Nonlinear dispersive equations, solitary waves and noise

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Nonlinear dispersive equations

- model equations for propagation of waves in nonlinear dispersive media
- "Universal models" : water waves, nonlinear optics, plasma physics, energy transfer in molecular systems, Bose-Einstein condensation ...
- conservative equations
- In general

 $i\partial_t u + P(D)u + F(u) = 0$

where u = u(t, x) is the unknown and

$$\widehat{P(D)u}(\xi) = p(\xi)\widehat{u}(\xi)$$

where *p* is **real valued**; dispersion relation : $\omega(k) = -p(k)$

Examples

Korteweg - de Vries equations

$$(KdV) \qquad \qquad \partial_t u + \partial_x^3 u + \partial_x(u^2) = 0$$

- Boussinesq, 1872, Korteweg- de Vries, 1895 after observation by J. Scott Russel, 1834 http://www.ma.hw.ac.uk/solitons
- asymptotic model for long waves at the surface of water (small amplitude, shallow water, unidirectional propagation)

rigorous derivation (from free surface Euler equations) : W. Craig, CPDE, 1985

• here,
$$p(k) = k^3$$
 (strong dispersion)

► Model for plasma physics : Herman, J. Phys. A, 1990

Examples

Nonlinear Schrödinger equations

 $(NLS) i\partial_t u + \Delta u + F(u) = 0$

- ▶ here, $p(k) = |k|^2$
- ► describes enveloppe of wave packets in water waves (deep water) Zakharov, 1968, F(u) = κ|u|²u
- ▶ propagation of light in dispersive and nonlinear media (e.g. optic fibers) F(u) = κ|u|²u rigorous derivation (as enveloppe, from Maxwell equations) : Donnat, Joly, Metivier, Rauch, 1996 in optic fibers : special case of the Manakov system
- ► Bose-Einstein condensation : Gross-Pitaevskii equation $F(u) = V(x)u + \kappa |u|^2 u$

Integrable equations

Some of those equations are integrable by inverse scattering

 \rightsquigarrow infinity of invariant functionals

 \rightsquigarrow existence of solitons : localized solutions propagating without change of form, elastic interactions

 \rightsquigarrow resolution into solitons + dispersive tail

KdV : Gardner, Green, Kruskal, Miura, 1967

cubic NLS equations in dimension one $(x \in \mathbf{R})$: Zakharov-Shabat, 1972

Non integrable equations : higher dimension, higher order nonlinearity, external (possibly random) forces... which of those properties still hold? sometimes still localized solutions : solitary waves

Why adding noise?

KdV-type equations (no rigorous mathematical derivation)

- ► random pressure field (water surface waves) : e.g., turbulent wind on the surface → additive noise, white in time Ė(t, x)
- ► variations of the bottom topography modeled by a stationary (in x) random process : → add a term (∂_xu)ξ(t), white in time Craig, de Bouard, Diaz-Espinoza, Guyenne, Sulem, Nonlinearity, 2008
- ► temperature effects (plasma physics) : Herman, J. Phys. A, 1990 random potentials : uξ(t,x) or (∂_xu)ξ(t,x)
- ► model for weak turbulence (Kuksin et; al.), random perturbations of nonlinearity, velocity or dispersion (Garnier) = ∽ac

Why adding noise?

NLS-type equations

- ► temperature effects (light propagation in molecular systems) : →→ potential terms uξ(t, x) Bang, Christiansen, If, Rasmussen, Gaididei, Phys. Rev. E, 1994
- ► inhomogeneities in the medium (e.g. optic fibers) : Falkovich, Kolokolov, Lebedev, Turitsyn, Phys. Rev. E, 1994 amplifiers : → additive noise ξ(t, x) dispersion management → perturbation of dispersion ξ(t)∆u
- ► fluctuations of the laser frequency (Bose-Einstein condensation) : induces fuctuations of the confining potential Abdullaev, Baizakov, Konotop, Nonlinearity and Disorder, 2001 ~→ ξ(t)V(x)

Localized solutions propagating without change of form (due to nonlinearity + dispersion)

- ► travelling waves : $u(x,t) = \varphi_v(x vt)$, $v \in \mathbf{R}^d$
- ▶ standing waves : $u(x, t) = e^{i\omega t} \varphi_{\omega}(x)$, $\omega \in \mathbf{R}$

Symmetries of equations lead to more general families of solutions KdV-type equations : two parameter family of solutions

$$u_{c,x_0}(x,t) = \varphi_c(x-ct-x_0), c > 0, x_0 \in \mathbf{R}$$

NLS-type equations : 2d + 2-parameter family of solutions

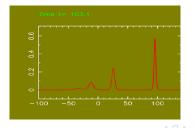
$$u_{\omega,\theta,v,x_0}(x,t) = \varphi_{\omega}(x-2vt-x_0)e^{i(\omega t-v.x+v^2t+\theta)}$$

(translation, Galilean and Gauge transformations)

Integrable cases : resolution into soliton for any localized solution

Theorem : (Eckaus-Schuur, 1986, Deft-Zhou, 1993) Let u(x, t) be a regular and localized solutions of the KdV equation; then there exist $N \in \mathbf{N}$, $c_1, \dots, c_N > 0$, $\gamma_1, \dots, \gamma_N \in \mathbf{R}$, $\nu > 0$ and $\mu > 0$ such that

$$\lim_{t\to\infty}\sup_{x\geq-\mu-\nu t^{1/3}}|u(x,t)-\sum_{k=1}^N\varphi_{c_k}(x-c_kt-\gamma_k)|=0$$



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Symplectic formulation of the equation

 $\partial_t u = JH'(u)$

where $J = \partial_x$ for (KdV), J = i for (NLS) and

(KdV)
$$H(u) = \frac{1}{2} \int (\partial_x u)^2 dx - \frac{1}{3} \int u^3 dx$$

energy or Hamiltonian

(NLS)
$$H(u) = \frac{1}{2} \int |\nabla u|^2 dx - \frac{1}{4} \int |u|^4 dx$$

the mass or charge si also conserved :

$$m(u)=\frac{1}{2}\int |u|^2dx$$

Solitary wave = critical point of the action functional

$$\mathcal{E}_{\omega}(u) = H(u) + \omega m(u)$$

Numerical methods for computations of solitary waves

Shooting methods (radial solutions)

$$\begin{cases} \varphi''(r) + \frac{d-1}{r}\varphi'(r) - \omega\varphi(r) + \kappa |\varphi(r)|^{2\sigma}\varphi(r) = 0\\ \varphi(0) = \beta, \ \varphi'(0) = 0 \end{cases}$$

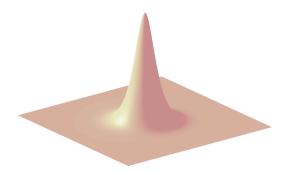
+ dichotomy argument to find β^* such that $\lim_{r \to \infty} \varphi(r) = 0$

Excited states, central vortices, systems of equations Di Menza, M2AN, 2009

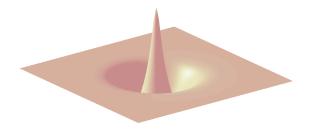
Complex time integration : solve the heat flow

$$\partial_t u = H'(u)$$

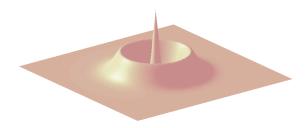
with renormalization of the L^2 -norm at each time step \rightsquigarrow convergence to a solitary wave



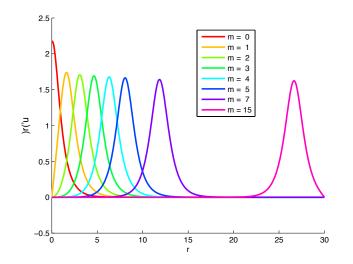
computation of the ground state of NLS by shooting method (Di Menza, 2009)



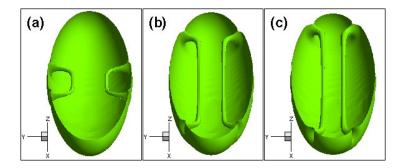
computation of excited state of NLS by shooting method (Di Menza, 2009)



computation of excited state of NLS by shooting method (Di Menza, 2009)



(Belaouar, 2011)



computation of vortices of 3-D NLS by complex time integration (Danaïla, 2006)

Solitary waves : orbital stability

Define

$$(\mathsf{GKdV}) \qquad \qquad \mathsf{U}_{\varepsilon} = \left\{ u \in \mathsf{H}^1, \ \inf_{s \in \mathsf{R}} \|u - \varphi_{\omega}(.-s)\|_{\mathsf{H}^1} \leq \varepsilon \right\}$$

 $\ensuremath{arphi}_{\omega}$ is orbitally stable if, given $\ensuremath{arphi} > 0$, any solution starting sufficiently close to $\ensuremath{arphi}_{\omega}$ stays in $U_{\ensuremath{arepsilon}}$ for all time

Theorem : φ_{ω_0} is stable iff $\mathcal{E}_{\omega}(\varphi_{\omega})$ is a convex function of ω near ω_0

Benjamin, Bona-Souganidis-Strauss, Weinstein, Grillakis-Shatah-Strauss

Solitary waves : orbital stability

Key point : study of $L_{\omega} = \mathcal{E}''_{\omega}(\varphi_{\omega})$ (not positive definite)

 If d/dωm(φω0) > 0 then φω0 is a minimum of H for constant m

 if d/dω m(φω0) < 0 then there is a curve ψα with m(ψα) = m(φω0) on which H is maximized at φω0

Solitary waves : asymptotic stability

linearization : $u(t,x) = \varphi_{\omega}(x - \omega t) + v(t,x - \omega t)$ (GKdV)

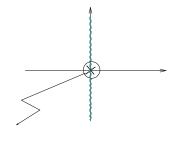
$$\rightsquigarrow \quad \frac{dv}{dt} = JL_{\omega}v$$

• $\sigma_e(JL_\omega) = i\mathbf{R}$

 nullspace generated by invariances of equation

ex (GKdV) :

$$\begin{cases} \partial_{x} L_{\omega}(\partial_{x}\varphi_{\omega}) = 0\\ \\ \partial_{x} L_{\omega}(\partial_{\omega}\varphi_{\omega}) = -\partial_{x}\varphi_{\omega} \end{cases}$$



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Solitary waves : asymptotic stability

GKdV : Pego-Weinstein, 1994, Martel-Merle, 2001 NLS : Buslaev-Perelman, 1992, Buslaev-Sulem, 2003

Principal part written as a modulated solitary wave :

$$u(t,x) = \varphi_{\omega(t)}(x - x(t)) + v(t, x - x(t))$$

and $\omega(t)$, x(t) chosen in order to eliminate secular modes

- ► cvgence to a solitary wave with shifted parameters $\omega(t) \rightarrow \omega^+, \quad x(t) \sim \omega^+ t + x^+ \text{ as } t \rightarrow +\infty$
- cvgence of v in a space with exponential weight (or locally in space)
- also true for *n*-solitary wave solutions Martel-Merle-Tsai, 2003
- ► recent results on non elastic collision of solitons for GKdV Martel-Merle. 2009

$$du + (\partial_x^3 u + \partial_x(u^2))dt = \left\{egin{array}{c} arepsilon dW\ arepsilon u dW\ arepsilon u dW \end{array}
ight.$$

W(t) infinite dimensional Wiener process i.e.

$$W(t,x) = \sum_{j} \Phi(e_j)(x) W_j(t)$$

 W_j indep. 1-D BM, (e_j) c.o.s. in $L^2(\mathbf{R})$,

- Φ Hilbert-Schmidt operator from L²(R) into H¹(R), if additive noise
- $\Phi(e_j) = k * e_j$, with $k \in H^1(\mathbf{R}) \cap L^1(\mathbf{R})$ if multiplicative noise; equivalently

$$W(t,x) = \int_0^t \int_{\mathbf{R}} k(x-y)B(ds,dy)$$

where B is a Brownian sheet on $\mathbf{R}^+ \times \mathbf{R}_{\rightarrow}$, \mathbf{R}_{\rightarrow} ,

Let $u^{\varepsilon}(0,x) = \varphi_{\omega_0}(x)$; write the solution u^{ε} of the stochastic equation as

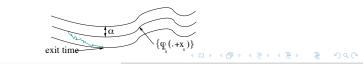
$$u^{\varepsilon}(t,x) = \varphi_{\omega^{\varepsilon}(t)}(x - x^{\varepsilon}(t)) + \varepsilon \eta^{\varepsilon}(t, x - x^{\varepsilon}(t))$$

where the parameters $x^{\varepsilon}(t)$ and $\omega^{\varepsilon}(t)$ are random modulation parameters, chosen such that for all t, $(\eta^{\varepsilon}(t), \varphi_{\omega_0}) = (\eta^{\varepsilon}(t), \partial_x \varphi_{\omega_0}) = 0$

This decomposition holds as long as $\|\varepsilon\eta^{\varepsilon}(t)\|_{H^1} \leq \alpha$ and $|\omega^{\varepsilon}(t) - \omega_0| \leq \alpha$ for $\alpha > 0$ sufficiently small.

Question : Can we estimate the time $\tau^{\varepsilon}_{\alpha}$ with

 $\tau_{\alpha}^{\varepsilon} = \inf\{t > 0, \; \|\varepsilon\eta^{\varepsilon}(t)\|_{H^{1}} \geq \alpha \text{ or } |\omega^{\varepsilon}(t) - \omega_{0}| \geq \alpha\}?$



joint works with A. Debussche, E. Gautier, 2007-2010 For all T > 0, and $\varepsilon > 0$ with $\varepsilon^2 T$ sufficiently small,

$$\mathbf{P}(\tau_{\alpha}^{\varepsilon} \leq T) \leq \exp(-\frac{C(\alpha)}{\varepsilon^{2}T})$$

Moreover, in the additive case, if W replaced by W_n approximating space-time white noise, then there exists a constant $C(\alpha, \omega_0)$ such that for all T > 0,

$$\liminf_{n \to +\infty} \liminf_{\varepsilon \to 0} \varepsilon^2 \log \mathsf{P}(\tau_{\alpha}^{n,\varepsilon} \leq T) \geq -\frac{\mathcal{C}(\alpha,\omega_0)}{\mathcal{T}}$$

Remark :

- ► LDP holds in multiplicative case; however, have to solve a controllability problem by a potential ~→ open problem
- ► lower bounds on the exit time without modulation : $-\frac{C(\alpha,\omega_0)}{T^3}$

Multiplicative homogeneous case :

 η^{ε} converges to η as ε goes to zero, on fixed time intervals, in the mean square sense ; η solution of

$$d\eta = \partial_x L_{\omega_0} \eta dt + Q(\varphi_{\omega_0} d\tilde{W})$$

with $\eta(0) = 0$ and

- $\tilde{W}(t,x) = W(t,x+\omega_0 t)$
- ► Q : projector on the "stable manifold"
- η is a centered Gaussian process ("Ornstein-Uhlenbeck" if
 ∂_xL_{ω₀} dissipative operator)

Pego, Weinstein, CMP, 1994 : $Q\partial_x L_{\omega_0}$ dissipative in spaces with exponential weights

 $\rightsquigarrow \eta$ converges weakly to a Gaussian stationary measure as t goes to infinity

The modulation equations are given by

$$\begin{cases} dx^{\varepsilon} = \omega_0 + \varepsilon B_1 dt + \varepsilon dB_2 + o(\varepsilon) \\ d\omega^{\varepsilon} = \varepsilon dB_1 + o(\varepsilon) \end{cases}$$

with (B_1, B_2) a **R**²-valued brownian motion, corresponding to projection of the noise on the center manifold

• Keeping only first order terms in ε , we obtain

$$\max_{x \in \mathbf{R}} \mathbf{E} \left(\varphi_{\omega^{\varepsilon}(t)}(x - x^{\varepsilon}(t)) \right) \leq K_{\omega_0} \varepsilon^{-1/2} t^{-5/4}$$

for large t

Wadati, J. Phys. Soc. Japan, 1983 : additive pure time white noise, $Ct^{-3/2}$

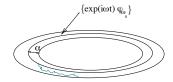
Stochastic case : NLS

Same kind of results for NLS equation with

- confining potential : $V(x) = |x|^2$
- small noise : $\varepsilon V(x)u \circ dW(t)$

AdB, Fuikuizumi, 2009

$$\psi^{\varepsilon}(t,x) = e^{i\theta^{\varepsilon}(t)}(\phi_{\omega^{\varepsilon}(t)}(x) + \varepsilon \eta^{\varepsilon}(t,x))$$



No asymptotic stability (bounds states) but asymptotics on η for ω close to $\omega_{\min} = -d$

Space-time NLS : Crank-Nicolson in time + finite differences or finite elements in space + semi-implicit discretization of the noise $u \circ dW(t, x)$

Debussche-Di Menza, 2002, Barton-Smith-Debussche-Di Menza, 2005

convergence of the semi-discretization in time + order estimates dB, Debussche, 2004, 2006

Additive KdV : Crank-Nicolson in time + finite elements in space

Debussche-Printems, 1999, 2001

convergence of the semi-discretization in time Debussche-Printems, 2006

NLS with time-dependent noise :

Splitting methods :

- $i\partial_t u + \Delta u = 0$: FFT
- ▶ nonlinearity + noise : explicit integration

M. Gazeau, 2011, work in progress with R. Belaouar

Alternative to Crank-Nicolson : relaxation scheme (avoids nonlinear implicitness)

C. Besse, deterministic NLS, 1998

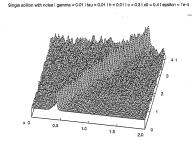
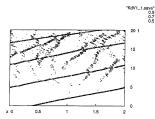


FIG. 3.13: Single soliton with noise, $\gamma = 10^{-2}$, c = 0.3, $\varepsilon = 10^{-4}$, $x_0 = 0.4$ on [0, 3].

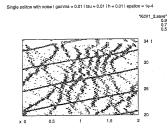
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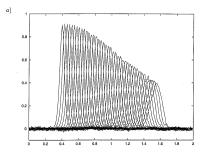




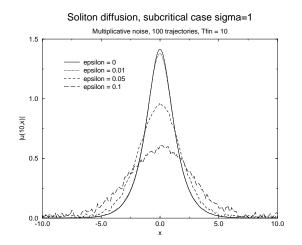
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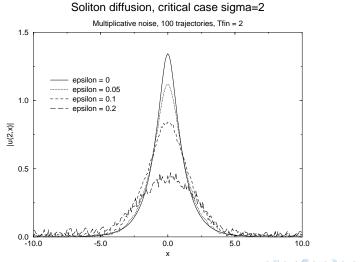
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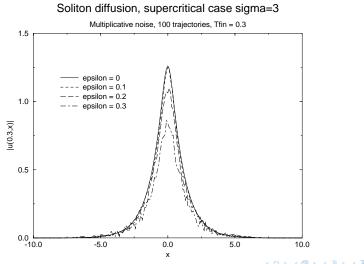




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Conclusion and open problems

Dynamics of stochastic nonlinear dispersive equations still needs investigations : lots of applications

Open problems in asymptotic dynamics :

- Take account of asymptotic stability for KdV in additive case?
- ► Explain diffusion NLS soliton with space-time noise?
- ▶ KdV in periodic case $x \in \mathbb{T}$: Y. Tsutsumi, 2009

Assume $|k * |v|^2|_{L^2}^2 \ge \delta^2 |v|_{L^2}^4$ with $2\delta^2 \ge |k|_{L^2}^2$

Then the solution u of

$$du + (\partial_x^3 u + \partial_x(u^2))dt = udW$$

satisfies :

$$|u(t)|_{L^2}
ightarrow 0, \; a.s. ext{ as } t
ightarrow +\infty$$

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Conclusion and open problems

• Dynamics at time
$$1/\varepsilon^2$$
 : averaging?

Inverse scattering : Garnier, 1998 (NLS), 2001 (KdV) Noise representing perturbations of velocity, dispersion or nonlinearity; Propagation of solitons : equations on the scattering data; no estimate on the remaining terms for the original solution

Action-angle variables : Kuksin, Piatnitski, 2008 Hasminski-Whitham averaging for

$$\partial_t u + \partial_x^3 u - \nu \partial_x^2 u + \partial_x (u^2) = \sqrt{\nu} \dot{\xi};$$

modeling of weak turbulence.

Conclusion and open problems

Rigorous derivation of stochastic models

Needs stochastic homogenization (and more...) e.g.

- Dirichlet to Neumann operator in domain with random boundary (water wave problem)
- Propagation in molecular systems : stochastic NLS equation formally obtained from interacting particle system

$$\begin{cases} i\hbar \frac{d\phi_n}{dt} + \sum_{p \neq n} J_{pn}\phi_p + \chi u_n\phi_n = 0\\ M\frac{d^2u_n}{dt^2} + M\lambda\frac{du_n}{dt} + M\omega_0^2u_n = \chi |\phi_n|^2 + \eta_n \end{cases}$$

Last step : diffusion approximation (current work with A. Debussche, M. Gazeau)