# WEAK UNIQUENESS OF FOKKER-PLANCK EQUATIONS WITH DEGENERATE AND BOUNDED COEFFICIENTS 

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Abstract. In this note, by using the theory of stochastic differential equations (SDE), we prove uniqueness of measure-valued solutions and $L^{p}$-solutions to degenerate second order FokkerPlanck equations under weak conditions on the coefficients. Our uniqueness results are based on the natural connection between Fokker-Planck equations and SDEs.

Résumé. Dans cette Note, en utilisant la théorie des équations différentielles stochastiques (EDS), nous démontrons l'unicité de solutions $L^{p}$ et à valeurs mesures pour des équations de Fokker-Planck du second ordre dégénérées, sous des conditions faibles sur les coefficients. Nos résultats d'unicité sont fondés sur le lien naturel existant entre les équations de Fokker-Planck et les EDS.

## 1. Introduction and Main Results

Let $\mathbb{W}^{d}:=C\left([0,1] ; \mathbb{R}^{d}\right)$ be the space of all continuous functions from $[0,1]$ to $\mathbb{R}^{d}$. Let $\mathscr{W}_{t}$ be the canonical filtration generated by the coordinate process $W_{t}(\omega)=\omega(t)$, where $\omega \in \mathbb{W}^{d}$. Write $\mathscr{W}:=\mathscr{W}_{1}$. Let $v$ be the standard Wiener measure on $\left(\mathbb{W}^{d}, \mathscr{W}\right)$ so that $(t, \omega) \rightarrow W_{t}(\omega)$ is a standard $d$-dimensional Brownian motion.

Let $\left(X_{t}\right)_{t[0,1]}$ be a continuous $\mathscr{W}_{t}$-adapted process and solve the following SDE in $\mathbb{R}^{d}$ :

$$
\begin{equation*}
\mathrm{d} X_{t}=\sigma_{t}\left(X_{t}\right) \mathrm{d} W_{t}+b_{t}\left(X_{t}\right) \mathrm{d} t, \tag{1.1}
\end{equation*}
$$

where $\sigma:[0,1] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d} \times \mathbb{R}^{d}$ and $b:[0,1] \times \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ are two bounded measurable functions. Denote by $\mu_{t}$ the law of $X_{t}$ in $\mathbb{R}^{d}$, i.e.: for any $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$

$$
\begin{equation*}
\int_{\mathbb{R}^{d}} \varphi(x) \mu_{t}(\mathrm{~d} x)=\mathbb{E} \varphi\left(X_{t}\right) . \tag{1.2}
\end{equation*}
$$

Write

$$
L_{t}(x)=b_{t}^{i}(x) \partial_{i}+\frac{1}{2}\left[\sigma_{t}^{i k} \sigma_{t}^{j k}\right](x) \partial_{i j}^{2}
$$

By Itô's formula, $\mu_{t}$ solves the following Fokker-Planck equation in the sense of distribution:

$$
\begin{equation*}
\partial_{t} \mu_{t}=L_{t}^{*} \mu_{t}, \tag{1.3}
\end{equation*}
$$

where $L_{t}^{*}$ is the adjoint operator of $L_{t}$. More precisely, for any $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \int_{\mathbb{R}^{d}} \varphi(x) \mu_{t}(\mathrm{~d} x)=\int_{\mathbb{R}^{d}} L_{t} \varphi(x) \mu_{t}(\mathrm{~d} x),
$$

where the initial condition means that $\mu_{t}$ weakly $*$ converges to $\mu_{0}$ as $t \rightarrow 0$. In particular, if the law of $X_{t}$ is absolutely continuous with respect to Lebesgue measure, i.e., $\mu_{t}(\mathrm{~d} x)=u_{t}(x) \mathrm{d} x$, then $u_{t}(x)$ solves the following PDE in the weak sense:

$$
\begin{equation*}
\partial_{t} u_{t}=L_{t}^{*} u_{t} . \tag{1.4}
\end{equation*}
$$

Let $\mathcal{P}\left(\mathbb{R}^{d}\right)$ be the set of all probability measures on $\left(\mathbb{R}^{d}, \mathcal{B}\left(\mathbb{R}^{d}\right)\right)$. It is well known from [1] that if $\sigma^{i k}$ is uniformly non-degenerate and Lipschitz continuous, $b$ is locally integrable and coercive, then the uniqueness for (1.3) holds in $\mathcal{P}\left(\mathbb{R}^{d}\right)$, at least if the initial measure has finite entropy. In the degenerate case, in order to prove the uniqueness for (1.4), one usually needs
to impose some regularity on the solution. For example, Le Bris and Lions [7] proved the uniqueness of solutions to (1.4) for a given initial condition in the following class:

$$
\left\{u \in L^{\infty}\left(0,1 ;\left(L^{1} \cap L^{\infty}\right)\left(\mathbb{R}^{d}\right)\right), \sigma^{\mathrm{t}} \nabla u \in L^{2}\left(0,1 ; L^{2}\left(\mathbb{R}^{d}\right)\right)\right\}
$$

where $\sigma^{\mathrm{t}}$ denotes the transpose of $\sigma$. However, to the best of our knowledge, if $\sigma$ is degenerate, there are only a few results about the uniqueness of measure-valued solutions to (1.3) and $L^{p}$ solutions to (1.4).

For $p \geqslant 1$, define

$$
\mathcal{M}^{p}\left(\mathbb{R}^{d}\right):=\left\{u \in L^{p}\left(0,1 ; L_{l o c}^{p}\left(\mathbb{R}^{d}\right)\right) ; u \geqslant 0 \text { and } \int_{\mathbb{R}^{d}} u_{t}(x) \mathrm{d} x=1, \forall t \in[0,1]\right\} .
$$

Below, by $B_{R}:=\left\{x \in \mathbb{R}^{d}:|x| \leqslant R\right\}$ we denote the ball around zero in $\mathbb{R}^{d}$. Our main results are:
Theorem 1.1. Assume that $\sigma$ and $b$ are bounded measurable functions and for some $q \in[1, \infty]$ and any $R>0$, there exists a real function $f_{R} \in L^{q}\left([0,1] \times B_{R}\right)$ such that for almost all $(t, x, y) \in$ $[0,1] \times B_{R} \times B_{R}$

$$
\begin{equation*}
2\left\langle x-y, b_{t}(x)-b_{t}(y)\right\rangle+\left\|\sigma_{t}(x)-\sigma_{t}(y)\right\|^{2} \leqslant\left(f_{R, t}(x)+f_{R, t}(y)\right) \cdot|x-y|^{2} . \tag{1.5}
\end{equation*}
$$

Then for any given probability distribution density $\rho$, there is at most one weak solution $u_{t}$ to $\operatorname{PDE}(1.4)$ in the class $\mathcal{M}^{p}\left(\mathbb{R}^{d}\right)$, where $p=\frac{q}{q-1}$, with $u_{0}=\rho$.
Remark 1.2. Condition (1.5) is satisfied if for some $q \in(1, \infty]$,

$$
\left.b \in L^{q}\left(0,1 ; W_{l o c}^{q, 1} \mathbb{R}^{d}\right)\right), \quad \sigma \in L^{q \vee 2}\left(0,1 ; W_{l o c}^{q \vee 2,1}\left(\mathbb{R}^{d}\right)\right) .
$$

Indeed, in this case, there exists a constant $C_{d}>0$ such that for almost all $(t, x, y) \in[0,1] \times$ $B_{R} \times B_{R}(c f$. [2, Lemma A.2, A.3] or [9, Lemma 3.7])

$$
\left|b_{t}(x)-b_{t}(y)\right| \leqslant C_{d} \cdot\left(M_{R}\left|\nabla b_{t}\right|(x)+M_{R}\left|\nabla b_{t}\right|(y)\right) \cdot|x-y|
$$

and

$$
\left\|\sigma_{t}(x)-\sigma_{t}(y)\right\| \leqslant C_{d} \cdot\left(M_{R}\left|\nabla \sigma_{t}\right|(x)+M_{R}\left|\nabla \sigma_{t}\right|(y)\right) \cdot|x-y|,
$$

where $M_{R} g(x):=\sup _{0<r<R} f_{B_{r}} g(x+y)$ dy denotes the maximal function of $g$. By the boundedness of the maximal operator in $L^{q}(c f .[8])$, one knows that $M_{R}|\nabla b.| \in L^{q}\left([0,1] \times B_{R}\right)$ and $M_{R}|\nabla \sigma.| \in$ $L^{q \vee 2}\left([0,1] \times B_{R}\right)$.
Theorem 1.3. Assume that $\sigma$ and $b$ are bounded measurable functions and for some $q \in[1, \infty]$ and any $R>0$, there exists a real function $f_{R} \in L^{q}\left([0,1] \times B_{R}\right)$ such that for almost all $(t, x) \in$ $[0,1] \times B_{R}$ and all $y \in B_{R}$

$$
\begin{equation*}
2\left\langle x-y, b_{t}(x)-b_{t}(y)\right\rangle+\left\|\sigma_{t}(x)-\sigma_{t}(y)\right\|^{2} \leqslant f_{R, t}(x) \cdot|x-y|^{2} . \tag{1.6}
\end{equation*}
$$

Suppose that there exists a solution $u_{t}(x)$ to (1.4) in the class $\mathcal{M}^{p}\left(\mathbb{R}^{d}\right)$, where $p=\frac{q}{q-1}$. Then for any measure-valued solution $\mu_{t}$ to (1.3) in $\mathcal{P}\left(\mathbb{R}^{d}\right)$ with initial value $\mu_{0}(\mathrm{~d} x)=u_{0}(x) \mathrm{d} x$,

$$
\mu_{t}(\mathrm{~d} x)=u_{t}(x) \mathrm{d} x, \quad \forall t \in[0,1] .
$$

Remark 1.4. Condition (1.6) is satisfied if for some $q \in(d, \infty]$

$$
b \in L^{q}\left(0,1 ; W_{l o c}^{q, 1}\left(\mathbb{R}^{d}\right)\right), \quad \sigma \in L^{q \vee 2}\left(0,1 ; W_{l o c}^{q \vee 2,1}\left(\mathbb{R}^{d}\right)\right) .
$$

Indeed, in this case, there exists a constant $C_{d, q}>0$ such that for almost all $(t, x, y) \in[0,1] \times$ $B_{R} \times B_{R}(c f .[5, \mathrm{p} .143$, Theorem 3])

$$
\left|b_{t}(x)-b_{t}(y)\right| \leqslant C_{d, q} \cdot\left(M_{R}\left|\nabla b_{t}\right|^{q}(x)\right)^{1 / q} \cdot|x-y|
$$

and

$$
\left\|\sigma_{t}(x)-\sigma_{t}(y)\right\| \leqslant C_{d, q} \cdot\left(M_{R}\left|\nabla \sigma_{t}\right|^{q}(x)\right)^{1 / q} \cdot|x-y|
$$

Since $b$ and $\sigma$ are continuous by Sobolev's embedding theorem, the above two inequalities hold for all $y \in B_{R}$.

Theorems 1.1 and 1.3 will be proven in the next section. Our argument is based on the representation (1.2) (see Theorem 2.5 below) and Yamada-Watanbe's theorem (cf. [6]).

## 2. Proofs of Main Results

For proving our main results, we first recall some facts from the theories of SDEs and PDEs.
Definition 2.1. (Martingale solutions) Given $\mu_{0} \in \mathcal{P}\left(\mathbb{R}^{d}\right)$, a probability measure $P_{\mu_{0}}$ on ( $\left.\mathbb{W}^{d}, \mathscr{W}\right)$ is called a martingale solution of SDE (1.1) with initial distribution $\mu_{0}$ if $P_{\mu_{0}} \circ \omega_{0}^{-1}=\mu_{0}$ and for any $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$, $\varphi\left(\omega_{t}\right)-\varphi\left(\omega_{0}\right)-\int_{0}^{t} L_{s} \varphi\left(\omega_{s}\right) \mathrm{d}$ s is an $\mathscr{W}_{t}$-martingale under $P_{\mu_{0}}$.
Definition 2.2. (Weak solutions) Let $\mu_{0} \in \mathcal{P}\left(\mathbb{R}^{d}\right)$. We say that Eq.(1.1) has a weak solution with initial law $\mu_{0}$ if there exist a stochastic basis $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t \in[0,1]}\right)$, a $\mathbb{R}^{d}$-valued continuous $\left(\mathscr{F}_{t}\right)$ adapted stochastic process $X$ and a d-dimensional standard $\left(\mathscr{F}_{t}\right)$-Brownian motions $\left(W_{t}\right)_{t \in[0,1]}$ such that $X_{0}$ has law $\mu_{0}$ and $X_{t}=X_{0}+\int_{0}^{t} b_{s}\left(X_{s}\right) \mathrm{d} s+\int_{0}^{t} \sigma_{s}\left(X_{s}\right) \mathrm{d} W_{s}, \forall t \geqslant 0$, a.s. This solution is denoted by $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t \in[0,1]} ; W, X\right)$.

The following two propositions are well known (cf. [6, Chapter IV, Theorem 1.1 and Proposition 2.1]).

Proposition 2.3. (Equivalence between martingale solutions and weak solutions) Given $\mu_{0} \in$ $\mathcal{P}\left(\mathbb{R}^{d}\right)$ and let $P_{\mu_{0}}$ be a martingale solution of $\operatorname{SDE}(1.1)$. Then there exists a weak solution $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t \in[0,1]} ; W, X\right)$ to $\operatorname{SDE}(1.1)$ such that $P \circ X^{-1}=P_{\mu_{0}}$.

Proposition 2.4. Given two weak solutions to $\operatorname{SDE}$ (1.1)

$$
\left(\Omega^{(i)}, \mathscr{F}^{(i)}, P^{(i)} ;\left(\mathscr{F}_{t}^{(i)}\right)_{t \in[0,1]} ; W^{(i)}, X^{(i)}\right), \quad i=1,2,
$$

with the same initial law $\mu_{0} \in \mathcal{P}\left(\mathbb{R}^{d}\right)$, there exists a stochastic basis $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t[0,1]}\right)$, a standard d-dimensional $\left(\mathscr{F}_{t}\right)$-Brownian motion $W$ and two continuous $\left(\mathscr{F}_{t}\right)$-adapted processes $Y^{(i)}, i=1,2$ such that $P\left(Y_{0}^{(1)}=Y_{0}^{(2)}\right)=1$ and $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t[0,1]} ; W, Y^{(i)}\right), i=1,2$ are two weak solutions of (1.1), and $X^{(i)}$ and $Y^{(i)}$ have the same laws in $\mathbb{W}^{d}$ for $i=1,2$.

The following result is due to Figalli [4, Theorem 2.6].
Theorem 2.5. Assume that $\sigma$ and $b$ are bounded measurable functions. Given $\mu_{0} \in \mathcal{P}\left(\mathbb{R}^{d}\right)$, let $\mu_{t} \in \mathcal{P}\left(\mathbb{R}^{d}\right)$ be a measure-valued solution of PDE (1.3) with initial value $\mu_{0}$. Then there exists a martingale solution $P_{\mu_{0}}$ to $\operatorname{SDE}$ (1.1) with initial distribution $\mu_{0}$ such that for any $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$

$$
\int_{\mathbb{R}^{d}} \varphi(x) \mu_{t}(\mathrm{~d} x)=\int_{\mathbb{W}^{d}} \varphi\left(\omega_{t}\right) P_{\mu_{0}}(\mathrm{~d} \omega), \quad \forall t \in[0,1] .
$$

We are now in a position to give the proofs of our main results.
Proof of Theorem 1.1. Let $u_{t}^{(i)}, i=1,2$ be two weak solutions of (1.4) in the class $\mathcal{M}^{p}\left(\mathbb{R}^{d}\right)$ with the same initial value $u_{0}$. By Theorem 2.5, there exists two martingale solutions $P_{u_{0}}^{(i)}, i=1,2$ to $\operatorname{SDE}$ (1.1) with the same initial law $u_{0}(x) \mathrm{d} x$ such that for any $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{d}\right)$

$$
\begin{equation*}
\int_{\mathbb{R}^{d}} \varphi(x) u_{t}^{(i)}(x) \mathrm{d} x=\int_{\mathbb{W}^{d}} \varphi\left(\omega_{t}\right) P_{u_{0}}^{(i)}(\mathrm{d} \omega), \quad i=1,2 . \tag{2.1}
\end{equation*}
$$

By Propositions 2.3 and 2.4 , there is a common stochastic basis $\left(\Omega, \mathscr{F}, P ;\left(\mathscr{F}_{t}\right)_{t \in[0,1]}\right)$, a standard $d$-dimensional $\left(\mathscr{F}_{t}\right)$-Brownian motion $W$ and two continuous $\left(\mathscr{F}_{t}\right)$-adapted processes $Y^{(i)}, i=$ 1,2 such that $P\left(Y_{0}^{(1)}=Y_{0}^{(2)}\right)=1$ and for $i=1,2$

$$
\begin{equation*}
Y_{t}^{(i)}=Y_{0}^{(i)}+\int_{0}^{t} b_{s}\left(Y_{s}^{(i)}\right) \mathrm{d} s+\int_{0}^{t} \sigma_{s}\left(Y_{s}^{(i)}\right) \mathrm{d} W_{s}, \tag{2.2}
\end{equation*}
$$

and $Y^{(i)}$ has law $P_{u_{0}}^{(i)}$ in ( $\left.\mathbb{W}^{d}, \mathscr{W}\right)$.

Set now $Z_{t}:=Y_{t}^{(1)}-Y_{t}^{(2)}$ and for $R>0, \tau_{R}:=\inf \left\{t \in[0,1]:\left|Y_{t}^{(1)}\right| \vee\left|Y_{t}^{(2)}\right| \geqslant R\right\}$. By Itô's formula, for any $\delta>0$, we have

$$
\begin{align*}
\log \left(\frac{\left|Z_{t \wedge \tau_{R}}\right|^{2}}{\delta^{2}}+1\right)= & \int_{0}^{t \wedge \tau_{R}} \frac{\left.2\left\langle Z_{s}, b_{s}\left(Y_{s}^{(1)}\right)-b_{s}\left(Y_{s}^{(2)}\right)\right\rangle+\| \sigma_{s}\left(Y_{s}^{(1)}\right)\right)-\sigma_{s}\left(Y_{s}^{(2)}\right) \|^{2}}{\left|Z_{s}\right|^{2}+\delta^{2}} \mathrm{~d} s \\
& +2 \int_{0}^{t \wedge \tau_{R}} \frac{\left\langle Z_{s},\left(\sigma_{s}\left(Y_{s}^{(1)}\right)-\sigma_{s}\left(Y_{s}^{(2)}\right)\right) \mathrm{d} W_{s}\right\rangle}{\left|Z_{s}\right|^{2}+\delta^{2}} \\
& -2 \int_{0}^{t \wedge \tau_{R}} \frac{\left|\left(\sigma_{s}\left(Y_{s}^{(1)}\right)-\sigma_{s}\left(Y_{s}^{(2)}\right)\right)^{\mathrm{t}} \cdot Z_{s}\right|^{2}}{\left(\left|Z_{s}\right|^{2}+\delta^{2}\right)^{2}} \mathrm{~d} s . \tag{2.3}
\end{align*}
$$

Let $\rho$ be a nonnegative smooth function on $\mathbb{R}^{d}$ with support in $\left\{x \in \mathbb{R}^{d}:|x|<1\right\}$ and $\int_{\mathbb{R}^{d}} \rho(x) \mathrm{d} x=$ 1. For $\varepsilon \in(0,1)$, let $\rho_{\varepsilon}(x):=\varepsilon^{-d} \rho(x / \varepsilon)$ be a mollifier and define $b_{s}^{\varepsilon}:=b_{s} * \rho_{\varepsilon}, \sigma_{s}^{\varepsilon}:=\sigma_{s} * \rho_{\varepsilon}$, where $*$ denotes the convolution. By the property of mollifier, we have

$$
\lim _{\varepsilon \downarrow 0} \int_{0}^{t} \int_{B_{R}}\left(\left|b_{s}^{\varepsilon}(x)-b_{s}(x)\right|^{p}+\left\|\sigma_{s}^{\varepsilon}(x)-\sigma_{s}(x)\right\|^{p}\right) \mathrm{d} x \mathrm{~d} s=0, \quad p \in[1, \infty),
$$

and by (1.5) and the property of convolution, for almost all $t$ and all $x, y \in B_{R}$

$$
2\left\langle x-y, b_{t}^{\varepsilon}(x)-b_{t}^{\varepsilon}(y)\right\rangle+\left\|\sigma_{t}^{\varepsilon}(x)-\sigma_{t}^{\varepsilon}(y)\right\|^{2} \leqslant\left(f_{R+1, t}^{\varepsilon}(x)+f_{R+1, t}^{\varepsilon}(y)\right) \cdot|x-y|^{2}
$$

Thus, by taking expectations for (2.3), we obtain

$$
\begin{aligned}
\mathbb{E} \log \left(\frac{\left|Z_{t \wedge \tau_{2}}\right|^{2}}{\delta^{2}}+1\right) \leqslant & \mathbb{E} \int_{0}^{t \wedge \tau_{R}} \frac{2\left\langle Z_{s}, b_{s}\left(Y_{s}^{(1)}\right)-b_{s}\left(Y_{s}^{(2)}\right)\right\rangle+\left\|\sigma_{s}\left(Y_{s}^{(1)}\right)-\sigma_{s}\left(Y_{s}^{(2)}\right)\right\|^{2}}{\left|Z_{s}\right|^{2}+\delta^{2}} \mathrm{~d} s \\
\leqslant & \mathbb{E} \int_{0}^{t \wedge \tau_{R}} \frac{2\left\langle Z_{s}, b_{s}^{\varepsilon}\left(Y_{s}^{(1)}\right)-b_{s}^{\varepsilon}\left(Y_{s}^{(2)}\right)\right\rangle+\left\|\sigma_{s}^{\varepsilon}\left(Y_{s}^{(1)}\right)-\sigma_{s}^{\varepsilon}\left(Y_{s}^{(2)}\right)\right\|^{2}}{\left|Z_{s}\right|^{2}+\delta^{2}} \mathrm{~d} s \\
& +\frac{2}{\delta} \mathbb{E} \int_{0}^{t \wedge \tau_{R}}{ }^{\left(\left|b_{s}^{\varepsilon}\left(Y_{s}^{(1)}\right)-b_{s}\left(Y_{s}^{(1)}\right)\right|+\left|b_{s}^{\varepsilon}\left(Y_{s}^{(2)}\right)-b_{s}\left(Y_{s}^{(2)}\right)\right|\right) \mathrm{d} s} \\
& +\frac{3}{\delta^{2}} \mathbb{E} \int_{0}^{t \wedge \tau_{R}}\left(\left\|\sigma_{s}^{\varepsilon}\left(Y_{s}^{(1)}\right)-\sigma_{s}\left(Y_{s}^{(1)}\right)\right\|^{2}+\left\|\sigma_{s}^{\varepsilon}\left(Y_{s}^{(2)}\right)-\sigma_{s}\left(Y_{s}^{(2)}\right)\right\|^{2}\right) \mathrm{d} s \\
=: & I_{1}^{\varepsilon}+I_{2}^{\varepsilon}+I_{3}^{\varepsilon} .
\end{aligned}
$$

For $I_{1}^{\varepsilon}$, we have

$$
\begin{aligned}
I_{1}^{\varepsilon} & \leqslant \mathbb{E} \int_{0}^{t \wedge \tau_{R}}\left(f_{R+1, s}^{\varepsilon}\left(Y_{s}^{(1)}\right)+f_{R+1, s}^{\varepsilon}\left(Y_{s}^{(2)}\right)\right) \mathrm{d} s \\
& \leqslant \mathbb{E} \int_{0}^{t}\left(1_{\left|Y_{s}^{(1)}\right| \leqslant R} \cdot f_{R+1, s}^{\varepsilon}\left(Y_{s}^{(1)}\right)+1_{\left|Y_{s}^{(2)}\right| \leqslant R} \cdot f_{R+1, s}^{\varepsilon}\left(Y_{s}^{(2)}\right)\right) \mathrm{d} s \\
& =\int_{0}^{t} \int_{B_{R}} f_{R+1, s}^{\varepsilon}(x) u_{s}^{(1)}(x) \mathrm{d} x \mathrm{~d} s+\int_{0}^{t} \int_{B_{R}} f_{R+1, s}^{\varepsilon}(x) u_{s}^{(2)}(x) \mathrm{d} x \mathrm{~d} s \\
& \left.\leqslant\left\|f_{R+1}^{\varepsilon}\right\|_{L^{q}\left([0,1] \times B_{R}\right)}\left\|u^{(1)}\right\|_{L^{p}\left([0,1] \times B_{R}\right)}+\left\|f_{R+1}^{\varepsilon}\right\|_{L^{q}\left([0,1] \times B_{R}\right)}\right)\left\|u^{(2)}\right\|_{L^{p}\left([0,1] \times B_{R}\right)} .
\end{aligned}
$$

Similarly, we have

$$
I_{2}^{\varepsilon} \leqslant C\left(\int_{0}^{t} \int_{B_{R}}\left|b_{s}^{\varepsilon}(x)-b_{s}(x)\right|^{q} \mathrm{~d} x \mathrm{~d} s\right)^{1 / q}
$$

and

$$
I_{3}^{\varepsilon} \leqslant C\left(\int_{0}^{t} \int_{B_{R}}\left|\sigma_{s}^{\varepsilon}(x)-\sigma_{s}(x)\right|^{q} \mathrm{~d} x \mathrm{~d} s\right)^{1 / q}
$$

where the constant $C$ depends on $\left\|u^{(i)}\right\|_{L^{p}\left[[0,1] \times B_{R}\right)}$, but is independent of $\varepsilon$.

Combining the above calculations and letting $\varepsilon$ go to zero, we get

$$
\mathbb{E} \log \left(\frac{\left|Z_{t \wedge \tau_{R}}\right|^{2}}{\delta^{2}}+1\right) \leqslant\left\|f_{R+1}\right\|_{L^{q}\left([0,1] \times B_{R}\right)} \cdot\left(\left\|u^{(1)}\right\|_{\left.L^{p}(0,1] \times B_{R}\right)}+\left\|u^{(2)}\right\|_{L^{p}\left([0,1] \times B_{R}\right)}\right) .
$$

Now, letting $\delta \rightarrow 0$, we obtain that for any $R>0$ and $t \in[0,1]$

$$
\begin{equation*}
Z_{t \wedge \tau_{R}}=0, \text { a.s. } \tag{2.4}
\end{equation*}
$$

Since $b$ and $\sigma$ are bounded, from (2.2), it is now standard to prove that

$$
\mathbb{E}\left(\sup _{t[[0,1]}\left|Y_{t}^{(i)}\right|\right)<+\infty, \quad i=1,2
$$

Hence,

$$
P\left\{\omega: \lim _{R \rightarrow \infty} \tau_{R}(\omega)=1\right\}=1
$$

and letting $R \rightarrow \infty$ in (2.4), we further have

$$
Z_{t}=0, \text { a.s., } \forall t \in[0,1] .
$$

So, $P_{u_{0}}^{(1)}=P_{u_{0}}^{(2)}$. Now, the uniqueness follows by (2.1).
Proof of Theorem 1.3. Following the proof of Theorem 1.1, let $Y_{t}^{(1)}$ (resp. $Y_{t}^{(2)}$ ) be the weak solution corresponding to $u_{t}(x) \mathrm{d} x\left(\right.$ resp. $\left.\mu_{t}(\mathrm{~d} x)\right)$. By (1.6) and (2.3), we have

$$
\mathbb{E} \log \left(\frac{\left|Z_{t \wedge \tau_{R}}\right|^{2}}{\delta^{2}}+1\right) \leqslant \mathbb{E} \int_{0}^{t \wedge \tau_{R}} f_{R, s}\left(Y_{s}^{(1)}\right) \mathrm{d} s \leqslant\left\|f_{R}\right\|_{L^{q}\left([0,1] \times B_{R}\right)} \cdot\|u\|_{L^{p}\left([0,1] \times B_{R}\right)} .
$$

From this, as above we obtain the uniqueness.

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