

# Existence results for Fokker–Planck equations in Hilbert spaces

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## Abstract

We consider a stochastic differential equation in a Hilbert space with time-dependent coefficients for which no general existence result

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is known. We prove, under suitable assumptions, existence of a measure valued solution, for the corresponding Fokker–Planck equation.

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## 1 Introduction

Let us consider a stochastic differential equation on a separable Hilbert space  $H$  (with norm  $|\cdot|$  and inner product  $\langle \cdot, \cdot \rangle$ ) of the form

$$\begin{cases} dX(t) = [AX(t) + F(t, X(t))]dt + \sqrt{C}dW(t), \\ X(0) = x, \end{cases} \quad (1.1)$$

where  $A : D(A) \subset H \rightarrow H$  is a self-adjoint operator,  $C : H \rightarrow H$  is linear self-adjoint and nonnegative,  $F(t, \cdot) : Y \subset H \rightarrow H$  (where  $Y$  is a subspace of  $H$ ),  $t \in [0, T]$ , form a family of non linear mappings and  $W(t)$  is a cylindrical Wiener process in  $H$  defined on a stochastic basis  $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ .

The Kolmogorov operator  $L_0$  corresponding to (1.1) reads as follows

$$\begin{aligned} L_0 u(t, x) = D_t u(t, x) + \frac{1}{2} \operatorname{Tr} [C D_x^2 u(t, x)] \\ + \langle x, A D_x u(t, x) \rangle + \langle F(t, x), D_x u(t, x) \rangle. \end{aligned} \quad (1.2)$$

The operator  $L_0$  is defined on the space  $D(L_0) := \mathcal{E}_A([0, T] \times H)$ , the linear span of all real parts of functions  $u_{\phi, h}$  of the form

$$u_{\phi, h}(t, x) = \phi(t) e^{i \langle x, h(t) \rangle}, \quad t \in [0, T], \quad x \in H,$$

where  $\phi \in C^1([0, T])$ ,  $h \in C^1([0, T]; D(A))$  and  $\phi(T) = 0$ .

We are interested in the following Fokker–Planck equation

$$\begin{cases} \frac{d}{dt} \int_H u(t, x) \mu_t(dx) = \int_H L_0 u(t, x) \mu_t(dx) \text{ for } dt\text{-a.e. } t \in (0, T], \quad \forall u \in D(L_0) \\ \lim_{t \rightarrow 0} \int_H \varphi(x) \mu_t(dx) = \int_H \varphi(x) \zeta(dx), \quad \forall \varphi \in \mathcal{E}_A(H), \end{cases} \quad (1.3)$$

where  $\frac{d}{dt}$  denotes the weak derivative on  $[0, T]$ . Here  $\mathcal{E}_A(H)$  is the linear span of all real parts of functions of the form

$$\varphi(x) = e^{i\langle x, h \rangle}, \quad x \in H, \quad h \in D(A),$$

and, as in (1.4) and (1.5) (see also (2.4) below), we always implicitly assume that

$$\int_{[0, T] \times H} (|x| + |F(t, x)|) \mu_t(dx) dt < \infty,$$

so that  $L_0 u \in L^1([0, T] \times H, \mu)$  for all  $u \in D(L_0)$ , where  $\mu(dt, dx) = \mu_t(dx) dt$ .

Furthermore,  $\zeta \in \mathcal{P}(H)$  is given and  $\mu_t(dx)$ ,  $t \in [0, T]$ , is a kernel of probability measure (shortly probability kernel) <sup>(1)</sup> from  $(H, \mathcal{B}(H))$  to  $([0, T], \mathcal{B}([0, T]))$ , in particular the mapping  $t \mapsto \int_H u(t, x) \mu_t(dx)$  is measurable for any bounded measurable function  $u$ . By  $\mathcal{P}(H)$  we mean the set of all Borel probability measures on  $H$ .

We can also write equation (1.3) in the integral form

$$\int_H u(t, x) \mu_t(dx) = \int_H u(0, x) \zeta(dx) + \int_0^t ds \int_H L_0 u(s, x) \mu_s(dx),$$

for  $dt$ -a.e.  $t \in [0, T]$ ,  $\forall u \in D(L_0)$ , (1.4)

or also, setting  $t = T$  as,

$$\int_{[0, T] \times H} L_0 u(s, x) \mu(ds, dx) = - \int_H u(0, x) \zeta(dx), \quad \forall u \in D(L_0). \quad (1.5)$$

Let us set our assumptions. Concerning the linear operators  $A$  and  $C$  we shall assume that

**Hypothesis 1.1** (i)  $A$  is self-adjoint.

(ii)  $C$  is bounded, symmetric, nonnegative and such that  $C^{-1} \in L(H)$ .

(iii) There exists  $\delta \in (0, 1/2)$  such that  $(-A)^{-2\delta}$  is of trace class.

Let us notice that from (iii) it follows that the embedding  $D(A) \subset H$  is compact.

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<sup>(1)</sup>We recall that a probability kernel is a family  $\mu_t, t \in [0, T]$ , of probability measures on  $(H, \mathcal{B}(H))$  such that for all  $A \in \mathcal{B}(H)$  the map  $t \mapsto \mu_t(A)$  is  $\mathcal{B}([0, T])$ -measurable.

**Remark 1.2** (i) Since we have used this also in our previous papers, let us explain in detail in what precise sense (1.3),(1.4) and (1.5) are really equivalent. So, let  $\mu_t(dx)$ ,  $t \in [0, T]$ , be a probability kernel as above and let  $\mu(dt, dx) = \mu_t(dx)dt$  be the corresponding measure on  $([0, T] \times H, \mathcal{B}([0, T] \times H))$ . Then by definition  $\mu$  solves (1.3) if the first equation in (1.3) holds and after a possible change of the map  $t \mapsto \mu_t(dx)$  on a set of  $dt$ -measure zero also the second equation in (1.3) holds. In this case, obviously,  $\mu(dt, dx) = \mu_t(dx)dt$  solves (1.4) and (1.5), and such a  $\mu$  obviously solves (1.4) if and only if it satisfies (1.5). Much more subtle is the fact that if such a  $\mu$  solves (1.4) (equivalently (1.5)), it also solves the second equation in (1.3) in the above sense. The reason is that the above  $dt$  modification of  $t \mapsto \mu_t(dx)$  cannot be obtained from (1.4) by just defining it so that  $\int_H \varphi d\mu_t$  is equal to the right hand side of (1.4) for  $\varphi \in \mathcal{E}_A(H)$  (since then the second equation in (1.3) trivially holds), because the  $dt$ -zero set would firstly depend on  $\varphi$  (and there are uncountably many of them) and secondly the right hand side of (1.4) does not per se define a positive measure acting on  $\varphi$ . So, a more involved argument is required.

To this end we fix  $\mu$  as above solving (1.4). Then clearly the first equation in (1.3) holds. Let us prove that the second holds for a  $dt$ -modification of  $t \mapsto \mu_t(dx)$ . By Hypothesis 1.1(iii), there exists an eigenbasis  $\{e_k : k \in \mathbb{N}\}$  of  $H$  for  $A$ . Define

$$\mathcal{F}C_b^\infty(\{e_k\}) = \{g(\langle e_1, \cdot \rangle, \dots, \langle e_N, \cdot \rangle) : N \in \mathbb{N}, g \in C_b^\infty(\mathbb{R}^N)\}$$

and

$$\mathcal{F}C_0^\infty(\{e_k\}) = \text{linear span } \{g(\langle e_1, \cdot \rangle, \dots, \langle e_N, \cdot \rangle) : N \in \mathbb{N}, g \in C_0^\infty(\mathbb{R}^N)\},$$

where  $C_b^\infty(\mathbb{R}^N)$ ,  $C_0^\infty(\mathbb{R}^N)$  denote the set of all bounded smooth real valued functions on  $\mathbb{R}^N$  with all partial derivatives bounded, respectively of compact support.

**Claim** *There exist  $\varphi_n \in \mathcal{F}C_0^\infty(\{e_k\})$ ,  $n \in \mathbb{N}$ , such that  $\mu$  satisfies (1.4) with  $\varphi_n$  replacing  $u \in D(L_0)$  for every  $n \in \mathbb{N}$ , and such that if  $\mu$  satisfies (1.4) with  $\varphi_n$  replacing  $u \in D(L_0)$  for a fixed  $t \in [0, T]$  for all  $n \in \mathbb{N}$  then  $\mu$  satisfies (1.4) for this  $t$  with  $\varphi$  replacing  $u \in D(L_0)$  for all  $\varphi \in \mathcal{E}_A(H)$ .*

**Proof.** Let  $\varphi = g(\langle e_1, \cdot \rangle, \dots, \langle e_N, \cdot \rangle) \in \mathcal{F}C_0^\infty(\{e_k\})$ . Writing its base function  $g \in C_0^\infty(\mathbb{R}^N)$  as the Fourier transform of a Schwartz test function and

discretizing the Fourier integral, one sees by taking the limit in (1.4) that  $\mu$  satisfies (1.4) with  $\varphi$  replacing  $u \in D(L_0)$ . But  $C_0^\infty(\mathbb{R}^N)$  is separable with respect to the norm

$$\|g\|_{\infty,2} := \|g\|_\infty + \|Dg\|_\infty + \|D^2g\|_\infty, \quad g \in C_0^\infty(\mathbb{R}^N).$$

Hence we can find  $\{\varphi_k : k \in \mathbb{N}\} \in \mathcal{F}C_0^\infty(\{e_k\})$  such that if  $\mu$  satisfies (1.4) for some  $t \in [0, T]$  with  $\varphi_k$  replacing  $u \in D(L_0)$  for all  $k \in \mathbb{N}$ , then it does so for this  $t$  and all  $\varphi \in \mathcal{F}C_0^\infty(\{e_k\})$  replacing  $u \in D(L_0)$ , and by an easy localization argument it does so also for all  $\varphi \in \mathcal{F}C_b^\infty(\{e_k\})$ . A further easy approximation then proves the Claim.  $\square$

Now we can easily define the required modification of  $t \mapsto \mu_t(dx)$ . Let  $M := \{t \in [0, T] : (1.4) \text{ holds for } t \text{ and } \varphi_k \text{ replacing } u \in D(L_0) \text{ for all } k \in \mathbb{N}\}$ , where  $\varphi_k, k \in \mathbb{N}$ , are as in the Claim. Define

$$\tilde{\mu}_t(dx) = \begin{cases} \mu_t(dx) & \text{if } t \in M \\ \zeta & \text{if } t \in [0, T] \setminus M. \end{cases}$$

Then by the Claim (1.4) holds with  $\tilde{\mu}_t$  replacing  $\mu_t$  for all  $\varphi \in \mathcal{E}_A(H)$  replacing  $u \in D(L_0)$  and all  $t \in M$ . Hence the second equation in (1.3) holds for the  $dt$ -modification  $\tilde{\mu}_t(dx)$ ,  $t \in [0, T]$ , since it is equal to  $\zeta$  on  $[0, T] \setminus M$ .

(ii) We note that applying (1.4) to a countable subset of functions  $\phi \in C^1([0, T])$  replacing  $u \in D(L_0)$  with  $\phi(T) = 0$ , which is dense with respect to  $\|\cdot\|_\infty$ , it follows that  $\mu_t(H) = 1$  for  $dt$ -a.e.  $t \in [0, T]$ . Hence by e.g. setting  $\mu_t = \zeta$  for those  $t$  for which this does not hold, we see that the requirement that for a solution  $\mu = \mu_t(dx)dt$  of (1.4) the  $\mu_t(dx)$  are all probability measures automatically holds after a  $dt$ -modification of the map  $t \mapsto \mu_t(dx)$ .

It is well known that, under Hypothesis 1.1(iii) the stochastic convolution

$$W_A(t) = \int_0^t e^{(t-s)A} \sqrt{C} dW(s), \quad t \geq 0,$$

is a well defined mean square continuous process in  $H$  with values in  $D((-A)^\delta)$  and that

$$\sup_{t \in [0, T]} \mathbb{E}|(-A)^\delta W_A(t)|^2 \leq \|C\| \operatorname{Tr} [(-A)^{-2\delta}] := c_\delta. \quad (1.6)$$

Concerning the nonlinear operators  $F(t, \cdot)$ ,  $t \in [0, T]$ , we shall assume that

**Hypothesis 1.3** (i) *There exists a measurable mapping  $a : Y \rightarrow \mathbb{R}$  and  $c > 0$  such that*

$$\langle F(t, y + z), y \rangle \leq a(z)|y| + c|y|^2, \quad \forall y, z \in Y, t \in [0, T]. \quad (1.7)$$

(ii) *There exists  $\kappa > 0$  such that setting  $a := \infty$  on  $H \setminus Y$  we have*

$$\mathbb{E} [a(W_A(t))^2 + |W_A(t)|^2] \leq \kappa \quad \forall t \in [0, T]. \quad (1.8)$$

(iii) *For each  $\alpha > 0$  there exists a continuous mapping  $F_\alpha : [0, T] \times H \rightarrow H$ , such that for all  $t \in [0, T]$ ,  $x \in H$ ,*

$$\lim_{\alpha \rightarrow 0} F_\alpha(t, x) = F(t, x), \quad (1.9)$$

$$|F_\alpha(t, x)| \leq |F(t, x)|, \quad (1.10)$$

$$|F(t, x) - F_\alpha(t, x)| \leq \alpha |F(t, x)|^2. \quad (1.11)$$

**Example 1.4** Let  $H = L^2(0, 1)$ ,  $Ax = D^2x$  for all  $x \in H^2(0, 1)$  such that  $x(0) = x(1) = 0$ ,  $C = I$ . Moreover, let  $p$  be a polynomial of odd degree  $d > 1$  and such that

$$p'(\xi) \leq \beta, \quad \forall \xi \in \mathbb{R},$$

where  $\beta \in \mathbb{R}$ . Finally, let  $h : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  be bounded and continuous. Then set

$$F(t, x)(\xi) = p(x(\xi)) + h(t, x(\xi)), \quad x \in L^{2d}(0, 1), \xi \in [0, 1],$$

and  $Y = L^{2d}(0, 1)$ . It is easy to see that Hypotheses 1.1 and 1.3 are fulfilled with

$$a(z) = |p(z)| + \sup_{(t,s) \in \mathbb{R} \times \mathbb{R}} |h(t, s)|, \quad \forall z \in Y$$

and  $c = \beta$  (cf. Section 3 for details).

**Remark 1.5** Under Hypotheses 1.1 and 1.3 we do not know whether equation (1.1) has a solution or not. Notice that (1.7) is a weaker condition than quasi-monotonicity of  $F(t, \cdot)$ .

In a series of papers [1], [2], [3] and [4] we considered parabolic equations for measures on  $\mathbb{R}^d$ . In [5] and [6] (see also [9] for the case when  $F$  is independent of  $t$ ) we were concerned with similar problems in infinite dimensions. Here we present a different existence result.

## 2 Existence

It is convenient to introduce a family of approximating stochastic equations

$$\begin{cases} dX_\alpha(t) = [AX_\alpha(t) + F_\alpha(t, X_\alpha(t))]dt + \sqrt{C}dW(t), \\ X_\alpha(0) = x. \end{cases} \quad (2.1)$$

For each  $\alpha \in (0, 1]$ ,  $F_\alpha : [0, T] \times H$  is well defined and continuous by Hypothesis 1.3(iii).

Since  $C^{-1} \in L(H)$ , by Girsanov's theorem it follows that equation (2.1) has a unique weak solution which we denote by  $X_\alpha(\cdot, x)$ . Let us introduce the transition evolution operator

$$P_{0,t}^\alpha \varphi(x) = \mathbb{E}[\varphi(X_\alpha(t, x))], \quad t > 0, \varphi \in B_b(H). \quad (2.2)$$

The Kolmogorov operator  $L_\alpha$  corresponding to (2.1) is for  $u \in D(L_0)$  given by

$$\begin{aligned} L_\alpha u(t, x) = D_t u(t, x) + \frac{1}{2} \text{Tr} [CD_x^2 u(t, x)] \\ + \langle x, A^* D_x u(t, x) \rangle + \langle F_\alpha(t, x), D_x u(t, x) \rangle. \end{aligned} \quad (2.3)$$

and the Fokker–Planck equation looks like

$$\begin{aligned} \int_H u(t, x) \mu_t^\alpha(dx) = \int_H u(0, x) \zeta(dx) + \int_0^t ds \int_H L_\alpha u(s, x) \mu_s^\alpha(dx), \\ \text{for all } t \in [0, T], \forall u \in D(L_0), \end{aligned} \quad (2.4)$$

or

$$\int_0^T ds \int_{[0,T] \times H} L_\alpha u(s, x) \mu^\alpha(dt, dx) = - \int_H u(0, x) \zeta(dx), \quad \forall u \in D(L_0), \quad (2.5)$$

where  $\mu^\alpha(dt, dx) = \mu_t^\alpha(dx)dt$ .

We need a further assumption.

**Hypothesis 2.1** *There exist  $K > 0$  and a lower semicontinuous function  $\tilde{F} : [0, T] \times H \rightarrow [0, \infty]$  such that  $|F| + |x| \leq \tilde{F}$  on  $[0, T] \times H$ , where  $|F| := \infty$  on  $[0, T] \times (H \setminus Y)$ , and*

$$\mathbb{E}|\tilde{F}(t, X_\alpha(t, x))|^2 \leq K(1 + |\tilde{F}(t, x)|^2), \quad \forall x \in Y, \alpha \in (0, 1], t \in [0, T]. \quad (2.6)$$

Define

$$c_1(t) := \int_0^t \int_H |\tilde{F}(s, x)|^2 ds \zeta(dx), \quad t \in [0, T]. \quad (2.7)$$

Arguing as in [4], [6] one can show that if  $\zeta \in \mathcal{P}(H)$  is such that

$$c_1(T) < +\infty,$$

then equation (2.5) has a solution  $\mu_t^\alpha$  which is determined by the identity

$$\int_H \varphi(x) \mu_t^\alpha(dx) = \int_H P_{0,t}^\alpha \varphi(x) \zeta(dx), \quad \forall \varphi \in \mathcal{E}_A(H). \quad (2.8)$$

**Lemma 2.2** *Assume that Hypothesis 2.1 is fulfilled. Then we have*

$$\int_0^t \int_H |\tilde{F}(s, x)|^2 \mu^\alpha(ds, dx) \leq K(t + c_1(t)), \quad \forall \alpha \in (0, 1], t \in [0, T]. \quad (2.9)$$

**Proof.** Taking into account (2.8) and (2.6) we have for all  $\alpha \in (0, 1]$ ,  $t \in [0, T]$ ,

$$\begin{aligned} \int_0^t \int_H |\tilde{F}(s, x)|^2 \mu^\alpha(ds, dx) &= \int_0^t \int_H P_{0,t}^\alpha(|\tilde{F}(s, \cdot)|^2)(x) \zeta(dx) ds \\ &= \int_0^t \int_H \mathbb{E} |\tilde{F}(s, X_\alpha(s, x))|^2 \zeta(dx) ds \\ &\leq \int_{[0, T] \times H} K(1 + |\tilde{F}(s, x)|^2) \zeta(dx) ds \leq K(t + c_1(t)), \end{aligned}$$

so that (2.9) follows.  $\square$

We note that indeed  $L_\alpha u \in L^1([0, T] \times H, \mu^\alpha)$  for all  $u \in D(L_0)$  by Lemma 2.2. Furthermore, by (2.8) the map  $t \mapsto \int_H u(t, x) \mu_t^\alpha(dx)$  is continuous on  $[0, T]$  for all  $u \in D(L_0)$ . Hence since the right hand side of (2.4) is so, too, we have (2.4) for all  $t \in [0, T]$  in this case.

Our aim is to pass to the limit as  $\alpha \rightarrow 0$  in (2.5), proving existence for the Fokker–Planck equation (1.5). This will be done in the following two steps showing that

**Step 1**  $\{\mu^\alpha\}_{\alpha>0}$  is tight.



**Step 2** If  $\mu$  is a cluster point of  $\{\mu^\alpha\}_{\alpha>0}$  there exists  $\alpha_k \downarrow 0$  such that

$$\lim_{k \rightarrow \infty} \int_{[0,T] \times H} L_{\alpha_k} u d\mu^{\alpha_k} = \int_{[0,T] \times H} L_0 u d\mu, \quad \forall u \in \mathcal{E}_A([0, T] \times H), \quad (2.10)$$

and  $\mu(dt, dx) = \mu_t(dx)dt$ .

We note that Step 2 and Remark 1.2(i) imply that  $\mu$  satisfies (1.4), hence by Remark 1.2(ii) after a possible modification each  $\mu_t$  is a probability measure.

Let us first prove tightness of  $\{\mu^\alpha\}_{\alpha>0}$ .

**Proposition 2.3** *Assume that Hypotheses 1.1 and 1.3 are fulfilled. Let  $\zeta \in \mathcal{P}(H)$  such that  $\int_H |x|^2 d\zeta < \infty$ . Then  $(\mu^\alpha)_{\alpha \in (0,1]}$  is tight.*

**Proof.** Set  $Y_\alpha(t) = X_\alpha(t) - W_A(t)$ . Then (in the mild sense)

$$\frac{d}{dt} Y_\alpha(t) = AY_\alpha(t) + F_\alpha(t, X_\alpha(t)), \quad t \geq 0.$$

Multiplying both sides by  $Y_\alpha(t)$ , yields

$$\frac{1}{2} \frac{d}{dt} |Y_\alpha(t)|^2 + |(-A)^{1/2} Y_\alpha(t)|^2 = \langle F_\alpha(t, Y_\alpha(t) + W_A(t)), Y_\alpha(t) \rangle.$$

By (1.10) and (1.7) we obtain

$$\frac{1}{2} \frac{d}{dt} |Y_\alpha(t)|^2 + |(-A)^{1/2} Y_\alpha(t)|^2 \leq a(W_A(t)) |Y_\alpha(t)| + c|Y_\alpha(t)|^2$$

which yields

$$\frac{d}{dt} |Y_\alpha(t)|^2 + 2|(-A)^{1/2} Y_\alpha(t)|^2 \leq (1+c)|Y_\alpha(t)|^2 + |a(W_A(t))|^2. \quad (2.11)$$

It follows that

$$|Y_\alpha(t)|^2 \leq e^{(1+c)t} |x|^2 + \int_0^t e^{(1+c)(t-s)} |a(W_A(s))|^2 ds$$

from which, taking expectation and recalling (1.8),

$$\mathbb{E}|Y_\alpha(t)|^2 \leq e^{(1+c)T} (|x|^2 + \kappa). \quad (2.12)$$

Consequently,

$$\begin{aligned}\mathbb{E}|X_\alpha(t, x)|^2 &\leq 2e^{(1+c)T}(|x|^2 + \kappa) + 2\mathbb{E}|W_A(t)|^2 \\ &\leq 2e^{(1+c)T}(|x|^2 + \kappa) + 2\kappa =: \kappa_1(|x|^2 + 1).\end{aligned}\quad (2.13)$$

This is equivalent to

$$P_{0,t}^\alpha(|x|^2) \leq \kappa_1(|x|^2 + 1).$$

By (2.8) it follows that

$$\int_H |x|^2 \mu_t^\alpha(dx) = \int_H P_{0,t}^\alpha(|x|^2) \zeta(dx) \leq \kappa_1 \int_H |x|^2 \zeta(dx) + \kappa_1. \quad (2.14)$$

Moreover, by (2.11) we get

$$2 \int_0^T |(-A)^{1/2} Y_\alpha(t)|^2 dt \leq |x|^2 + (1+c) \int_0^T |Y_\alpha(t)|^2 dt + \int_0^T |a(W_A(t))|^2 dt,$$

which implies

$$\begin{aligned}&\int_0^T |(-A)^\delta Y_\alpha(t)|^2 dt \\ &\leq \|(-A)^{-1/2+\delta}\| \left( |x|^2 + (1+c) \int_0^T |Y_\alpha(t)|^2 dt + \int_0^T |a(W_A(t))|^2 dt \right)\end{aligned}$$

and then, taking expectation by (1.6) we obtain

$$\begin{aligned}&\int_0^T \mathbb{E}|(-A)^\delta X_\alpha(t, x)|^2 dt \\ &\leq 2\|(-A)^{-1/2+\delta}\| \left( |x|^2 + (1+c) \int_0^T \mathbb{E}|Y_\alpha(t)|^2 dt + \int_0^T \mathbb{E}|a(W_A(t))|^2 dt \right) + 2c_\delta T.\end{aligned}$$

Now (1.8) and (2.12) imply

$$\begin{aligned}&\int_0^T \mathbb{E}|(-A)^\delta X_\alpha(t, x)|^2 dt \\ &\leq 2\|(-A)^{-1/2+\delta}\| \left( |x|^2 + (1+c) \int_0^T (e^{(1+c)T}(|x|^2 + \kappa)) dt + T\kappa \right) + 2c_\delta T \\ &=: \kappa_2(1 + |x|^2).\end{aligned}$$

Consequently,

$$\int_0^T P_{0,t}^\alpha(|(-A)^\delta x|^2) dt \leq \kappa_2(1 + |x|^2).$$

Again by(2.8) follows that

$$\begin{aligned} \int_{[0,T] \times H} |(-A)^\delta x|^2 \mu^\alpha(dt, dx) &= \int_{[0,T] \times H} P_{0,t}^\alpha(|(-A)^\delta x|^2) dt \zeta(dx) \\ &\leq \kappa_2 \left( \int_H |x|^2 \zeta(dx) + 1 \right). \end{aligned}$$

Since  $(-A)^{-\delta}$  is compact, the tightness of  $(\mu_\alpha)_{\alpha \in (0,1]}$  follows by a standard argument.  $\square$

We are now ready to prove

**Theorem 2.4** *Assume that Hypotheses 1.1, 1.3 and 2.1 hold and that*

$$c_1(T) = \int_0^T dt \int_H (|x|^2 + |F(t, x)|^2) \zeta(dx) < \infty.$$

*Let  $\mu$  be a cluster point of  $(\mu^\alpha)_{\alpha \in (0,1]}$ . Then  $\mu$  is a solution of the Fokker-Planck equation (1.5).*

**Proof.** Let  $\alpha_k \downarrow 0$  such that  $(\mu^{\alpha_k})$  weakly converges to  $\mu$ . Since  $\tilde{F}$  is lower semicontinuous it follows by (2.9) that

$$\int_{[0,T] \times H} |\tilde{F}(t, x)|^2 \mu(dt, dx) \leq K(T + c_1(T)),$$

in particular,  $\mu([0, T] \times Y) = 1$ , because  $\tilde{F} = \infty$  on  $H \setminus Y$ .

Since

$$\int_0^T ds \int_H L_{\alpha_k} u(s, x) \mu_s^{\alpha_k}(dx) = - \int_H u(0, x) \zeta(dx), \quad \forall u \in D(L_0),$$

it is enough to show that

$$\begin{aligned} \lim_{k \rightarrow \infty} \int_{[0,T] \times H} \langle F_{\alpha_k}(s, x), D_x u(s, x) \rangle \mu^{\alpha_k}(ds, dx) \\ = \int_{[0,T] \times H} \langle F(s, x), D_x u(s, x) \rangle \mu(ds, dx), \quad \forall u \in D(L_0). \end{aligned} \quad (2.15)$$

and that

$$\begin{aligned} \lim_{k \rightarrow \infty} \int_{[0,T] \times H} \langle x, D_x u(s, x) \rangle \mu^{\alpha_k}(ds, dx) \\ = \int_{[0,T] \times H} \langle x, D_x u(s, x) \rangle \mu(ds, dx), \quad \forall u \in D(L_0). \end{aligned} \quad (2.16)$$

We have in fact

$$\begin{aligned} & \left| \int_{[0,T] \times H} \langle F_{\alpha_k}(t, x), D_x u(s, x) \rangle \mu^{\alpha_k}(ds, dx) \right. \\ & \left. - \int_{[0,T] \times H} \langle F(s, x), D_x u(s, x) \rangle \mu(ds, dx) \right| \\ & \leq \left| \int_{[0,T] \times H} \langle (F_{\alpha_k}(s, x) - F(s, x)), D_x u(s, x) \rangle \mu^{\alpha_k}(ds, dx) \right| \\ & + \left| \int_{[0,T] \times H} \langle F(s, x), D_x u(s, x) \rangle \mu^{\alpha_k}(ds, dx) \right. \\ & \left. - \int_{[0,T] \times H} \langle F(s, x), D_x u(s, x) \rangle \mu(ds, dx) \right| \\ & =: I_1 + I_2. \end{aligned} \quad (2.17)$$

In view of (1.11), (2.9) we have

$$\begin{aligned} I_1 & \leq \sup |D_x u| \int_{[0,T] \times H} |F_{\alpha_k}(s, x) - F(s, x)| \mu^{\alpha_k}(ds, dx) \\ & \leq \alpha_k \sup |D_x u| \int_{[0,T] \times H} |\tilde{F}(s, x)|^2 \mu^{\alpha_k}(ds, dx) \leq K(T + c_1(T)) \alpha_k \sup |D_x u|. \end{aligned} \quad (2.18)$$

Moreover, for any  $\epsilon > 0$ ,

$$\begin{aligned}
I_2 &\leq \left| \int_{[0,T] \times H} \langle F_\epsilon(t, x), D_x u(t, x) \rangle \mu^{\alpha_k}(dt, dx) \right. \\
&\quad \left. - \int_{[0,T] \times H} \langle F_\epsilon(t, x), D_x u(t, x) \rangle \mu(dt, dx) \right| \\
&\quad + \epsilon \sup |D_x u| \left( \int_{[0,T] \times H} |F(t, x)|^2 d\mu^{\alpha_k}(dt, dx) \right. \\
&\quad \left. + \int_{[0,T] \times H} |F(t, x)|^2 d\mu(dt, dx) \right) \tag{2.19} \\
&\leq \left| \int_{[0,T] \times H} \langle F_\epsilon(t, x), D_x u(t, x) \rangle d\mu^{\alpha_k}(dt, dx) \right. \\
&\quad \left. - \int_{[0,T] \times H} \langle F_\epsilon(t, x), D_x u(t, x) \rangle d\mu(dt, dx) \right| \\
&\quad + 2K(T + c_1(T))\epsilon \sup |D_x u|.
\end{aligned}$$

Now the equation (2.15) follows letting  $k \rightarrow \infty$  and then  $\epsilon \rightarrow 0$ . (2.16) is proved analogously.

It remains to prove that  $\mu(dt, dx) = \mu_t(dx)dt$ . But the projection of  $\mu$  onto  $([0, T], \mathcal{B}([0, T]))$  is Lebesgue measure since it is the weak limit of the corresponding projections of  $\mu^{\alpha_k}$  which are all Lebesgue measure. Hence  $\mu$  disintegrates as

$$\mu(dt, dx) = \mu_t(dx)dt$$

where  $\mu_t(dx)$ ,  $t \in [0, T]$ , are kernels.  $\square$

### 3 An application

Let  $H = L^2(0, 1)$ ,  $A : D(A) \subset H \rightarrow H$  be defined by

$$Ax(\xi) = \partial_\xi^2 x(\xi), \quad D(A) = H^2(0, 1) \cap H_0^1(0, 1), \quad \xi \in [0, 1].$$

Let

$$F(t, x)(\xi) = p(x(\xi)) + h(t, x(\xi)), \quad x \in L^{2m}(0, 1), \quad \xi \in [0, 1],$$

where  $p$  is a polynomial of odd degree  $m > 1$  such that  $p' \leq c$  and  $h : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is bounded and continuous. Under these assumptions we do not know whether the stochastic equation (1.1) has a solution. Finally, let  $C, C^{-1} \in L(H)$ ,  $C$  symmetric nonnegative

We set  $Y = L^{2m}(0, 1)$  and prove that Hypotheses 1.1, 1.3 and 2.1 are fulfilled.

First, Hypothesis 1.1 holds with  $\omega = \pi^2$  because  $A^{-1}$  is of trace class. Let us check Hypothesis 1.3. Since the polynomial  $p$  is decreasing we have for each  $y, z \in Y$

$$\begin{aligned} p(y+z)y + h(t, y+z)y &= (p(y+z) - p(z))y + p(z)y + h(t, y+z)y \\ &\leq c|y|^2 + |p(z)||y| + \|h\|_\infty|y| \leq c|y|^2 + c_1(1 + |z|^m)|y|, \end{aligned} \quad (3.1)$$

where  $c_1 > 0$ . Consequently

$$\langle F(t, y+z), y \rangle \leq c|y|^2 + c_1(1 + |z|_{L^{2m}(0,1)}^m) |y|. \quad (3.2)$$

So, (1.7) holds. Moreover, (1.8) is proved in [8]. For  $\alpha \in (0, 1]$  define

$$F_\alpha(t, x)(\xi) = \frac{F(t, x)(\xi)}{1 + \alpha|F(t, x)(\xi)|}, \quad \xi \in (0, 1).$$

Hence also Hypothesis 1.3 holds since (iii) is obviously true for  $F_\alpha$ . Finally, Hypothesis 2.1 follows from the proposition below for  $\tilde{F}(t, x) := C(1 + |x|_{L^{2m}(0,1)}^m)$  and  $C$  a large enough constant.

**Proposition 3.1** *Let  $\alpha > 0$ . Then for any  $m \in \mathbb{N}$  there exists  $c_m > 0$  such that*

$$\mathbb{E} \left( |X_\alpha(t, x)|_{L^{2m}(0,1)}^{2m} \right) \leq c_m(1 + |x|_{L^{2m}(0,1)}^{2m}), \quad t \in [0, T].$$

**Proof.** Setting  $Y_\alpha(t) = X_\alpha(t) - W_A(t)$ , (2.1) reduces to

$$\begin{cases} Y'_\alpha(t) = AY_\alpha(t) - F_\alpha(Y_\alpha(t) + W_A(t)), & t \in [0, T], \\ Y_\alpha(0) = x. \end{cases}$$

Now, multiplying both sides of the first equation by  $(Y_\alpha(t))^{2m-1}$  yields (after integration by parts)

$$\begin{aligned} &\frac{1}{2m} \frac{d}{dt} \int_0^1 |Y_\alpha(t)|^{2m} d\xi + (2m-1) \int_0^1 |Y_\alpha(t)|^{2m-2} |\partial_\xi Y_\alpha(t)|^2 d\xi \\ &= \int_0^1 F_\alpha(Y_\alpha(t) + W_A(t)) Y_\alpha(t)^{2m-1} d\xi. \end{aligned}$$

Taking into account (3.1) we find

$$\begin{aligned} \frac{1}{2m} \frac{d}{dt} \int_0^1 |Y_\alpha(t)|^{2m} d\xi + (2m-1) \int_0^1 |Y_\alpha(t)|^{2m-2} |\partial_\xi Y_\alpha(t)|^2 d\xi \\ \leq c \int_0^1 |Y_\alpha(t)|^{2m} d\xi + c_1 \int_0^1 (1 + |W_A(t)|^m) |Y_\alpha(t)|^{2m-1} d\xi. \end{aligned}$$

Moreover,

$$\int_0^1 |Y_\alpha(t)|^{2m-2} |\partial_\xi Y_\alpha(t)|^2 d\xi = m^{-2} \int_0^1 |\partial_\xi (Y_\alpha^m(t))|^2 d\xi \geq 0.$$

Consequently, there exists constants  $a_1, \tilde{c} > 0$  such that

$$\frac{d}{dt} \int_0^1 |Y_\alpha(t)|^{2m} d\xi \leq \tilde{c} \int_0^1 |Y_\alpha(t)|^{2m} d\xi + a_1 \int_0^1 (1 + |W_A(t)|^m)^{2m} d\xi.$$

Consequently,

$$|Y_\alpha(t)|_{L^{2m}(0,1)}^{2m} \leq e^{\tilde{c}t} |x|_{L^{2m}(0,1)}^{2m} + a_1 \int_0^t e^{\tilde{c}(t-s)} \int_0^1 (1 + |W_A(s)|^m)^{2m} d\xi ds,$$

and, for a constant  $a_2 > 0$ ,

$$|Y_\alpha(t)|_{L^{2m}(0,1)}^{2m} \leq e^{\tilde{c}t} |x|_{L^{2m}(0,1)}^{2m} + a_2 \sup_{(s,\xi) \in [0,T] \times [0,1]} (1 + |W_A(s, \xi)|^m)^{2m}, \quad \forall t \in [0, T].$$

By [8, Theorem 4.8] there exists  $a_3 > 0$  such that

$$\mathbb{E} \left( |Y_\alpha(t)|_{L^{2m}(0,1)}^{2m} \right) \leq e^{\tilde{c}t} |x|_{L^{2m}(0,1)}^{2m} + a_3, \quad \forall t \in [0, T],$$

and so, there exists  $a_4 > 0$  such that

$$\mathbb{E} \left( |X_\alpha(t, x)|_{L^{2m}(0,1)}^{2m} \right) \leq e^{\tilde{c}t} |x|_{L^{2m}(0,1)}^{2m} + a_4, \quad \forall t \in [0, T].$$

Now the conclusion follows.  $\square$

In conclusion all assumptions of Theorem 2.4 are fulfilled.

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