SPDES driven by Poisson Random Measures and their numerical Approximation

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Outline

- Lévy processes Poisson Random Measure
- Stochastic Integration in Banach spaces
- SPDEs driven by Poisson Random Measure
- Their Numerical Approximation

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The equation we would like to approximate

Let \mathcal{O} be a bounded domain in \mathbb{R}^d with smooth boundary. The Equation:

$$(\star) \begin{cases} \frac{du(t,\xi)}{dt} &= \frac{\partial^2}{\partial\xi^2}u(t,\xi) + \alpha\nabla u(t,\xi) + g(u(t,\xi))\dot{L}(t) \\ &+ f(u(t,\xi)), \quad \xi \in \mathcal{O}, \ t > 0; \\ u(0,\xi) &= u_0(\xi) \quad \xi \in \mathcal{O}; \\ u(t,\xi) &= u(t,\xi) = 0, \quad t \ge 0, \ \xi \in \partial\mathcal{O}; \end{cases}$$

where $u_0 \in L^p(\mathcal{O})$, $p \ge 1$, g a certain mapping and L(t) is a space time Lévy noise specified later.

Problem: To find an approximation of

$$u: [0,\infty) \times \mathcal{O} \longrightarrow \mathbb{R}$$

solving Equation (\star) .

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A Lévy Process

Definition

Let *E* be a Banach space. An *E*-valued stochastic process $L = \{L(t), 0 \le t < \infty\}$ is a Lévy process over $(\Omega; \mathcal{F}; \mathbb{P})$ iff

• L(0) = 0;

- L has independent and stationary increments;
- L is stochastically continuous, i.e. for any A ∈ B(E) the function t → El_A(L(t)) is continuous on R⁺;
- L has a.s. càdlàg ^a paths;

acàdlàg = continue à droite, limitée à gauche.

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Lévy - Khinchin - Formula

E denotes a separable Banach space and E' the dual on E. If L is an E-valued Lévy process, then there exist

- a ∈ E',
- $Q: E' \to E$ is a positive operator,
- and ν : B(E) → ℝ⁺ is a Lévy measure (called usually the characteristic measure of L).

such that following formula holds for all $y \in E'$

$$\mathbb{E} e^{i\langle L(1), y \rangle} = \exp\left\{i\langle a, y \rangle \lambda - \frac{1}{2}\langle Qy, y \rangle + \int_{E} \left(e^{i\lambda\langle y, a \rangle} - 1 - i\lambda y \mathbf{1}_{\{|y| \le 1\}}\right)\nu(dy)\right\}.$$

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A Lévy Process

In what follows *E* denotes a separable Banach space, $\mathcal{B}(E)$ denotes the Borel- σ algebra on *E* and *E'* the dual on *E*.

Definition

(see Linde (1986), Section 5.4) A symmetric^{*a*} σ -finite, Borel-measure $\nu : \mathcal{B}(E) \to \mathbb{R}^+$ is called a Lévy measure if $\nu(\{0\}) = 0$ and the function

$$E'
i a \mapsto \exp\left(\int_E (\cos(\langle x, a
angle) - 1) \,
u(dx)
ight) \in \mathbb{C}$$

is a characteristic function of a certain Radon measure on E.

 ${}^{a}
u(A) =
u(-A)$ for all $A \in \mathcal{B}(E)$

An arbitrary σ -finite Borel measure ν is a Lèvy measure if its symmetrization $\nu + \nu^-$ is a symmetric Lévy measure.

Remark Let *L* be a Lévy process over $(\Omega, \mathcal{F}, \mathbb{P})$. Defining the so-called counting measure for $A \in \mathcal{B}(E)$

$$\mathsf{N}(t, \mathcal{A}) = \sharp \{ s \in (0, t] : \Delta L(s) = L(s) - L(s-) \in \mathcal{A} \} \in \mathbb{N} \cup \{\infty\}$$

one can show that

- N(t, A) is a random variable over $(\Omega; \mathcal{F}; \mathbb{P})$;
- $N(t,A) \sim \text{Poisson}(t\nu(A)) \text{ and } N(t,\emptyset) = 0;$
- For any disjoint sets A₁,..., A_n, the random variables N(t, A₁),..., N(t, A_n) are independent; (independently scattered)

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Definition

Let (Z, \mathcal{Z}) be a measurable space and $(\Omega, \mathcal{A}, \mathbb{P})$ a probability space. A Poisson random measure on (Z, \mathcal{Z}) is a family

$$\eta = \{\eta(\omega, \centerdot), \omega \in \Omega\}$$

of non-negative integer valued measures $\eta(\omega, \centerdot): \mathcal{S} \to \mathbb{N}$, such that

- $\eta(\mathbf{.}, \emptyset) = 0$ a.s.
- η is a.s. σ -additive.
- η is a.s. independently scattered.
- for each $A \in \mathbb{Z}$ such that $\mathbb{E} \eta(\cdot, A)$ is finite, $\eta(\cdot, A)$ is a Poisson random variable with parameter $\mathbb{E} \eta(\cdot, A)$.

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Let (S, S) be a measurable space and $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \ge 0}, \mathbb{P})$ be a probability space. Definition

(see Ikeda Watanabe - 1981) A time homogeneous Poisson random measure η on (S, S) over $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \ge 0}, \mathbb{P})$, is a measurable function

$$\eta: (\Omega, \mathcal{F}) \to (M_I(S \times \mathbb{R}_+), \mathcal{M}_I(S \times \mathbb{R}_+)),$$

such that

- (i) for each $B \in S \otimes \mathcal{B}(\mathbb{R}_+)$, $\eta(B) := i_B \circ \eta : \Omega \to \overline{\mathbb{N}}$ is a Poisson random variable with parameter^a $\mathbb{E}\eta(B)$;
- (ii) η is independently scattered;
- (iii) for each $U \in S$, the $\mathbb{\bar{N}}$ -valued process $(N(t, U))_{t \ge 0}$ defined by $N(t, U) := \eta(U \times (0, t]), t \ge 0$

is $\{\mathcal{F}_t\}_{t\geq 0}$ -adapted and its increments are independent of the past, i.e. if $t > s \geq 0$, then $N(t, U) - N(s, U) = \eta(U \times (s, t])$ is independent of \mathcal{F}_s .

^aIf $\mathbb{E}\eta(B) = \infty$, then obviously $\eta(B) = \infty$ a.s..

Example

Let η be a time homogeneous Poisson random measure on *E* with intensity ν , where ν is a Lévy measure. Then, the stochastic process

$$[0,\infty)
i t \mapsto \hat{L}(t) := \int_0^t \int_E z \, \tilde{\eta}^s(ds,dt)$$

is a Lévy process with characteristic measure ν .

^aGive a Poisson random measure $\eta : \mathcal{B}(E) \times \mathcal{B}([0,\infty)) \to \mathbb{N}_0$ we denote the compensated Poisson random measure by $\tilde{\eta}$.

Definition

Let

$$\eta:\Omega\times\mathcal{B}(E)\times\mathcal{B}(\mathbb{R}^+)\to\mathbb{R}^+$$

be a Poisson random measure on E over $(\Omega; \mathcal{F}; \mathbb{P})$ and $\{\mathcal{F}_t, 0 \leq t < \infty\}$ the filtration induced by η . Then the predictable measure

$$\gamma: \Omega \times \mathcal{B}(E) \times \mathcal{B}(\mathbb{R}^+) \to \mathbb{R}^+$$

is called compensator of η , if for any $A \in \mathcal{B}(E)$ the process

$$\widetilde{\eta}(A imes (0,t]) := \eta(A imes (0,t]) - \gamma(A imes [0,t])$$

is a local martingale over $(\Omega; \mathcal{F}; \mathbb{P})$.

Remark The compensator is unique up to a \mathbb{P} -zero set and in case of a time homogeneous Poisson random measure given by

$$\gamma(A \times [0, t]) = t \ \nu(A), \quad A \in \mathcal{B}(E).$$

Space - Time - White - Noise

Let us recall the Definition of a Gaussian white noise (Dalang 2003):

Definition

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space and (S, S, σ) a measure space. Then a Gaussian white noise on S based on σ is a measurable mapping

$$W:(\Omega,\mathcal{F})\to (M(E),\mathcal{M}(E))^a$$

- For A ∈ S, W(A) is a real valued Gaussian random variable with mean 0 and variance σ(A), provided σ(A) < ∞;
- if A and $B \in S$ are disjoint, then the random variables W(A) and W(B) are independent and $W(A \cup B) = W(A) + W(B)$.

^aM(S) denotes the set of all measures from S into \mathbb{R} , i.e. $M(S) := \{\mu : S \to \mathbb{R}\}$ and $\mathcal{M}(S)$ is the σ -field on M(S) generated by functions $i_B : M(S) \ni \mu \mapsto \mu(B) \in \mathbb{R}, \ B \in S.$

Space - Time - White - Noise

Put

- $\mathcal{O} \subset \mathbb{R}^d$ be a bounded domain with smooth boundary.
- $S = \mathcal{O} \times [0, \infty)$,

•
$$\mathcal{S} = \mathcal{B}(\mathcal{O}) \times \mathcal{B}([0,\infty))$$

•
$$\sigma = \lambda_{d+1}^{1}$$
.

Then, by definition, the space time Gaussian white noise is the measure valued process process

$$t\mapsto W(\cdot \times [0,t)).$$

 $^{1}\lambda_{d+1}$ denotes the Lebesgue measure in \mathbb{R}^{d} .

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Space - Time - White - Noise

Definition

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space and let (S, S, σ) be a measurable space. Then the Lévy white noise on S based on σ with characteristic jump size measure $\nu \in \mathcal{L}(\mathbb{R})$ is a measurable mapping

$$L: (\Omega, \mathcal{F}) \to (M(S), \mathcal{M}(S))^a$$

such that

 For A ∈ S, L(A) is a real valued infinite divisible random variables with characteristic exponent

$$e^{i\theta L(A)} = \exp\left(\sigma(A) \int_{\mathbb{R}} \left(1 - e^{i\theta x} - i\sin(\theta x)\right) \nu(dx)\right),$$

provided $\sigma(A) < \infty$.

if A and B ∈ S are disjoint, then the random variables L(A) and L(B) are independent and L(A ∪ B) = L(A) + L(B).

 ${}^{s}M(E)$ denotes the set of all measures from \mathcal{E} into \mathbb{R} , i.e. $M(S) := \{\mu : S \to \mathbb{R}\}$ and $\mathcal{M}(S)$ is the σ -field on M(S) generated by functions $i_{B} : M(S) \ni \mu \mapsto \mu(B) \in \mathbb{R}, B \in S$.

Space - Time - White - Noise

Again put

- $\mathcal{O} \subset \mathbb{R}^d$ be a bounded domain with smooth boundary.
- $S = \mathcal{O} \times [0,\infty)$,
- $\mathcal{S} = \mathcal{B}(\mathcal{O}) \times \mathcal{B}([0,\infty))$
- $\sigma = \lambda_{d+1}$.

Then, by definition, the space time Lévy white noise is the measure valued process process

$$t\mapsto L(\cdot \times [0,t));$$

(for more details we refer to Breźniak and Hausenblas (2009) or Peszat and Zabczyk (2007))

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The Numerical Approximation

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The Numerical Approximation of a Lévy walk

Let μ be a Poisson random measure on \mathbb{R} with intensity ν , i.e. let $L = \{L(t) : 0 \le t < \infty\}$ be the corresponding Lévy process with characteristic measure ν defined by

$$[0,\infty)
i t \mapsto L(t) := \int_0^t \int_{\mathbb{R}} z \, \widetilde{\mu}(dz,ds) \in \mathbb{R}.$$

Question:

Given the characteristic measure of a Lévy process, how to simulate the Lévy walk ?

That means, how to simulate

$$\left(\Delta_{\tau}^{0}L,\Delta_{\tau}^{1}L,\Delta_{\tau}^{2}L,\ldots,\Delta_{\tau}^{k}L,\ldots\right),$$

where

$$\Delta^k_ au L := L((k+1) au) - L(k au), \quad k \in \mathbb{N}.$$

The Numerical Approximation of a Lévy walk

Different approaches:

- Direct generation: in case of stable, exponential, gamma, geometric and negative binomial distribution.
- Generation from compound Poisson Process (Rubenthaler (2003), Amussen and Rósinski, Fornier (2010))
- generation with shot noise representation (Bondesson (1980), Rosinski (2001), Kawai and Imai (2007))
- Approximation of the density function by series (Eberlein, ...)
- Via Fouriertransform (Taqqu ...)

The Numerical Approximation of a Lévy walk

Generation with shot noise representation

Assume U is a random variable on [0, T] the Lévy measure can be written as

$$u(B) = \int_0^\infty \mathbb{P}(H(r, U) \in B) dr, \quad B \in \mathcal{B}(\mathbb{R}).$$

• $\{E_k : k \in \mathbb{N}\}$ sequence of iid exponential random variables with unit mean;

- { $\Gamma_k : k \in \mathbb{N}$ } sequence of standard Poisson arrivials time, in particular { $\Gamma_k \Gamma_{k-1} : k \in \mathbb{N}$ } are exponential distributed with certain parameter;
 - $\{U_k: k \in \mathbb{N}\}$ sequence of iid uniform distributed random variables on [0,1]

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The Numerical Approximation

- Cutting off the small jumps;
- Approximating the characteristic measure by a discrete measure;
- Generating a random variable $\hat{\Delta}_{\tau}^{k} L_{\epsilon}$ which approximates $\Delta_{\tau}^{k} L_{\epsilon}$;
- Approximating the small jumps by a Wiener process (optional);

The Numerical Approximation

- Cutting off the small jumps;
- Approximating the characteristic measure by a discrete measure;
- Generating a random variable $\hat{\Delta}_{\tau}^{k} L_{\epsilon}$ which approximates $\Delta_{\tau}^{k} L_{\epsilon}$;
- Approximating the small jumps by a Wiener process (optional);

Cutting off the small jumps

- fix a cut off parameter $\epsilon > 0$;
- define the new characteristic measure

$$u^{\epsilon\epsilon}: \mathcal{B}(\mathbb{R}) \ni B \mapsto \nu\left(B \cap \left((-\infty, -\epsilon] \cup [\epsilon, \infty)\right)\right).$$

Let μ^{cε} be a Poisson random measure corresponding where the supports does not include [-ε, ε], i.e.

$$\mu^{c\epsilon}: \mathcal{B}(\mathbb{R}) \times \mathcal{B}(\mathbb{R}^+) \ni B \times I \mapsto \int_{(-\infty, -\epsilon] \cup [\epsilon, \infty)} \int_I 1_B(z) \, \mu(dz, dt) \in \mathbb{N} \cup \{\infty\}.$$

 Let L_ε = {L(t) : 0 ≤ t < ∞} the Lévy process which arises by cutting off the small jumps, i.e.

$$L_{\epsilon}(t):=\int_{0}^{t}\int_{\mathbb{R}}\zeta\, ilde{\mu}^{c\epsilon}(d\zeta,ds),\quad t\geq 0.$$

The Numerical Approximation

- Cutting off the small jumps;
- Approximating the characteristic measure by a discrete measure;
- Generating a random variable $\hat{\Delta}_{\tau}^{k} L_{\epsilon}$ which approximates $\Delta_{\tau}^{k} L_{\epsilon}$;
- Approximating the small jumps by a Wiener process (optional);

Approximating the characteristic measure by a discrete measure

Approximate the characteristic measure $\nu^{c\epsilon}$ by a characteristic measure $\hat{\nu}^{c\epsilon}$ having the following form:

- Let B_1, \ldots, B_J be disjoint sets with $\cup_{j=1}^J B_j \subset (-\infty, -\epsilon] \cup [\epsilon, \infty);$
- let c_1, \dots, c_J be points belonging to \mathbb{R} such that $c_j \in D_j$, $j = 1 \dots J$;
- $\nu^{c\epsilon}$ can be written as

$$\hat{\nu}^{c\epsilon} := \sum_{j=1}^{J} \nu(B_j) \delta_{c_j}.$$

Example

- Put $B_j = [x_j, x_{j+1}), j = 1, \dots, J/2 1, B_{J/2} = [x_{J/2}, \infty),$ $B_{J/2+j} = [-x_j, -x_{j+1}), j = 1, \dots, J/2 - 1$, such that $\nu(B_j) < \gamma$;
- Put $B_J = [-x_{J-1}, -\infty)$, where $x_0 = \epsilon < x_1 < \cdots < x_{J/2} < \infty$;
- Put $c_j := x_j$.
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The Numerical Approximation

Different Discretization:

- equally weighted mesh: Let $D_1 = [\epsilon, x_2), D_J = [x_J, \infty)$, and $D_i = [x_i, x_{i+1})$ such that $\nu(D_i) = \nu(D_j)$ for $1 \le i, j \le J \sim O(\epsilon^{-1})$.
- equally spaced mesh: Let $D_1 = [\epsilon, x_2), D_J = [x_J, \infty)$, and $D_i = [x_i, x_{i+1})$ such that $\lambda(D_i) = \lambda(D_j)$ for $1 \le i, j \le J \sim O(\epsilon^{-1})$.
- strechted mesh: Let $D_1 = [\epsilon^2, x_2), D_J = [x_J, \infty)$, and choose $\epsilon_j := \lambda(D_j)$ according to

$$\epsilon_j := \begin{cases} j\epsilon^2 & \text{if } x_j < 1, \\ j^\gamma \epsilon & \text{if } x_j \ge 1, \end{cases}$$

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for some $0 < \gamma < 1$. (Here, one can fit 2 and γ according to α and β)

The Numerical Approximation

- Cutting off the small jumps;
- Approximating the characteristic measure by a discrete measure;
- Generating a random variable $\hat{\Delta}_{\tau}^{k} L_{\epsilon}$ which approximates $\Delta_{\tau}^{k} L_{\epsilon}$;
- Approximating the small jumps by a Wiener process (optional);

Generating a random variable

 $\hat{\Delta}_{\tau}^{k} L_{\epsilon}$

Remember

• (Independently scattered property)

The family

$$\{\eta (D_j \times [t_{k-1}, t_k)) : j = 1, \ldots, n, k = 1, \ldots, K\}$$

of random variables over $(\Omega, \mathcal{F}, \mathbb{P})$ is mutually independent;

• for any $D \times I \in \{D_j \times [t_{k-1}, t_k) : j = 1, \dots, n, k = 1, \dots, K\}$ the random variable

 $\eta(D \times I)$

is Poisson distributed with Parameter $\nu(D) \cdot \lambda(I)$.

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Generating a random variable

 $\hat{\Delta}_{\tau}^{k}L_{\epsilon}$ At each time step k generate a family $\{q_{k}^{1},\ldots,q_{k}^{J}\}$ of independent random variables, where

$$\mathbb{P}\left(\mathsf{q}_{k}^{j}=l\right)=\exp(-\tau\nu(B_{j}))\frac{\tau^{\prime}\nu(B_{j})^{\prime}}{l!},\quad l\geq0.$$

The approximation $\hat{\Delta}_{\tau}^{k}L$ will be given as follows.

$$\hat{\Delta}^k_{\tau} L_{\epsilon} := \sum_{j=1}^J \left(\mathsf{q}^j_k - \tau \nu(B_j) \right) c_j, \quad k \ge 0.$$

The Lévy random walk is approximated by

$$\left(\hat{\Delta}_{\tau}^{0}L_{\epsilon},\hat{\Delta}_{\tau}^{1}L_{\epsilon},\hat{\Delta}_{\tau}^{2}L_{\epsilon},\ldots,\hat{\Delta}_{\tau}^{k}L_{\epsilon},\ldots\right),$$

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Open Question

At each time step $k \ge 1$ is it sufficient to simulate a family $\{q_k^1, \dots, q_k^J\}$ of independent random variables, where

$$\mathbb{P}\left(\mathsf{q}_{k}^{j}=\mathsf{0}
ight)=\exp(- au
u(B_{j})) \hspace{1em} j=1,\ldots,k$$

and

$$\mathbb{P}\left(\mathsf{q}_{k}^{j}=1
ight)=1-\exp(- au
u(B_{j})) \hspace{1em} j=1,\ldots,k.$$

The approximation is now given as follows.

$$\hat{\Delta}^k_{ au} L_\epsilon := \sum_{j=1}^J \left(\mathsf{q}^j_k - au
u(B_j)
ight) c_j, \quad k \geq 0.$$

The Lévy random walk is approximated by

$$\left(\hat{\Delta}_{\tau}^{0}L_{\epsilon},\hat{\Delta}_{\tau}^{1}L_{\epsilon},\hat{\Delta}_{\tau}^{2}L_{\epsilon},\ldots,\hat{\Delta}_{\tau}^{k}L_{\epsilon},\ldots\right),$$

Simulation des Lévy walks







Simulation des Lévy walks





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SPDES driven by Poisson Random Measures

Approximating the small jumps (optional);

At each time step k generate a Gaussian random variables $\Delta_{\tau}^{k}W$, where

$$\mathcal{L}(\Delta_{\tau}^{k}W_{\epsilon}) = \sigma(\epsilon) \mathcal{N}(0,\tau)$$

and

$$\sigma(\epsilon) := \sqrt{\int_{-\epsilon}^{\epsilon} \zeta^2 \nu(d\zeta)}.$$

The Lévy random walk is approximated by

$$\left(\hat{\Delta}^0_{ au} L_{\epsilon} + \Delta^0_{ au} W_{\epsilon}, \hat{\Delta}^1_{ au} L_{\epsilon} + \Delta^1_{ au} W_{\epsilon}, \hat{\Delta}^2_{ au} L_{\epsilon} + \Delta^2_{ au} W_{\epsilon}, \ldots, \hat{\Delta}^k_{ au} L_{\epsilon} + \Delta^k_{ au} W_{\epsilon}, \ldots
ight)$$

The Numerical Approximation

Proposition Assume, that the intensity is of type α , $\alpha \in (0, 2]$. Then,

$$\mathbb{E}\left|\Delta_{\tau}^{k}L_{\epsilon}^{c}-\Delta_{\tau}^{k}W_{\epsilon}\right|^{p}\leq C\ \tau^{\frac{p}{3}}\ \epsilon^{\frac{p(3-\alpha)}{3}},\quad \epsilon>0\ \tau>0,$$

where $\Delta_{\tau}^{k} L_{\epsilon}^{c} := \Delta_{\tau}^{k} L - \Delta_{\tau}^{k} L_{\epsilon}$. If, in addition, $\tau = \epsilon^{\rho}$, then

$$\mathbb{E}\left|\Delta_{\tau}^{k} \mathcal{L}_{\epsilon}^{c} - \Delta_{\tau}^{k} W_{\epsilon}\right|^{p} \leq C \ \tau \epsilon^{\frac{p}{3}(3-\alpha+\rho(1-\frac{3}{p})}, \quad \epsilon > 0 \ \tau > 0.$$

The proof is via the Fourier transform, tail estimates and Taylor approximations.

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The Approximation of a space time Lévy noise

Let \mathcal{O} be a bounded domain and let \mathcal{T} be a subdivision with

- a set of element domains $\mathcal{K} = \{K_i : i = 1 \dots, l\},\$
- a set of nodals variable $\mathcal{N} = \{N_i, i = 1..., I\}$ and
- a set of space functions $\mathcal{P} = \{\phi_i : i = 1, \dots, l\}$
- a Voronoi decomposition $\mathcal{J} = \{J_i; i = 1, \dots, l\}$ induced by \mathcal{N}

Let $\mathbf{L} = \{L^i : i = 1, \dots, l\}$ be a family of independent Lévy processes where L^{i} has characteristic $\rho_{i} \nu, \rho_{i} = \lambda(J_{i}), i = 1, \dots, I$. The measure valued process $\tilde{\mathbf{L}} = \{\tilde{\mathbf{L}}(t) : t \geq 0\}$ given by

$$ilde{\mathsf{L}}(t):\mathcal{B}(\mathcal{O})
i A\mapsto \sum_{i=1}^N c_i\,\int_A\phi_i(x)\,dx\,L^i(t),\quad t\ge 0,$$

where $c_i = (|\phi_i|_{l^1}^{-1})$, is an approximation in space of the space time Lévy noise.

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Space - Time - Poissonian Noise



The Equation to Approximate

Let $\mathcal{O} = [0, 1] \times [0, 1]$. The Equation:

$$(\star) \quad \begin{cases} \frac{du(t,\xi)}{dt} &= \frac{\partial^2}{\partial\xi^2}u(t,\xi) + \alpha \nabla u(t,\xi) + g(u(t,\xi))\dot{L}(t) \\ &+ f(u(t,\xi)), \quad \xi \in \mathcal{O}, \ t > 0; \\ u(0,\xi) &= u_0(\xi) \quad \xi \in \mathcal{O}; \\ u(t,\xi) &= u(t,\xi) = 0, \quad t \ge 0, \ \xi \in \partial\mathcal{O}; \end{cases}$$

where $u_0 \in L^p(0,1)$, $p \ge 1$, g a certain mapping and L(t) is a Lévy process taking values in a certain Banach space.

Problem: To find a function

$$u: \mathbb{R}_+ \times \mathcal{O} \longrightarrow \mathbb{R}$$

solving Equation (\star) .

Numeric of SPDEs

The implicit Euler scheme. Here

$$rac{u_n(t+ au_n)-u_n(t)}{ au_n}pprox Au_n(t+ au_n) \ f(u_n(t))+g(u_n(t))\Delta_nL(t),$$

Again, if v_n^k denotes the approximation of $u_n(k\tau_n)$, then

$$\begin{cases} v_n^{k+1} = (1 - \tau_n A_n)^{-1} v_n^k + \tau_n f(v_n^k) \\ & + \sqrt{\tau_n} g(u_n(t)) \xi_k^n, \\ v_n^0 = x. \end{cases}$$

Between the points $k\tau_n$ and $(k+1)\tau_n$ the solution is linear interpolated.

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Numerical Analysis

Theorem

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(E.H. 2008)

• Let $u = \{u(t); 0 \le t < \infty\}$ be the mild solution of an SPDE wit space time Lévy noise

- Let $\hat{u} = \{\hat{u}_k, k \in \mathbb{N}\}$ be the approximation of u
 - Discretization in space: affine finite Elements with length h;

• Discretization in time: implicit Euler scheme with time step τ_h . Then, the error is given by

$$\left[\mathbb{E} \left\| u(k\tau_h) - \hat{u}_h^k \right\|_{L^p(\mathcal{O})}^p\right]^{\frac{1}{p}} \leq C_0 \tau^{\alpha} + C_1 h^{\delta}.$$

Here $\alpha < \frac{2}{p} - d + \frac{d}{p}$ and $\delta < \left(2 + \frac{d}{2} - \frac{d}{p}\right) \left(\frac{2}{p} - d + \frac{d}{p}\right).$

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The Numerical Approximation

Assume in addition that the space time Lévy white noise is approximated as described before. Then The following holds.

• For any $M \in \mathbb{N}$ there exist constants C_1 and C_2 such that

$$\begin{split} \sup_{0\leq m\leq M} \mathbb{E} \|v_h^m - \hat{v}_{\epsilon_h}^m\|_{L^p(\mathcal{O})}^p &\leq C_1 \epsilon_h^{p-\alpha} \\ &+ C_2 \int_{\zeta\in \mathbb{R}\setminus (-\epsilon_h,\epsilon_h)} |\zeta|^p d(\hat{\nu}^{\epsilon_h} - \nu^{\epsilon_h}) (d\zeta). \end{split}$$

• If the stability condition (*) is satisfied, then there exist constants C_1 and C_2 such that for any $\theta > 0$, and ϵ_h with $\epsilon_h \sim \tau_h^{\theta}$,

$$\begin{split} \sup_{0 \le m \le M} \mathbb{E} \, \left\| v_h^m - \hat{v}_{h,\epsilon}^{w,m} \right\|_{L^p(\mathcal{O})}^p \le C_1 \, \tau_h^{\frac{p}{3}} \, \epsilon_h^{\frac{p(3-\alpha)}{3}} \\ &+ C_2 \int_{\zeta \in \mathbb{R} \setminus (-\epsilon_h,\epsilon_h)} |\zeta|^p d(\hat{\nu}^{c,\epsilon_h} - \nu^{\epsilon_h}) (d\zeta). \end{split}$$