Breaking the chain

Michael Allman

Mathematics Institute University of Warwick Coventry, UK

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PhD supervisor: Volker Betz (Warwick)

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Let $\mathbf{x}(s) = (x_0(s), x_1(s), \dots, x_N(s))$ be the positions of N + 1 particles in \mathbb{R} at time *s*, evolving according to

$$\mathrm{d} x_i(s) = -\frac{\partial H}{\partial x_i}(\mathbf{x}(s))\,\mathrm{d} s + \sigma \mathrm{d} W_i(s), \ 0 \leqslant i \leqslant N$$

where H is potential energy of the chain given by

$$H(\mathbf{x}) = \sum_{0 \leq i < j \leq N} U(x_i - x_j)$$

and U is a pair potential.

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Main properties of U:

- U has a unique minimum at a > 0
- U has finite range b > 0
- ▶ *b* < 2*a*

Initially we take the chain to be in the minimal energy configuration:

$$\mathbf{x}(0) = (0, a, 2a, \dots, Na)$$

We would like to slowly stretch the chain of particles: Fix $x_0 \equiv 0$ and let $x_N(s) = Na(1 + \varepsilon s)$, where $\varepsilon > 0$ is small. The other N-1 particles then evolve according to

$$\mathrm{d} x_i(s) = -\frac{\partial H}{\partial x_i}(\mathbf{x}(s), \varepsilon s) \,\mathrm{d} s + \sigma \mathrm{d} W_i(s), \ 1 \leqslant i \leqslant N-1$$

where H is now the time-dependent potential energy of the chain given by

$$H(\mathbf{x},\varepsilon s) = \sum_{0 \leq i < j \leq N-1} U(x_i - x_j) + \sum_{0 \leq i \leq N-1} U(x_i - Na(1 + \varepsilon s))$$

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As the chain is stretched, new minimal energy configurations will become possible.

We consider the chain to break when its configuration enters a small neighbourhood of one of these new minima.

We define the break location by which of the new minima is reached first.

General goal: Writing $\varepsilon = \varepsilon(\sigma)$, to identify how different speeds of stretching affect the break location, as $\sigma \downarrow 0$.

Take N = 3 so that $\mathbf{x}(s) = (0, x_s, 2a(1 + \varepsilon s))$. Only the middle particle is free. It satisfies a one-dimensional non-autonomous SDE

$$\mathrm{d} x_{s} = -\frac{\partial H}{\partial x}(x_{s},\varepsilon s)\mathrm{d} s + \sigma\mathrm{d} W_{s}$$

with initial condition $x_0 = a$ and time-dependent potential energy given by

$$H(x,\varepsilon s) = U(x) + U(2a(1+\varepsilon s) - x)$$

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We rescale time as $t = \varepsilon s$, so that $\mathbf{x}(t) = (0, x_t, 2a(1+t))$ and x_t solves

$$\mathrm{d} x_t = -\frac{1}{\varepsilon} \frac{\partial H}{\partial x} (x_t, t) \mathrm{d} t + \frac{\sigma}{\sqrt{\varepsilon}} \mathrm{d} W_t$$

We say the chain breaks as soon as the middle particle is a distance b from one of its neighbours.

So the chain is unbroken at time t if

$$x_t < b$$
 and $2a(1+t) - x_t < b$

which combine to give

 $2a(1+t) - b < x_t < b$

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Let

$$\tau = \inf\{t \ge 0 : x_t \notin (2a(1+t) - b, b)\}$$

This is the time that the chain breaks. Clearly,

 $\tau \leqslant b/a - 1$

so the chain breaks in finite time. The chain breaks on the left-hand side if $x_{\tau} = b$. Otherwise, it breaks on the right-hand side.

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Recall that our potential U has unique minimum at a > 0 and finite range b > 0, where b < 2a. In addition, we will assume: There exists $a_0 \in (0, a)$ such that $U''(y) \ge u_0 > 0$ for all $y \in (a_0, b)$.

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An example of such a potential is a cut-off quadratic given by

$$U(y) = \begin{cases} (|y| - a)^2 - (b - a)^2 & 0 \leq |y| \leq b \\ 0 & \text{otherwise} \end{cases}$$

where b < 2a, shown below for a = 2, b = 3.



The potential energy H(x, t) = U(x) + U(2a(1 + t) - x) when t = 0



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Notation: $f(\sigma) \ll g(\sigma)$ means $f(\sigma)/g(\sigma) \to 0$ as $\sigma \downarrow 0$. Theorem (A.,Betz)

1. Fast Stretching If

$$\sigma |\ln \sigma|^{1/2} \ll \varepsilon(\sigma) \ll 1$$

then $\mathbb{P}\{x_{\tau} = b\} \rightarrow 0 \text{ as } \sigma \downarrow 0.$

2. Slow Stretching

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$$\frac{1}{\sigma^{2/3}} \exp\left\{-\frac{1}{\sigma^{2/3}}\right\} \ll \varepsilon(\sigma) \ll \sigma |\ln \sigma|^{-1/2}$$

then $\mathbb{P}\{x_{\tau} = b\} \rightarrow 1/2 \text{ as } \sigma \downarrow 0.$

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In the slow stretching case, we expect the result to hold without the lower bound on $\varepsilon,$ i.e. for all

$\varepsilon \ll \sigma |\ln \sigma|^{-1/2}$

Indeed, when U is quadratic, this is true. The lower bound is related to the theory of large deviations. Let x_t^{det} be solution when $\sigma = 0$,

$$\frac{\mathrm{d}}{\mathrm{d}t} x_t^{\mathsf{det}} = -\frac{1}{\varepsilon} \frac{\partial H}{\partial x} (x_t^{\mathsf{det}}, t)$$

with $x_0^{det} = a$. A particular solution is given by

$$x_t^{\mathsf{det}} = a(1+t) - rac{arepsilon a}{2U''(a(1+t))} + \mathcal{O}(arepsilon^2)$$

This shows x_t^{det} lags behind the midpoint of the chain at distance $\mathcal{O}(\varepsilon)$. So the deterministic chain always breaks on the right-hand side.

We expect x_t to stay close to x_t^{det} . Let

$$y_t = x_t - x_t^{\text{det}}$$

For the chain to be unbroken, we require

$$2a(1+t) - b < x_t < b$$

which is the same as

$$2a(1+t) - b - x_t^{\mathsf{det}} < y_t < b - x_t^{\mathsf{det}}$$

Using our expression for x_t^{det} , this gives

 $a(1+t) - b + \mathcal{O}(\varepsilon) < y_t < b - a(1+t) + \mathcal{O}(\varepsilon)$

where the $\mathcal{O}(\varepsilon)$ terms are both the same and are uniform in t.

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Then the breaking time, τ , can be expressed in terms of y_t :

$$\tau = \inf\{t \geqslant 0 : y_t \notin (d_-(t), d_+(t))\}$$

where

$$d_+(t) = b - x_t^{\mathsf{det}} = b - a(1+t) + \mathcal{O}(arepsilon)$$

and

$$d_{-}(t) = 2a(1+t) - b - x_t^{\mathsf{det}} = a(1+t) - b + \mathcal{O}(\varepsilon)$$

Now, the chain breaks on the left-hand side if $y_{\tau} = d_{+}(\tau)$.

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We would like to show that y_t never gets too big. The following lemma is based on a result by Berglund and Gentz.

Lemma Let $\sigma \ll D(\sigma) \ll 1$ be such that

$$rac{D^2}{\sigma^2}\exp\left\{-rac{D^2}{\sigma^2}
ight\}\llarepsilon(\sigma)\ll 1$$

Then

$$\lim_{\sigma \downarrow 0} \mathbb{P} \left\{ \sup_{0 \leqslant t \leqslant \tau} |y_t| \ge D \right\} = 0$$

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The lower bound on ε is related to the Eyring-Kramers time. An excursion of size D corresponds to climbing a potential height of $\mathcal{O}(D^2)$, which we expect to occur as soon as t/ε is of order e^{D^2/σ^2} .

Fast Stretching

When $\sigma |\ln \sigma|^{1/2} \ll \varepsilon(\sigma) \ll 1$, we can use the lemma with $D = d_+(b/a - 1)$ to show that $|y_t| < d_+(b/a - 1)$ for all $0 \leq t \leq \tau$.



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The process y_t can be written

$$y_t = y_t^0 + y_t^1$$

where y_t^0 is a centred Gaussian process with variance $\mathcal{O}(\sigma^2)$ and y_t^1 satisfies

 $|y_t^1| \leqslant C \sup_{0 \leqslant s \leqslant t} y_s^2$

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Given D such that

$$\lim_{\sigma\downarrow 0} \mathbb{P}\left\{\sup_{0\leqslant t\leqslant \tau} |y_t| \ge D\right\} = 0$$

we can assume that for all $0\leqslant t\leqslant au$,

$$y_t^0 - D^2 \leqslant y_t \leqslant y_t^0 + D^2$$

since all other cases have zero probability as $\sigma \downarrow 0$.

Then

and

$$\mathbb{P}\{y_{\tau} = d_{+}(\tau)\} \leqslant \mathbb{P}\{y_{t}^{0} + D^{2} \text{ hits } d_{+}(t) \text{ before } d_{-}(t)\}$$

$$\mathbb{P}\{y_{\tau} = d_{+}(\tau)\} \ge \mathbb{P}\{y_{t}^{0} - D^{2} \text{ hits } d_{+}(t) \text{ before } d_{-}(t)\}$$

We must show that the upper and lower bounds tend to 1/2.

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To show

$$\lim_{\sigma \downarrow 0} \mathbb{P} \{ y_t^0 - D^2 ext{ hits } d_+(t) ext{ before } d_-(t) \} = 1/2$$

we first rewrite it as

$$\lim_{\sigma \downarrow 0} \mathbb{P}\{y_t^0 \text{ hits } d_+(t) + D^2 \text{ before } d_-(t) + D^2\} = 1/2$$

We know that y_t^0 has an entirely symmetric distribution, so we first consider the stopping time given by

$$au_L = au_L(D) = \inf\{t \geqslant 0 : |y_t^0| \geqslant -d_-(t) - D^2\}$$



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We need information about the distribution of τ_L . Roughly speaking, we show that τ_L is concentrated near $b/a - 1 - \sigma$.

We then show that if

$$y_{\tau_L}^0 = -d_-(\tau_L) - D^2$$

then y_t^0 hits $d_+(t) + D^2$ soon after, by picking a suitable interval $[\tau_L, \tau_L + \Delta]$ and applying the reflection principle.

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Suppose U is piecewise linear, as below.



The potential energy H(x, t) = U(x) + U(2a(1 + t) - x) when t = 0



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When x is near the middle of the chain, it moves like free Brownian motion:

$$\mathbf{x}_t = \frac{\sigma}{\sqrt{\varepsilon}} W_t$$

with no drift term making it follow the midpoint of the chain. Recall that the chain is unbroken if x_t satifies

 $2a(1+t) - b < x_t < b$

To behave non-deterministically, x_t must diffuse with speed $\mathcal{O}(1)$. We see that $\sigma = \varepsilon^{1/2}$ is the critical scaling.

Hence, we require stronger noise to cause non-deterministic behaviour.

Next step

We want to do the same with U differentiable everywhere. Example:



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The potential energy H(x, t) = U(x) + U(2a(1 + t) - x) when t = 0



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Let

$$z_t = a(1+t) - x_t^{\mathsf{det}}$$

Assuming that there is a unique $x_0 \in (a, b)$ such that $U''(x_0) = 0$, we can show there are constants $c_1, c_2 > 0$ such that

$$z_t symp lpha egin{cases} arepsilon/(T-t) & 0\leqslant t\leqslant T-c_1arepsilon^{1/2}\ arepsilon^{1/2} & T-c_1arepsilon^{1/2}\leqslant t\leqslant T+c_2arepsilon^{1/2} \end{cases}$$

where T is the time bifurcation occurs at midpoint.

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Again we let

$$y_t = x_t - x_t^{\mathsf{det}}$$

and write it as $y_t = y_t^0 + y_t^1$. Then the variance of y_t^0 behaves like

$$\mathsf{Var}(y_t^0) symp egin{cases} & \displaystyle \delta^2/(T-t) & 0 \leqslant t \leqslant T - c_1 arepsilon^{1/2} \ & \sigma^2 arepsilon^{-1/2} & T - c_1 arepsilon^{1/2} \leqslant t \leqslant T + c_2 arepsilon^{1/2} \end{cases}$$

If the typical spreading of y_t^0 is bigger than z_t , then we expect equal chance to break on either side. Here, we require

$$\sigma \varepsilon^{-1/4} \gg \varepsilon^{1/2}$$

That is, we require $\sigma \gg \varepsilon^{3/4}$.