}} \mathrm{~d} s \tag{18}
\end{align*}
$$

$\left(3^{o}\right) \lim _{t \downarrow 0}\left\|\mathbf{u}(t)-\mathbf{u}_{0}\right\|_{L^{2}}=0$.
Remark 3.2. In the definition of a weak solution of the classical Navier-Stokes equation $($ i.e., $N=\infty)$, $\mathbf{u} \in L^{\infty}\left([0, T] ; L^{4}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)$ is replaced by $\mathbf{u} \in L^{\infty}\left([0, T] ; L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)$. For the former, we have uniqueness, but no existence, and for the later, we have existence, but no uniqueness(cf. [15]).

The following proposition is a well known consequence of Lemma 2.1(cf. [4]).
Proposition 3.3. Let $\mathbf{u}$ be a weak solution of (4)-(6) in the sense of Definition 3.1. Then we have for any $\mathbf{v} \in C^{1}\left([0, T] ; \mathbb{H}^{1}\right)$ with $\mathbf{v}(T)=0$

$$
\begin{align*}
& \int_{0}^{T}\left\langle\mathbf{u}(t), \partial_{t} \mathbf{v}(t)\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} t+\left\langle\mathbf{u}_{0}, \mathbf{v}(0)\right\rangle_{\mathbb{H}^{0}} \\
= & \int_{0}^{T}\langle\nabla \mathbf{u}(t), \nabla \mathbf{v}(t)\rangle_{\mathbb{H}^{0}} \mathrm{~d} t+\int_{0}^{T}\langle(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t), \mathbf{v}(t)\rangle_{\mathbb{H}^{0}} \mathrm{~d} t \\
& +\int_{0}^{T}\left\langle g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t), \mathbf{v}(t)\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} t-\int_{0}^{T}\langle\mathbf{f}(t), \mathbf{v}(t)\rangle_{\mathbb{H}^{0}} \mathrm{~d} t . \tag{19}
\end{align*}
$$

Moreover, the following energy equality holds

$$
\begin{align*}
& \|\mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}+2 \int_{0}^{t}\|\nabla \mathbf{u}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s+2 \int_{0}^{t}\left\|\sqrt{g_{N}\left(|\mathbf{u}(s)|^{2}\right)}|\mathbf{u}(s)|\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \\
= & \left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{0}}^{2}+2 \int_{0}^{t}\langle\mathbf{f}(s), \mathbf{u}(s)\rangle_{\mathbb{H}^{0}} \mathrm{~d} s, \quad \forall t \in[0, T] . \tag{20}
\end{align*}
$$

Proof. We have by Sobolev's inequality (12) and Hölder's inequality

$$
\begin{aligned}
& \int_{0}^{T}\left|\langle(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t), \mathbf{v}(t)\rangle_{\mathbb{H}^{0}}\right| \mathrm{d} t \\
\leqslant & \int_{0}^{T}\|\mathbf{u}(t)\|_{L^{4}}\|\nabla \mathbf{u}(t)\|_{L^{2}} \cdot\|\mathbf{v}(t)\|_{L^{4}} \mathrm{~d} t \\
\leqslant & C \cdot \sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{L^{4}} \cdot\left(\int_{0}^{T}\|\mathbf{u}(t)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} t\right)^{1 / 2}\left(\int_{0}^{T}\|\mathbf{v}(t)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} t\right)^{1 / 2}
\end{aligned}
$$

and

$$
\begin{aligned}
& \int_{0}^{T}\left|\left\langle g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t), \mathbf{v}(t)\right\rangle_{\mathbb{H}^{0}}\right| \mathrm{d} t \\
\leqslant & \int_{0}^{T} \int_{\mathbb{R}^{3}}|\mathbf{u}(t, x)|^{3} \cdot|\mathbf{v}(t, x)| \mathrm{d} x \mathrm{~d} t \\
\leqslant & \int_{0}^{T}\|\mathbf{u}(t)\|_{L^{4}}^{3} \cdot\|\mathbf{v}(t)\|_{L^{4}} \mathrm{~d} t \\
\leqslant & C \cdot \sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{L^{4}}^{3} \cdot \int_{0}^{T}\|\mathbf{v}(t)\|_{\mathbb{H}^{1}} \mathrm{~d} t .
\end{aligned}
$$

Hence, the right hand side of (19) is well defined. By using (18), equality (19) and the energy equality (20) follow from an appropriate approximation.

We may now prove the following uniqueness result.
Theorem 3.4. (Uniqueness) Let $\mathbf{u}$ and $\tilde{\mathbf{u}}$ be two generalized solutions of (4)-(6) in the sense of Definition 3.1. Then $\mathbf{u}=\tilde{\mathbf{u}}$.
Proof. Set

$$
\mathbf{w}:=\mathbf{u}-\tilde{\mathbf{u}} .
$$

Then analogously to proving (20) we obtain

$$
\|\mathbf{w}(t)\|_{\mathbb{H}^{0}}^{2}=-2 \int_{0}^{t}\|\nabla \mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s-2 \int_{0}^{t}\langle\mathbf{w}(s),(\mathbf{u}(s) \cdot \nabla) \mathbf{u}(s)-(\tilde{\mathbf{u}}(s) \cdot \nabla) \tilde{\mathbf{u}}(s)\rangle_{\mathbb{H}^{0}} \mathrm{~d} s
$$

$$
\begin{aligned}
& -2 \int_{0}^{t}\left\langle\mathbf{w}(s), g_{N}\left(|\mathbf{u}(s)|^{2}\right) \mathbf{u}(s)-g_{N}\left(|\tilde{\mathbf{u}}(s)|^{2}\right) \tilde{\mathbf{u}}(s)\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} s \\
=: & I_{1}+I_{2}+I_{3} .
\end{aligned}
$$

By (12) and Young's inequality, we have for any $\epsilon>0$

$$
\begin{align*}
& \left\|\mathbf{u}^{*}(s) \cdot \mathbf{u}(s)-\tilde{\mathbf{u}}^{*}(s) \cdot \tilde{\mathbf{u}}(s)\right\|_{\mathbb{H}^{0}}^{2} \\
\leqslant & \||\mathbf{w}(s)|(|\mathbf{u}(s)|+|\tilde{\mathbf{u}}(s)|)\|_{\mathbb{H}^{0}}^{2} \\
\leqslant & 2\|\mathbf{w}(s)\|_{L^{4}}^{2}\left(\|\mathbf{u}(s)\|_{L^{4}}^{2}+\|\tilde{\mathbf{u}}(s)\|_{L^{4}}^{2}\right) \\
\leqslant & 2 C_{1,0,2,2,4}\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{3 / 2}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{1 / 2}\left(\|\mathbf{u}(s)\|_{L^{4}}^{2}+\|\tilde{\mathbf{u}}(s)\|_{L^{4}}^{2}\right) \\
\leqslant & C_{\epsilon} M_{\mathbf{u}, \tilde{\mathbf{u}}}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2}+\epsilon\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2}, \tag{21}
\end{align*}
$$

where

$$
M_{\mathbf{u}, \tilde{\mathbf{u}}}:=\operatorname{ess} \sup _{s \in[0, T]}\left(\|\mathbf{u}(s)\|_{L^{4}}^{8}+\|\tilde{\mathbf{u}}(s)\|_{L^{4}}^{8}\right)<+\infty
$$

Hence, for $\epsilon=1 / 4$

$$
\begin{aligned}
I_{2} & =2 \int_{0}^{t}\left\langle\nabla \mathbf{w}(s),\left(\mathbf{u}^{*}(s) \cdot \mathbf{u}(s)-\tilde{\mathbf{u}}^{*}(s) \cdot \tilde{\mathbf{u}}(s)\right)\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} s \\
& \left.\leqslant \frac{1}{2} \int_{0}^{t}\|\nabla \mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s+2 \int_{0}^{t} \| \mathbf{u}^{*}(s) \cdot \mathbf{u}(s)-\tilde{\mathbf{u}}^{*}(s) \cdot \tilde{\mathbf{u}}(s)\right) \|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \\
& \leqslant \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s+2 C M_{\mathbf{u}, \tilde{\mathbf{u}}} \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s .
\end{aligned}
$$

On the other hand, we also have for any $\epsilon>0$

$$
\begin{aligned}
& \left|\left\langle\mathbf{w}(s), g_{N}\left(|\mathbf{u}(s)|^{2}\right) \mathbf{u}(s)-g_{N}\left(|\tilde{\mathbf{u}}(s)|^{2}\right) \tilde{\mathbf{u}}(s)\right\rangle_{\mathbb{H}^{0}}\right| \\
\leqslant & \int_{\mathbb{R}^{3}}|\mathbf{w}(s, x)|^{2} g_{N}\left(|\mathbf{u}(s, x)|^{2}\right) \mathrm{d} x \\
& +\int_{\mathbb{R}^{3}}|\mathbf{w}(s, x)| \cdot\left|g_{N}\left(|\mathbf{u}(s, x)|^{2}\right)-g_{N}\left(|\tilde{\mathbf{u}}(s, x)|^{2}\right)\right| \cdot|\tilde{\mathbf{u}}(s, x)| \mathrm{d} x \\
\leqslant & 4\||\mathbf{w}(s)|(|\mathbf{u}(s)|+|\tilde{\mathbf{u}}(s)|)\|_{\mathbb{H}^{0}}^{2} \\
\leqslant & C_{\epsilon} M_{\mathbf{u}, \tilde{\mathbf{u}}}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2}+\epsilon\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2},
\end{aligned}
$$

where we have used that $\left|g_{N}^{\prime}\right| \leqslant C$ and (21).
Hence for $\epsilon=1$ we obtain by integrating with respect to $\mathrm{d} s$

$$
I_{3} \leqslant \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s+C M_{\mathbf{u}, \tilde{\mathbf{u}}} \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s
$$

For $I_{1}$, we have

$$
I_{1}=-2 \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s+2 \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s .
$$

Combining all estimates on $I_{1}, I_{2}$ and $I_{3}$, we obtain

$$
\|\mathbf{w}(t)\|_{\mathbb{H}^{0}}^{2} \leqslant C M_{\mathbf{u}, \tilde{\mathbf{u}}} \int_{0}^{t}\|\mathbf{w}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s
$$

So, by Gronwall's inequality

$$
\mathbf{w}(t)=0, \quad \forall t>0,
$$

and the assertion is proved.

Let us now prove the following existence result.
Theorem 3.5. Let $\mathbf{u}_{0} \in \mathbb{H}^{1}$ and $\mathbf{f} \in L_{\text {loc }}^{2}\left([0, \infty) ; \mathbb{H}^{0}\right)$. Then there exists at least one solution $\mathbf{u}$ to (4)-(6) in the sense of Definition 3.1. Moreover,
$\left(1^{\circ}\right) \mathbf{u} \in C\left([0, \infty) ; \mathbb{H}^{1}\right) \cap L_{\mathbf{l o c}}^{2}\left([0, \infty) ; \mathbb{H}^{2}\right), \partial_{t} \mathbf{u} \in L_{\mathbf{l o c}}^{2}\left([0, \infty) ; \mathbb{H}^{0}\right)$, and

$$
\begin{align*}
& \|\mathbf{u}(t)\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{t}\left(\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2}+\||\mathbf{u}(s)| \cdot|\nabla \mathbf{u}(s)|\|_{L^{2}}^{2}\right) \mathrm{d} s \\
\leqslant & C(1+N)(t+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right), \quad t \geqslant 0 \tag{22}
\end{align*}
$$

where $N$ is as in (4)-(6).
$\left(2^{\circ}\right)$

$$
\begin{equation*}
\|\mathbf{u}(t)\|_{\mathbb{H}^{0}} \leqslant\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{0}}+\int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}} \mathrm{~d} s, \quad t \geqslant 0 \tag{23}
\end{equation*}
$$

and

$$
\begin{align*}
& \int_{0}^{t}\left(\|\nabla \mathbf{u}(s)\|_{\mathbb{H}^{0}}^{2}+\left\||\mathbf{u}(s)| \cdot \sqrt{g_{N}\left(|\mathbf{u}(s)|^{2}\right)}\right\|_{\mathbb{H}^{0}}^{2}\right) \mathrm{d} s \\
\leqslant & C\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{0}}^{2}+\left[\int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}} \mathrm{~d} s\right]^{2}\right), \quad t \geqslant 0 \tag{24}
\end{align*}
$$

( $3^{\circ}$ ) There exists a real function $p(t, x)$ with $\nabla p \in L_{\mathbf{l o c}}^{2}\left([0, \infty) ; L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)$ such that for almost all $t \geqslant 0$

$$
\partial_{t} \mathbf{u}(t)=\Delta \mathbf{u}(t)-(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t)+\nabla p(t)-g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)+\mathbf{f}(t)
$$

Proof. We use the standard Galerkin approximation, and only consider the finite time interval $[0, T]$. Let $\left\{\mathbf{e}_{k}, k \in \mathbb{N}\right\} \subset \mathcal{V}$ be a complete orthonormal basis of $\mathbb{H}^{1}$ such that $\operatorname{span}\left\{e_{k}, k \in \mathbb{N}\right\}$ is dense in $\mathbb{H}^{3}$. Fix $n \in \mathbb{N}$. For $\mathbf{y}=\left(y^{1}, \cdots, y^{n}\right) \in \mathbb{R}^{n}$, set

$$
\begin{aligned}
\mathbf{y} \cdot \mathbf{e} & :=\sum_{i=1}^{n} y^{i} \mathbf{e}_{i} \in \mathcal{V} \\
\mathbf{b}_{n}(\mathbf{y}) & :=\left(\llbracket A(\mathbf{y} \cdot \mathbf{e}), \mathbf{e}_{1} \rrbracket, \cdots, \llbracket A(\mathbf{y} \cdot \mathbf{e}), \mathbf{e}_{n} \rrbracket\right) \\
\mathbf{f}_{n}(t) & :=\left(\left\langle\rho_{n} * \mathbf{f}(t), \mathbf{e}_{1}\right\rangle_{\mathbb{H}^{1}}, \cdots,\left\langle\rho_{n} * \mathbf{f}(t), \mathbf{e}_{n}\right\rangle_{\mathbb{H}^{1}}\right),
\end{aligned}
$$

where $\rho_{n}$ is a family of mollifiers and $\rho_{n} * f(t)$ denotes the convolution on $\mathbb{R}^{3}$.
Consider the following ordinary differential equation

$$
\mathrm{d} \mathbf{y}_{n}(t) / \mathrm{d} t=\mathbf{b}_{n}\left(\mathbf{y}_{n}(t)\right)+\mathbf{f}_{n}(t)
$$

subject to the initial condition

$$
\mathbf{y}_{n}(0)=\left(\left\langle\mathbf{u}_{0}, \mathbf{e}_{1}\right\rangle_{\mathbb{H}^{1}}, \cdots,\left\langle\mathbf{u}_{0}, \mathbf{e}_{n}\right\rangle_{\mathbb{H}^{1}}\right) .
$$

By Lemma 2.2, we have for some $C_{n, N}>0$

$$
\left\langle\mathbf{y}, \mathbf{b}_{n}(\mathbf{y})\right\rangle_{\mathbb{R}^{n}} \leqslant C_{n, N}|\mathbf{y}|^{2} .
$$

Moreover, it is easy to see that $\mathbf{y} \mapsto \mathbf{b}_{n}(\mathbf{y})$ is a smooth function. Hence, by the theory of ODE there is a unique $\mathbf{y}_{n}(t)$ satisfying

$$
\mathbf{y}_{n}(t)=\mathbf{y}_{n}(0)+\int_{0}^{t} \mathbf{b}_{n}\left(\mathbf{y}_{n}(s)\right) \mathrm{d} s+\int_{0}^{t} \mathbf{f}_{n}(s) \mathrm{d} s, \quad t \geqslant 0
$$

Set

$$
\begin{aligned}
\mathbf{u}_{n}(t) & :=\mathbf{y}_{n}(t) \cdot \mathbf{e}=\sum_{i=1}^{n} y_{n}^{i}(t) \mathbf{e}_{i} \\
\Pi_{n} A\left(\mathbf{u}_{n}(t)\right) & :=\sum_{i=1}^{n} \llbracket A\left(\mathbf{u}_{n}(t)\right), \mathbf{e}_{i} \rrbracket \mathbf{e}_{i} \\
\Pi_{n} \mathbf{f}(t) & :=\sum_{i=1}^{n}\left\langle\rho_{n} * \mathbf{f}(t), \mathbf{e}_{i}\right\rangle_{\mathbb{H}^{1}} \mathbf{e}_{i} .
\end{aligned}
$$

Then

$$
\begin{equation*}
\partial_{t} \mathbf{u}_{n}(t)=\Pi_{n} A\left(\mathbf{u}_{n}(t)\right)+\Pi_{n} \mathbf{f}(t), \tag{25}
\end{equation*}
$$

and for any $n \geqslant k$

$$
\begin{align*}
\left\langle\mathbf{u}_{n}(t), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}} & =\left\langle\mathbf{u}_{n}(0), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}+\int_{0}^{t}\left\langle\Pi_{n} A\left(\mathbf{u}_{n}(s)\right), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}} \mathrm{~d} s+\int_{0}^{t}\left\langle\Pi_{n} \mathbf{f}(s), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}} \mathrm{~d} s \\
& =\left\langle\mathbf{u}_{0}, \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}+\int_{0}^{t} \llbracket A\left(\mathbf{u}_{n}(s)\right), \mathbf{e}_{k} \rrbracket \mathrm{~d} s+\int_{0}^{t}\left\langle\rho_{n} * \mathbf{f}(s), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}} \mathrm{~d} s . \tag{26}
\end{align*}
$$

We then have by (26) and (16)

$$
\begin{aligned}
\left\|\mathbf{u}_{n}(t)\right\|_{\mathbb{H}^{1}}^{2}= & \left\|\mathbf{u}_{n}(0)\right\|_{\mathbb{H}^{1}}^{2}+2 \int_{0}^{t} \llbracket A\left(\mathbf{u}_{n}(s)\right), \mathbf{u}_{n}(s) \rrbracket \mathrm{d} s+2 \int_{0}^{t}\left\langle\rho_{n} * \mathbf{f}(s), \mathbf{u}_{n}(s)\right\rangle_{\mathbb{H}^{1}} \mathrm{~d} s \\
\leqslant & \left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}-\int_{0}^{t}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s-\int_{0}^{t}\left\|\left|\mathbf{u}_{n}(s)\right| \cdot\left|\nabla \mathbf{u}_{n}(s)\right|\right\|_{L^{2}}^{2} \mathrm{~d} s \\
& +(3+2 N) \int_{0}^{t}\left\|\nabla \mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s+2 \int_{0}^{t}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \\
& +2 \int_{0}^{t}\left\|\rho_{n} * \mathbf{f}(s)\right\|_{\mathbb{H}^{0}}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{2}} \mathrm{~d} s \\
\leqslant & \left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}-\frac{1}{2} \int_{0}^{t}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s-\int_{0}^{t}\left\|\left|\mathbf{u}_{n}(s)\right| \cdot \mid \nabla \mathbf{u}_{n}(s)\right\|_{L^{2}}^{2} \mathrm{~d} s \\
& +C_{N} \int_{0}^{t}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} s+2 \int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s
\end{aligned}
$$

which implies by Gronwall's inequality that for all $n \in \mathbb{N}$

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|\mathbf{u}_{n}(t)\right\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{T}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s \leqslant C_{N, T, \mathbf{f}} . \tag{27}
\end{equation*}
$$

For fixed $k \in \mathbb{N}$, set

$$
G_{n}^{(k)}(t):=\left\langle\mathbf{u}_{n}(t), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}
$$

(27) implies that $G_{n}^{(k)}, n \in \mathbb{N}$, are uniformly bounded. Furthermore, for any $0 \leqslant r<t \leqslant T$, we have from (26) and Lemma 2.2

$$
\begin{aligned}
\left|G_{n}^{(k)}(t)-G_{n}^{(k)}(r)\right| & \leqslant \int_{r}^{t}\left|\llbracket A\left(\mathbf{u}_{n}(s)\right), \mathbf{e}_{k} \rrbracket\right| \mathrm{d} s+\int_{r}^{t}\left|\left\langle\rho_{n} * \mathbf{f}(s), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}\right| \mathrm{d} s \\
& \leqslant C\left\|\mathbf{e}_{k}\right\|_{\mathbb{H}^{3}} \int_{r}^{t}\left(1+\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{1}}^{3}\right) \mathrm{d} s+\left\|\mathbf{e}_{k}\right\|_{\mathbb{H}^{2}} \int_{r}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}} \mathrm{~d} s
\end{aligned}
$$

that $G_{n}^{(k)}, n \in \mathbb{N}$, are also equi-continuous by (27).

Thus, by Ascoli-Arzelà lemma, we may substract a subsequence $n_{l}$ such that $G_{n_{l}}^{(k)}(t)$ uniformly converges to a continuous function $G^{(k)}(t)$. This subsequence may depend on $k$. However, by a diagonalization method, we may find a common subsequence (still denoted by $n$ ) such that for any $k \in \mathbb{N}$

$$
\lim _{n \rightarrow \infty} \sup _{t \in[0, T]}\left|G_{n}^{(k)}(t)-G^{(k)}(t)\right|=0
$$

Thus, by (27) and since closed balls of $\mathbb{H}^{1}$ are weakly compact, there exits a $\mathbf{u} \in$ $L^{\infty}\left([0, T] ; \mathbb{H}^{1}\right)$ such that $t \mapsto \mathbf{u}(t)$ is weakly continuous, that is, continuous from $[0, T]$ to $\mathbb{H}^{1}$ equipped with the weak topology, and for any $\mathbf{v} \in \mathbb{H}^{1}$

$$
\lim _{n \rightarrow \infty} \sup _{t \in[0, T]}\left|\left\langle\mathbf{u}_{n}(t)-\mathbf{u}(t), \mathbf{v}\right\rangle_{\mathbb{H}^{1}}\right|=0
$$

In particular, for any $\tilde{\mathbf{v}} \in \mathbb{H}^{0}$, taking $\mathbf{v}=(I-\Delta)^{-1} \tilde{\mathbf{v}} \in \mathbb{H}^{2}$ we get

$$
\lim _{n \rightarrow \infty} \sup _{t \in[0, T]}\left|\left\langle\mathbf{u}_{n}(t)-\mathbf{u}(t), \tilde{\mathbf{v}}\right\rangle_{\mathbb{H}^{0}}\right|=0 .
$$

By Helmholtz-Weyl orthogonal decomposition(cf. [15]), we further have for any $\mathbf{w} \in$ $L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$ and $T>0$

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \sup _{t \in[0, T]}\left|\left\langle\mathbf{u}_{n}(t)-\mathbf{u}(t), \mathbf{w}\right\rangle_{L^{2}}\right|=0 . \tag{28}
\end{equation*}
$$

Moreover, by (27) and (28), we also have

$$
\int_{0}^{T}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s \leqslant \liminf _{n \rightarrow \infty} \int_{0}^{T}\left\|\mathbf{u}_{n}(s)\right\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s<+\infty
$$

Let us now check that $\mathbf{u}$ constructed above is a solution of (4)-(6).
Let $\mathcal{O} \subset \mathbb{R}^{3}$ be any bounded domain. Using (27) (28) and the following Friedrichs' inequality(see [8, p.176]): For any $\epsilon>0$, there exist $N_{\epsilon} \in \mathbb{N}$ functions $h_{i}^{\epsilon} \in L^{2}(\mathcal{O})$ such that for any $w \in W_{0}^{1,2}(\mathcal{O})$

$$
\begin{equation*}
\int_{\mathcal{O}}|w(x)|^{2} \mathrm{~d} x \leqslant \sum_{i=1}^{N_{\epsilon}}\left(\int_{\mathcal{O}} w(x) h_{i}^{\epsilon}(x) \mathrm{d} x\right)^{2}+\epsilon \int_{\mathcal{O}}|\nabla w(x)|^{2} \mathrm{~d} x \tag{29}
\end{equation*}
$$

we obviously have that for any $\mathcal{O}^{\prime} \subset \overline{\mathcal{O}}^{\prime} \subset \mathcal{O}$

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \sup _{t \in[0, T]} \int_{\mathcal{O}^{\prime}}\left|\mathbf{u}_{n}(t, x)-\mathbf{u}(t, x)\right|^{2} \mathrm{~d} x=0 \tag{30}
\end{equation*}
$$

For any $k \in \mathbb{N}$, let the support of $\mathbf{e}_{k}$ be contained in some bounded domain $\mathcal{O}_{k}$. By Lemma 2.3, (30) and the dominated convergence theorem, we have

$$
\int_{0}^{t} \llbracket A\left(\mathbf{u}_{n}(s)\right), \mathbf{e}_{k} \rrbracket \mathrm{~d} s \rightarrow \int_{0}^{t} \llbracket A(\mathbf{u}(s)), \mathbf{e}_{k} \rrbracket \mathrm{~d} s, \quad \text { as } n \rightarrow \infty .
$$

Now taking the limits $n \rightarrow \infty$ for (26) we obtain that for any $k \in \mathbb{N}$ and $t \geqslant 0$

$$
\left\langle\mathbf{u}(t), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}=\left\langle\mathbf{u}(0), \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{1}}+\int_{0}^{t} \llbracket A(\mathbf{u}(s)), \mathbf{e}_{k} \rrbracket \mathrm{~d} s+\int_{0}^{t}\left\langle\mathbf{f}(s),(I-\Delta) \mathbf{e}_{k}\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} s
$$

By an easy approximation and Lemma 2.2, we further have for any $\mathbf{v} \in \mathbb{H}^{3}$ and $t \geqslant 0$

$$
\langle\mathbf{u}(t), \mathbf{v}\rangle_{\mathbb{H}^{1}}=\langle\mathbf{u}(0), \mathbf{v}\rangle_{\mathbb{H}^{1}}+\int_{0}^{t} \llbracket A(\mathbf{u}(s)), \mathbf{v} \rrbracket \mathrm{d} s+\int_{0}^{t}\langle\mathbf{f}(s),(I-\Delta) \mathbf{v}\rangle_{\mathbb{H}^{0}} \mathrm{~d} s
$$

Since $(I-\Delta)^{-1} \mathbf{v} \in \mathbb{H}^{3}$ for any $\mathbf{v} \in \mathbb{H}^{3}$, from the above equality and (14) we obtain (18).

Let us now prove $\left(1^{o}\right)$ and $\left(2^{o}\right)$. Since $\mathbf{u} \in L^{\infty}\left([0, T] ; \mathbb{H}^{1}\right) \cap L^{2}\left([0, T] ; \mathbb{H}^{2}\right)$ for any $T>0$, by (18) we have for almost all $t \geqslant 0$

$$
\begin{equation*}
\partial_{t} \mathbf{u}(t)=\Delta \mathbf{u}(t)-P((\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t))-P\left(g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)\right)+\mathbf{f}(t) \text { in } \mathbb{H}^{0} \tag{31}
\end{equation*}
$$

and $\partial_{t} \mathbf{u}(t) \in L^{2}\left([0, T] ; \mathbb{H}^{0}\right)$. $\left(3^{o}\right)$ now follows from (18) and [15, Proposition 1.1].
Taking inner products with $\mathbf{u}(t)$ in $\mathbb{H}^{0}$ for both sides of (31), we have by (15)

$$
\begin{aligned}
\frac{\mathrm{d}\|\mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}}{\mathrm{~d} t}= & 2\langle A(\mathbf{u}(t)), \mathbf{u}(t)\rangle_{\mathbb{H}^{0}}+2\langle\mathbf{f}(t), \mathbf{u}(t)\rangle_{\mathbb{H}^{0}} \\
\leqslant & -2\|\nabla \mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}-2\left\||\mathbf{u}(t)| \cdot \sqrt{g_{N}\left(|\mathbf{u}(t)|^{2}\right)}\right\|_{\mathbb{H}^{0}}^{2} \\
& +2\|\mathbf{f}(t)\|_{\mathbb{H}^{0}} \cdot\|\mathbf{u}(t)\|_{\mathbb{H}^{0}}
\end{aligned}
$$

and thus

$$
\frac{\mathrm{d}\|\mathbf{u}(t)\|_{\mathbb{H}^{0}}}{\mathrm{~d} t} \leqslant\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}
$$

Both together implies $\left(2^{\circ}\right)$.
Since $\mathbb{H}^{2} \subset \mathbb{H}^{1} \subset \mathbb{H}^{0}$ forms an evolutional triple, we also have by $[15$, p. 260, Lemma 1.2] and (31)

$$
\begin{equation*}
\|\mathbf{u}(t)\|_{\mathbb{H}^{1}}^{2}=\|\mathbf{u}(0)\|_{\mathbb{H}^{1}}^{2}+2 \int_{0}^{t} \llbracket A(\mathbf{u}(s)), \mathbf{u}(s) \rrbracket \mathrm{d} s+2 \int_{0}^{t}\langle\mathbf{f}(s), \mathbf{u}(s)\rangle_{\mathbb{H}^{1}} \mathrm{~d} s \tag{32}
\end{equation*}
$$

Since the right hand side of (44) is continuous in $t$ and we have already know that $t \mapsto \mathbf{u}(t) \in \mathbb{H}^{1}$ is weakly continuous, it follows that this map is even (strongly) continuous in $\mathbb{H}^{1}$. Furthermore, the right hand side of (44) is by (16) and (24) bounded by

$$
\begin{aligned}
& \left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}-\int_{0}^{t}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s-\int_{0}^{t}\||\mathbf{u}(s)| \cdot|\nabla \mathbf{u}(s)|\|_{L^{2}}^{2} \mathrm{~d} s \\
& +(3+2 N) \int_{0}^{t}\|\nabla \mathbf{u}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s+2 \int_{0}^{t}\|\mathbf{u}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \\
& +2 \int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}} \mathrm{~d} s \\
\leqslant & -\frac{1}{2} \int_{0}^{t}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s-\int_{0}^{t}\||\mathbf{u}(s)| \cdot \mid \nabla \mathbf{u}(s)\|_{L^{2}}^{2} \mathrm{~d} s \\
& +C(1+N)(t+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right)
\end{aligned}
$$

which gives (22). The proof is thus finished.

## 4. Existence of Suitable Weak Solution

In this section we shall use the result of previous section to give a new construction the "suitable weak solution" to (1)-(3) that was introduced in [13] and [2].

Theorem 4.1. Given $T>0$, let $\mathbf{u}_{0} \in \mathbb{H}^{0}$ and $\mathbf{f} \in L^{2}\left([0, T] ; \mathbb{H}^{0}\right)$. There exists a Leray-
Hopf weak solution $(\mathbf{u}, p)$ to (1)-(3) satisfying the following generalized energy inequality: If $\phi \in C_{0}^{\infty}\left((0, T) \times \mathbb{R}^{3}\right)$ is nonnegative, then

$$
\begin{aligned}
& 2 \int_{0}^{T} \int_{\mathbb{R}^{3}}|\nabla \mathbf{u}(t, x)|^{2} \phi(t, x) \mathrm{d} x \mathrm{~d} s \\
\leqslant & \int_{0}^{T} \int_{\mathbb{R}^{3}}\left[|\mathbf{u}(t, x)|^{2}\left(\partial_{t} \phi(t, x)+\Delta \phi(t, x)\right)+2(\mathbf{u}(t, x) \cdot \mathbf{f}(t, x)) \phi(t, x)\right.
\end{aligned}
$$

$$
\begin{equation*}
\left.+\left(|\mathbf{u}(t, x)|^{2}+2 p(t, x)\right)\langle\mathbf{u}(t, x), \nabla \phi(t, x)\rangle_{\mathbb{R}^{3}}\right] \mathrm{d} x \mathrm{~d} t \tag{33}
\end{equation*}
$$

Proof. Choose $\mathbf{u}_{0}^{N} \in \mathbb{H}^{1}$ being such that

$$
\lim _{N \rightarrow \infty}\left\|\mathbf{u}_{0}^{N}-\mathbf{u}_{0}\right\|_{\mathbb{H}^{0}}=0
$$

Let $\mathbf{u}_{N}$ be the unique solution of (4)-(6) constructed in Theorem 3.5 with initial value $\mathbf{u}_{0}^{N}$. By $\left(2^{o}\right)$ of Theorem 3.5, we have

$$
\begin{equation*}
\sup _{t \in[0, T]}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{2}+\int_{0}^{T}\left(\left\|\mathbf{u}_{N}(s)\right\|_{\mathbb{H}^{1}}^{2}+\left\|\sqrt{g_{N}\left(\left|\mathbf{u}_{N}(s)\right|^{2}\right)} \cdot\left|\mathbf{u}_{N}(s)\right|\right\|_{L^{2}}^{2}\right) \mathrm{d} s \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}} \tag{34}
\end{equation*}
$$

Let $q \in[2, \infty)$ and $r \in(2,6]$

$$
\frac{3}{r}+\frac{2}{q}=\frac{3}{2}
$$

By (12) and (34) we have

$$
\begin{equation*}
\int_{0}^{T}\left\|\mathbf{u}_{N}(t)\right\|_{L^{r}}^{q} \mathrm{~d} t \leqslant C_{1,0,2,2, r}^{q} \int_{0}^{T}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{1}}^{2} \cdot\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{0}}^{q-2} \mathrm{~d} t \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}, r, q} \tag{35}
\end{equation*}
$$

As in the proof of Theorem 3.5, one may find a subsequence still denoted by $N$ and $\mathbf{u} \in L^{\infty}\left([0, T] ; \mathbb{H}^{0}\right) \cap L^{2}\left([0, T] ; \mathbb{H}^{1}\right)$ such that for any $\mathbf{w} \in L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)$

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \sup _{t \in[0, T]}\left|\left\langle\mathbf{u}_{N}(t)-\mathbf{u}(t), \mathbf{w}\right\rangle_{L^{2}}\right|=0 \tag{36}
\end{equation*}
$$

We shall now prove that in fact for any bounded domain $\Omega \subset \mathbb{R}^{3}$

$$
\begin{equation*}
\lim _{N \rightarrow \infty} \int_{0}^{T} \int_{\Omega}\left|\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t=0 \tag{37}
\end{equation*}
$$

Now, let $\Omega \subset \bar{\Omega} \subset \Omega^{\prime}$ and $\rho \geqslant 0$ be a smooth cutoff function with $\rho(x)=1$ on $\Omega$ and $\rho(x)=0$ on $\mathbb{R}^{3}-\Omega^{\prime}$. Then by Friedrichs' inequality (29) we have

$$
\begin{aligned}
& \int_{0}^{T} \int_{\Omega}\left|\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t \\
\leqslant & \int_{0}^{T} \int_{\Omega^{\prime}}\left|\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right|^{2} \cdot \rho^{2}(x) \mathrm{d} x \mathrm{~d} t \\
\leqslant & \sum_{i=1}^{N_{\epsilon}} \int_{0}^{T}\left(\int_{\Omega^{\prime}}\left(\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right) \rho(x) h_{i}(x) \mathrm{d} x\right)^{2} \mathrm{~d} t \\
& +\epsilon \int_{0}^{T} \int_{\Omega^{\prime}}\left|\nabla\left(\left(\mathbf{u}_{N}(t)-\mathbf{u}(t)\right) \rho\right)(x)\right|^{2} \mathrm{~d} x \mathrm{~d} t \\
=: & I_{1}(k, \epsilon)+I_{2}(k, \epsilon) .
\end{aligned}
$$

The second term is bounded by

$$
I_{2}(k, \epsilon) \leqslant \epsilon \cdot C_{\rho} \int_{0}^{T}\left(\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{1}}^{2}+\|\mathbf{u}(t)\|_{\mathbb{H}^{1}}^{2}\right) \mathrm{d} t \leqslant C_{\rho, T, \mathbf{u}_{0}, \mathbf{f}} \cdot \epsilon
$$

By (36) we have for the first term

$$
\lim _{N \rightarrow \infty} I_{1}(k, \epsilon) \leqslant T \sum_{i=1}^{N_{\epsilon}} \lim _{N \rightarrow \infty} \sup _{t \in[0, T]}\left|\int_{\mathbb{R}^{3}}\left(\mathbf{u}_{N}(t, x)-\mathbf{u}(t, x)\right) \rho(x) h_{i}^{\epsilon}(x) 1_{\Omega^{\prime}}(x) \mathrm{d} x\right|^{2}=0 .
$$

Hence (37) follows by the arbitrariness of $\epsilon$.

As in the proof of Theorem 3.5, in order to verify that $\mathbf{u}$ is a Leray-Hopf weak solution, it suffices to prove that for any $\mathbf{v} \in \mathcal{V}$

$$
\lim _{N \rightarrow \infty} \int_{0}^{t}\left\langle g_{N}\left(\left|\mathbf{u}_{N}(s)\right|^{2}\right) \mathbf{u}_{N}(s), \mathbf{v}\right\rangle_{\mathbb{H}^{0}} \mathrm{~d} s=0
$$

This is true, because by (35), this limit is dominated by

$$
\begin{aligned}
& \|\mathbf{v}\|_{L^{\infty}} \cdot \limsup _{N \rightarrow \infty} \int_{0}^{t} \int_{\mathbb{R}^{3}}\left|\mathbf{u}_{N}(s, x)\right|^{3} \cdot 1_{\left\{\left|\mathbf{u}_{N}(s, x)\right|^{2} \geqslant N\right\}} \mathrm{d} x \mathrm{~d} s \\
\leqslant & \|\mathbf{v}\|_{L^{\infty}} \cdot \limsup _{N \rightarrow \infty}\left(\int_{0}^{t}\left\|\mathbf{u}_{N}(s)\right\|_{L^{10 / 3}}^{10 / 3} \mathrm{~d} s\right)^{9 / 10} \cdot\left(\int_{0}^{t} \int_{\mathbb{R}^{3}} 1_{\left\{\left|\mathbf{u}_{N}(s, x)\right|^{2} \geqslant N\right\}} \mathrm{d} x \mathrm{~d} s\right)^{1 / 10} \\
\leqslant & C_{\mathbf{v}, T, \mathbf{u}_{0}, \mathbf{f}} \cdot \limsup _{N \rightarrow \infty}\left(\frac{1}{N} \int_{0}^{t}\left\|\mathbf{u}_{N}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right)^{1 / 10}=0
\end{aligned}
$$

Let us now check the generalized energy inequality. Note that by [15, Proposition 1.1], for some $p_{N} \in L^{2}\left([0, T] ; L_{\text {loc }}^{2}\left(\mathbb{R}^{3}, \mathbb{R}^{3}\right)\right)$ with $\nabla p_{N} \in L^{2}\left([0, T] ; L^{2}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)$

$$
\begin{equation*}
\partial_{t} \mathbf{u}_{N}=\Delta \mathbf{u}_{N}(t)-\left(\mathbf{u}_{N}(t) \cdot \nabla\right) \mathbf{u}_{N}(t)+\nabla p_{N}(t)-g_{N}\left(\left|\mathbf{u}_{N}(t)\right|^{2}\right) \mathbf{u}_{N}(t)+\mathbf{f}(t) . \tag{38}
\end{equation*}
$$

Taking inner product with $2 \mathbf{u}_{N} \phi$ and integrating by parts yield

$$
\begin{align*}
& 2 \int_{0}^{T} \int_{\mathbb{R}^{3}}\left|\nabla \mathbf{u}_{N}\right|^{2} \phi \mathrm{~d} x \mathrm{~d} s+2 \int_{0}^{T} \int_{\mathbb{R}^{3}} g_{N}\left(\left|\mathbf{u}_{N}\right|^{2}\right)\left|\mathbf{u}_{N}\right|^{2} \phi \mathrm{~d} x \mathrm{~d} s \\
= & \int_{0}^{T} \int_{\mathbb{R}^{3}}\left[\left|\mathbf{u}_{N}\right|^{2}\left(\partial_{t} \phi+\Delta \phi\right)+2\left(\mathbf{u}_{N} \cdot \mathbf{f}\right) \phi+\left(\left|\mathbf{u}_{N}\right|^{2}-2 p_{N}\right)\left\langle\mathbf{u}_{N}, \nabla \phi\right\rangle_{\mathbb{R}^{3}}\right] \mathrm{d} x \mathrm{~d} t . \tag{39}
\end{align*}
$$

Since $\mathbf{u} \mapsto \int_{0}^{T} \int_{\mathbb{R}^{3}}|\nabla \mathbf{u}|^{2} \phi \mathrm{~d} x \mathrm{~d} s$ is lower-semi continuous in $L^{2}\left([0, T], \mathbb{H}^{0}\right)$, the limit of the left hand side of (39) is greater than the left hand side of (33). Since $\phi$ has compact support, by (35)(with $q=r=10 / 3$ ) and (37), each term of the right hand side of (39) converges to the corresponding term of the right hand side of (33) except for the term including $p_{N}$. For this term, one takes the divergence (in the sense of Schwartz distributions) for (38) and then gets

$$
\begin{equation*}
\Delta p_{N}=\operatorname{div}\left(\left(\mathbf{u}_{N}(t) \cdot \nabla\right) \mathbf{u}_{N}(t)+g_{N}\left(\left|\mathbf{u}_{N}(t)\right|^{2}\right) \mathbf{u}_{N}(t)\right) . \tag{40}
\end{equation*}
$$

Noting that

$$
g_{N}^{9 / 8}(r) \cdot r^{9 / 16} \leqslant g_{N}(r) \cdot r
$$

we have by (34)

$$
\begin{align*}
& \int_{0}^{T} \int_{\mathbb{R}^{3}}\left|g_{N}\left(\left|\mathbf{u}_{N}(t, x)\right|^{2}\right) \cdot \mathbf{u}_{N}(t, x)\right|^{9 / 8} \mathrm{~d} x \mathrm{~d} t \\
\leqslant & \int_{0}^{T} \int_{\mathbb{R}^{3}} g_{N}\left(\left|\mathbf{u}_{N}(t, x)\right|^{2}\right) \cdot\left|\mathbf{u}_{N}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}} . \tag{41}
\end{align*}
$$

Moreover, by Hölder's inequality and (35)

$$
\begin{align*}
& \int_{0}^{T} \int_{\mathbb{R}^{3}}\left|\left(\mathbf{u}_{N}(t) \cdot \nabla\right) \mathbf{u}_{N}(t)\right|^{9 / 8} \mathrm{~d} x \mathrm{~d} t \\
\leqslant & \left(\int_{0}^{T}\left\|\mathbf{u}_{N}(t)\right\|_{L^{18 / 7}}^{18 / 7} \mathrm{~d} t\right)^{7 / 16} \cdot\left(\int_{0}^{T}\left\|\mathbf{u}_{N}(t)\right\|_{\mathbb{H}^{1}}^{2} \mathrm{~d} t\right)^{9 / 16} \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}} \tag{42}
\end{align*}
$$

By (12), we know that

$$
\begin{equation*}
\int_{0}^{T}\left\|p_{N}(t)\right\|_{L^{9 / 5}}^{9 / 8} \mathrm{~d} t \leqslant C_{1,0,9 / 8,9 / 8,9 / 5}^{9 / 8} \int_{0}^{T}\left\|p_{N}(t)\right\|_{1,9 / 8}^{9 / 8} \mathrm{~d} t \tag{43}
\end{equation*}
$$

Since the operator $\nabla(-\Delta)^{1 / 2}$ is bounded in $L^{p}\left(\mathbb{R}^{3}\right)$ for all $p>1$ (cf. [14]), it follows from (40)-(42) that the right hand side of (43) is uniformly bounded in $N$.

Therefore, there exists a subsequence(still denoted by $N$ ) and

$$
p \in L^{9 / 8}\left([0, T] ; L^{9 / 5}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right)
$$

such that

$$
\begin{equation*}
p_{N} \rightarrow p \text { weakly in } L^{9 / 8}\left([0, T] ; L^{9 / 5}\left(\mathbb{R}^{3} ; \mathbb{R}^{3}\right)\right) \tag{44}
\end{equation*}
$$

On the other hand, by (35) with $q=12, r=9 / 4$ again we have

$$
\int_{0}^{T}\left\|\mathbf{u}_{N}(t)\right\|_{L^{9 / 4}}^{12} \mathrm{~d} t \leqslant C_{T, \mathbf{u}_{0}, \mathbf{f}}
$$

So, by (37) and (44)

$$
\begin{aligned}
& \lim _{N \rightarrow \infty}\left|\int_{0}^{T} \int_{\mathbb{R}^{3}}\left\langle p_{N} \mathbf{u}_{N}-p \mathbf{u}, \nabla \phi\right\rangle_{\mathbb{R}^{3}}(t, x) \mathrm{d} x \mathrm{~d} t\right| \\
\leqslant & \lim _{N \rightarrow \infty}\left|\int_{0}^{T} \int_{\mathbb{R}^{3}}\left(p_{N}-p\right)(t, x) \cdot\langle\mathbf{u}, \nabla \phi\rangle_{\mathbb{R}^{3}}(t, x) \mathrm{d} x \mathrm{~d} t\right| \\
& +\lim _{N \rightarrow \infty}\left|\int_{0}^{T} \int_{\mathbb{R}^{3}} p_{N}(t, x) \cdot\left\langle\mathbf{u}_{N}-\mathbf{u}, \nabla \phi\right\rangle_{\mathbb{R}^{3}}(t, x) \mathrm{d} x \mathrm{~d} t\right| \\
\leqslant & \lim _{N \rightarrow \infty}\left(\int_{0}^{T}\left\|p_{N}(t)\right\|_{9 / 5}^{9 / 8} \mathrm{~d} t\right)^{8 / 9}\left(\int_{0}^{T}\left\|\left|\mathbf{u}_{N}(t)-\mathbf{u}(t)\right| \cdot|\nabla \phi(t)|\right\|_{9 / 4}^{9} \mathrm{~d} t\right)^{1 / 9}=0 .
\end{aligned}
$$

The proof is complete.

## 5. Proof of Theorem 1.1

For $T>0$, we write $S_{T}:=[0, T] \times \mathbb{R}^{3}$, and

$$
\|\mathbf{u}\|_{L^{q}\left(S_{T}\right)}:= \begin{cases}\left(\int_{S_{T}}|\mathbf{u}(s, x)|^{q} \mathrm{~d} x \mathrm{~d} s\right)^{1 / q}, \quad & q \in[1, \infty), \\ \sup _{(s, x) \in S_{T}}|\mathbf{u}(s, x)|, \quad q=\infty\end{cases}
$$

Let $T_{t}$ be the Gaussian heat semigroup on $\mathbb{R}^{3}$, i.e., for $h \in L^{1}\left(\mathbb{R}^{3}\right)$

$$
T_{t} h(x):=\frac{1}{(4 \pi t)^{3 / 2}} \int_{\mathbb{R}^{3}} e^{-|x-y|^{2} /(4 t)} h(y) \mathrm{d} y .
$$

Define

$$
B(\mathbf{u}, \mathbf{u})(t, x):=\sum_{i=1}^{3} \int_{0}^{t} \partial_{i} T_{t-s}\left[u^{i}(s) \mathbf{u}(s)-\sum_{j=1}^{3} \mathbf{R} R_{j} u^{j}(s) u^{i}(s)\right](x) \mathrm{d} s
$$

Then, the unique solution $\mathbf{u}$ constructed in Theorem 3.5 for fixed $N$ satisfies the following integral equation(cf. [1, Theorem 4.4]):

$$
\mathbf{u}(t, x)=\mathbf{f}_{N}(t, x)-B(\mathbf{u}, \mathbf{u})(t, x),
$$

where $\mathbf{f}_{N}$ is defined by

$$
\mathbf{f}_{N}(t, x):=T_{t} \mathbf{u}_{0}(x)-\int_{0}^{t} T_{t-s} P\left(g_{N}\left(|\mathbf{u}(s)|^{2}\right) \mathbf{u}(s)-\mathbf{f}(s)\right)(x) \mathrm{d} s
$$

Let us recall the following regularity result due to Fabes-Jones-Riviere [1, Theorem 3.4].
Theorem 5.1. Assume $\mathbf{u} \in L^{q}\left(S_{T}\right)$ for some $q \geqslant 5$. Let $k \in \mathbb{N}$ be such that $k+1<q$. If

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{f}_{N} \in L^{q /(|\alpha|+2 j+1)}\left(S_{T}\right) \quad \text { whenever }|\alpha|+2 j \leqslant k
$$

then also

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in L^{q /(|\alpha|+2 j+1)}\left(S_{T}\right) \quad \text { whenever }|\alpha|+2 j \leqslant k
$$

Here $D^{\alpha}$ denotes the usual derivative operator and $\alpha=\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$ denotes a multi index, $|\alpha|=\alpha_{1}+\alpha_{2}+\alpha_{3}$.

We are now in a position to prove our main Theorem 1.1.
Proof of Theorem 1.1:
Let us now use induction to prove that for $k \in \mathbb{N}$

$$
\mathbf{u} \in L^{10 \cdot(5 / 3)^{k-1}}\left(S_{T}\right), \quad D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in L^{2 \cdot(5 / 3)^{k}}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant 2, \quad\left(\mathscr{P}_{k}\right)
$$

First of all, by the Sobolev inequality (12) and (22), we have

$$
\begin{aligned}
\|\mathbf{u}\|_{L^{10}\left(S_{T}\right)}^{10} & \leqslant C_{2,0,2,6,10}^{10} \int_{0}^{T}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2} \cdot\|\mathbf{u}(s)\|_{L^{6}}^{8} \mathrm{~d} s \\
& \leqslant C \sup _{s \in[0, T]}\|\mathbf{u}(s)\|_{\mathbb{H}^{1}}^{8} \int_{0}^{T}\|\mathbf{u}(s)\|_{\mathbb{H}^{2}}^{2} \mathrm{~d} s<+\infty
\end{aligned}
$$

Thus

$$
g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u} \in L^{10 / 3}\left(S_{T}\right)
$$

Since $\mathbf{u}_{0}$ and $\mathbf{f}$ are smooth, by the $L^{p}$-theory of singular integrals of parabolic type (cf. [9]), we know

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{f}_{N} \in L^{10 / 3}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant 2
$$

By Theorem 5.1, we get

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in L^{10 / 3}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant 2
$$

Hence ( $\mathscr{P}_{1}$ ) holds.
Now suppose that $\left(\mathscr{P}_{k}\right)$ holds. Using the Sobolev inequality (12) and (22) again, we have

$$
\begin{aligned}
\|\mathbf{u}\|_{L^{10 \cdot(5 / 3)^{k}}\left(S_{T}\right)}^{10 \cdot(5 / 3)^{k}} & \leqslant C_{2,0,2 \cdot(5 / 3)^{k}, 6,10 \cdot(5 / 3)^{k}}^{10 \cdot(5 / 3)^{k}} \int_{0}^{T}\|\mathbf{u}(s)\|_{2,2 \cdot(5 / 3)^{k}}^{2 \cdot(5 / 3)^{k}} \cdot\|\mathbf{u}(s)\|_{L^{6}}^{8 \cdot(5 / 3)^{k}} \mathrm{~d} s \\
& \leqslant C \sup _{s \in[0, T]}\|\mathbf{u}(s)\|_{\mathbb{H}^{1}}^{8 \cdot(5 / 3)^{k}} \int_{0}^{T}\|\mathbf{u}(s)\|_{2,2 \cdot(5 / 3)^{k}}^{2 \cdot(5 / 3) k} \mathrm{~d} s<+\infty
\end{aligned}
$$

Thus,

$$
g_{N}\left(|\mathbf{u}|^{2}\right) \mathbf{u} \in L^{2 \cdot(5 / 3)^{k+1}}\left(S_{T}\right)
$$

and

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{f}_{N} \in L^{2 \cdot(5 / 3)^{k+1}}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant 2
$$

By Theorem 5.1 again, we get

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in L^{2 \cdot(5 / 3)^{k+1}} \underset{18}{\left(S_{T}\right)} \quad \text { for }|\alpha|+2 j \leqslant 2
$$

i.e., $\left(\mathscr{P}_{k+1}\right)$ holds.

Therefore,

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in \cap_{q>1} L^{q}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant 2
$$

Using Theorem 5.1, by the induction method, one finds that for any $m \in \mathbb{N}$

$$
D_{x}^{\alpha} D_{t}^{j} \mathbf{u} \in \cap_{q>1} L^{q}\left(S_{T}\right) \quad \text { for }|\alpha|+2 j \leqslant m .
$$

The smoothness of $\mathbf{u}$ now follows from the Sobolev embedding theorem (cf. [9]). In particular, for any $k, m \in \mathbb{N}$ and $T>0$

$$
\partial_{t}^{k} \mathbf{u} \in L^{2}\left([0, T] ; \mathbb{H}^{m}\right)
$$

and for all $t \geqslant 0$ and $m \in \mathbb{N}$

$$
\begin{equation*}
\partial_{t} \mathbf{u}(t)=\Delta \mathbf{u}(t)-P((\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t))-P\left(g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)\right)+\mathbf{f}(t) \text { in } \mathbb{H}^{m} \tag{45}
\end{equation*}
$$

We now prove the estimate (10). First of all, taking inner products with $\partial_{t} \mathbf{u}(t)$ in $\mathbb{H}^{0}$ for both sides of (45), we have by (14), (25) and Young's inequality

$$
\begin{aligned}
\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}= & \left\langle\Delta \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}-\left\langle(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
& -\left\langle g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}+\left\langle\mathbf{f}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
\leqslant & -\frac{1}{2} \cdot \frac{\mathrm{~d}\|\nabla \mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}}{\mathrm{~d} t}+\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}\|(\mathbf{u}(t) \cdot \nabla) \mathbf{u}(t)\|_{L^{2}} \\
& -\frac{1}{2} \cdot \frac{\mathrm{~d}\left\|\tilde{g}_{N}\left(|\mathbf{u}(t)|^{2}\right)\right\|_{L^{1}}}{\mathrm{~d} t}+\frac{1}{4}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}+\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2} \\
\leqslant & \left.-\frac{1}{2} \cdot \frac{\mathrm{~d}\|\nabla \mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}}{\mathrm{~d} t}+\frac{1}{2}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}+\| \| \mathbf{u}(t)|\cdot| \nabla \mathbf{u}(t) \right\rvert\, \|_{L^{2}}^{2} \\
& -\frac{1}{2} \cdot \frac{\mathrm{~d}\left\|\tilde{g}_{N}\left(|\mathbf{u}(t)|^{2}\right)\right\|_{L^{1}}}{\mathrm{~d} t}+\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2},
\end{aligned}
$$

where

$$
0 \leqslant \tilde{g}_{N}(r):=\int_{0}^{r} g_{N}(s) \mathrm{d} s \leqslant \frac{r^{2}}{2}
$$

Integrating both sides from 0 to $T$ with respect to $t$ and using (22) yields that

$$
\begin{align*}
\frac{1}{2} \int_{0}^{T}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} t \leqslant & -\frac{1}{2}\left(\|\nabla \mathbf{u}(T)\|_{\mathbb{H}^{0}}^{2}-\|\nabla \mathbf{u}(0)\|_{\mathbb{H}^{0}}^{2}\right) \\
& +\int_{0}^{T}\left(\| \| \mathbf{u}(t)|\cdot| \nabla \mathbf{u}(t)\left\|_{L^{2}}^{2}+\right\| \mathbf{f}(t) \|_{\mathbb{H}^{0}}^{2}\right) \mathrm{d} t \\
& -\frac{1}{2}\left(\left\|\tilde{g}_{N}\left(|\mathbf{u}(T)|^{2}\right)\right\|_{L^{1}}-\left\|\tilde{g}_{N}\left(|\mathbf{u}(0)|^{2}\right)\right\|_{L^{1}}\right) \\
\leqslant & \frac{1}{2}\|\mathbf{u}(0)\|_{\mathbb{H}^{1}}^{2}+\frac{1}{4}\|\mathbf{u}(0)\|_{L^{4}}^{4} \\
& +C(1+N)(1+T)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) \\
\leqslant & C(1+N)(1+T)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{4}+\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) . \tag{46}
\end{align*}
$$

On the other hand, differentiating (45) with respect to $t$ and then taking the inner products with $\partial_{t} \mathbf{u}(t)$ in $\mathbb{H}^{0}$ gives that

$$
\frac{1}{2} \frac{\mathrm{~d}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}}{\mathrm{~d} t}=\left\langle\Delta \partial_{t} \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}-\left\langle\left(\partial_{t} \mathbf{u}(t) \cdot \nabla\right) \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}
$$

$$
\begin{aligned}
& -\left\langle\partial_{t}\left(g_{N}\left(|\mathbf{u}(t)|^{2}\right) \mathbf{u}(t)\right), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}+\left\langle\partial_{t} \mathbf{f}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
= & -\left\|\nabla \partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}-\left\langle\nabla \partial_{t} \mathbf{u}(t), \mathbf{u}^{*}(t) \cdot \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
& -\left\langle g_{N}\left(|\mathbf{u}(t)|^{2}\right) \partial_{t} \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}}+\left\langle\partial_{t} \mathbf{f}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
& \left.-\left.\left\langle g_{N}^{\prime}\left(|\mathbf{u}(t)|^{2}\right) \partial_{t}\right| \mathbf{u}(t)\right|^{2} \mathbf{u}(t), \partial_{t} \mathbf{u}(t)\right\rangle_{\mathbb{H}^{0}} \\
\leqslant & -\frac{1}{2}\left\|\nabla \partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2}\left\||\mathbf{u}(t)| \cdot\left|\partial_{t} \mathbf{u}(t)\right|\right\|_{\mathbb{H}^{0}}^{2} \\
& -\left\|\sqrt{g_{N}\left(|\mathbf{u}(t)|^{2}\right)} \cdot\left|\partial_{t} \mathbf{u}(t)\right|\right\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2}\left\|\partial_{t} \mathbf{f}(t)\right\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2} \\
& -\frac{1}{2}\left\|\left.\sqrt{g_{N}^{\prime}\left(|\mathbf{u}(t)|^{2}\right)} \cdot\left|\partial_{t}\right| \mathbf{u}(t)\right|^{2}\right\|_{L^{2}}^{2} \\
\leqslant & -\frac{1}{2}\left\|\nabla \partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}-\frac{1}{2}\left\||\mathbf{u}(t)| \cdot\left|\partial_{t} \mathbf{u}(t)\right|\right\|_{\mathbb{H}^{0}}^{2} \\
& +(N+1)\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2}\left\|\partial_{t} \mathbf{f}(t)\right\|_{\mathbb{H}^{0}}^{2},
\end{aligned}
$$

where we have used that $g_{N}\left(|\mathbf{u}|^{2}\right) \geqslant|\mathbf{u}|^{2}-(N+1 / 2)$.
Integrating both sides and using (46) yield that for any $t \geqslant 0$

$$
\begin{align*}
\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2} \leqslant & \left\|\partial_{t} \mathbf{u}(0)\right\|_{\mathbb{H}^{0}}^{2}+2(N+1) \int_{0}^{t}\left\|\partial_{s} \mathbf{u}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s+\int_{0}^{t}\left\|\partial_{s} \mathbf{f}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \\
\leqslant & C\left(1+N^{2}\right)(t+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{4}+\int_{0}^{t}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) \\
& +C\left(\|\mathbf{u}(0)\|_{\mathbb{H}^{2}}^{6}+\|\mathbf{f}(0)\|_{\mathbb{H}^{0}}^{2}\right)+\int_{0}^{t}\left\|\partial_{s} \mathbf{f}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s \tag{47}
\end{align*}
$$

where we have used that $\left\|\partial_{t} \mathbf{u}(0)\right\|_{\mathbb{H}^{0}}^{2} \leqslant C\left(\|\mathbf{u}(0)\|_{\mathbb{H}^{2}}^{6}+\|\mathbf{f}(0)\|_{\mathbb{H}^{0}}^{2}\right)$ by (45).
Lastly, taking inner products with $\mathbf{u}(t)$ in $\mathbb{H}^{1}$ for both sides of (45), by (16) we get

$$
\begin{aligned}
\left\langle\partial_{t} \mathbf{u}(t), \mathbf{u}(t)\right\rangle_{\mathbb{H}^{1}}= & \llbracket A(\mathbf{u}(t)), \mathbf{u}(t) \rrbracket+\langle\mathbf{f}(t), \mathbf{u}(t)\rangle_{\mathbb{H}^{1}} \\
\leqslant & -\frac{1}{4}\|\mathbf{u}(t)\|_{\mathbb{H}^{2}}^{2}-\frac{1}{2}\||\mathbf{u}(t)| \cdot|\nabla \mathbf{u}(t)|\|_{L^{2}}^{2} \\
& +\left(\frac{3}{2}+N\right)\|\nabla \mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}+\|\mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}+\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2} .
\end{aligned}
$$

This implies that

$$
\begin{aligned}
\sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{\mathbb{H}^{2}}^{2} \leqslant & 4\left(\frac{3}{2}+N\right) \sup _{t \in[0, T]}\|\nabla \mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2}+4 \sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{\mathbb{H}^{0}}^{2} \\
& +4 \sup _{t \in[0, T]}\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2}+4 \sup _{t \in[0, T]}\left|\left\langle\partial_{t} \mathbf{u}(t), \mathbf{u}(t)\right\rangle_{\mathbb{H}^{1}}\right| \\
\leqslant & C\left(1+N^{2}\right)(T+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{4}+\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right) \\
& +4 \sup _{t \in[0, T]}\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2}+8 \sup _{t \in[0, T]}\left\|\partial_{t} \mathbf{u}(t)\right\|_{\mathbb{H}^{0}}^{2}+\frac{1}{2} \sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{\mathbb{H}^{2}}^{2},
\end{aligned}
$$

where we used (22) in the second step.
So, by (47)

$$
\sup _{t \in[0, T]}\|\mathbf{u}(t)\|_{\mathbb{H}^{2}}^{2} \leqslant C\left(1+N^{2}\right)(T+1)\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{2}+\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{1}}^{4}+\int_{0}^{T}\|\mathbf{f}(s)\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right)
$$

$$
+C\left(\left\|\mathbf{u}_{0}\right\|_{\mathbb{H}^{2}}^{6}+\sup _{t \in[0, T]}\|\mathbf{f}(t)\|_{\mathbb{H}^{0}}^{2}+\int_{0}^{T}\left\|\partial_{s} \mathbf{f}(s)\right\|_{\mathbb{H}^{0}}^{2} \mathrm{~d} s\right)
$$

which leads to the desired estimate (10). Since (8) follows from (34) (24), and (9) follows from (22), (2 $2^{o}$ is proved.

For $\left(3^{\circ}\right)$, suppose that the conclusion is false. Then, there exist a bounded domain $\Omega$, $\epsilon>0$ and a subsequence $N_{k}$ such that

$$
\int_{0}^{T} \int_{\Omega}\left|\mathbf{u}_{N_{k}}(t, x)-\mathbf{u}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t \geqslant \epsilon
$$

Starting from this subsequence and using Theorem 4.1, one may find a suitable solution $\tilde{\mathbf{u}}$ and another subsequence $N_{k}^{\prime}$ of $N_{k}$ such that(see (37))

$$
\lim _{k \rightarrow \infty} \int_{0}^{T} \int_{\Omega}\left|\mathbf{u}_{N_{k}^{\prime}}(t, x)-\tilde{\mathbf{u}}(t, x)\right|^{2} \mathrm{~d} x \mathrm{~d} t=0 .
$$

Under the assumptions of $\left(3^{\circ}\right)$, by well known results (cf. [4, Theorem 4.2 and Theorem 7.2]) we know that

$$
\tilde{\mathbf{u}}=\mathbf{u}, \text { a.e. }
$$

This contradiction proves $\left(3^{\circ}\right)$.

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