

# On positive solutions of semi-linear elliptic inequalities on Riemannian manifolds

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# Setup and problem statement

Let  $(M, g)$  be a connected Riemannian manifold,  $\Delta$  – the Laplace-Beltrami operator on  $M$ . In local coordinates  $x_1, \dots, x_n$  it has the form

$$\Delta = \frac{1}{D} \sum_{i,j=1}^n \partial_{x_i} (a_{ij}(x) \partial_{x_j}),$$

where  $D = \sqrt{\det(g_{ij})}$  and  $(a_{ij}) = D(g_{ij})^{-1}$ .

Consider the equation (or inequality)

$$-\Delta u + \Phi(x) u^\sigma = f \quad (\text{or } -\Delta u + \Phi(x) u^\sigma \geq f)$$

where  $\Phi, f \in C(M)$ ,  $f \geq 0$ ,  $\sigma > 0$ . Solution  $u$  should be *non-negative* and in  $C^2(M)$ .

Our goal is obtaining pointwise estimates of  $u$ .

Assume that  $\Delta$  has a positive Green function  $G(x, y)$  on  $M$ . Set  $Gf(x) = \int_M G(x, y) f(y) d\mu(y)$ .

It is known that if  $Gf$  is finite then  $\Delta(Gf) = -f$ .

## Linear case $\sigma = 1$

W. Hansen–Z.Ma 1990, AG–W.Hansen 2008: if

$$-\Delta u + \Phi(x) u \geq f \quad \text{on } M$$

where  $\Phi \geq 0$  and the function  $h = Gf$  is positive and finite, then

$$u \geq h \exp\left(-\frac{1}{h} G(h\Phi)\right).$$

This implies the lower bound for the Green function  $G_\Phi$  of  $-\Delta + \Phi$ :

$$G_\Phi(x, y) \geq G(x, y) \exp\left(-\frac{\int_M G(x, z) G(z, y) \Phi(z) d\mu(z)}{G(x, y)}\right).$$

In the case  $\Phi \leq 0$  a similar estimate under additional assumptions was obtained by N.Kalton–I.Verbitsky 1999.

# Main result

**Theorem 1** (AG–I. Verbitsky, 2015) *Let  $u \geq 0$  solve  $-\Delta u + \Phi u^\sigma \geq f$  in  $M$ . Set  $h = Gf$  and assume that  $0 < h < \infty$ . Assume also that  $G(h^\sigma \Phi)$  be well defined.*

(i) *If  $\sigma = 1$  then*

$$u \geq h \exp\left(-\frac{1}{h}G(h\Phi)\right). \quad (1)$$

(ii) *If  $\sigma > 1$  then*

$$u \geq \frac{h}{\left[1 + (\sigma - 1)\frac{1}{h}G(h^\sigma \Phi)\right]^{\frac{1}{\sigma-1}}}, \quad (2)$$

*where the expression in square brackets is necessarily positive, that is,*

$$-(\sigma - 1)G(h^\sigma \Phi) < h. \quad (3)$$

(iii) *If  $0 < \sigma < 1$  then*

$$u \geq h \left[1 - (1 - \sigma)\frac{1}{h}G(1_{\{u>0\}}h^\sigma \Phi)\right]_+^{\frac{1}{1-\sigma}}. \quad (4)$$

## Estimates with boundary condition

Let  $\Omega$  be a relatively compact domain in  $M$  with smooth boundary. Let  $G_\Omega(x, y)$  be the Green function of  $\Delta$  in  $\Omega$  with the Dirichlet boundary condition.

It suffices to prove (1)-(4) in  $\Omega$  with  $G_\Omega$  instead of  $G$  and with  $h = G_\Omega f$  instead of  $Gf$ .

Consider the following problem. Let  $h \in C^2(\Omega) \cap C(\overline{\Omega})$  be positive and superharmonic in  $\Omega$ . Set  $f := -\Delta h \geq 0$ . Assume that  $u \in C^2(\Omega) \cap C(\overline{\Omega})$ ,  $u \geq 0$ , satisfies

$$\begin{cases} -\Delta u + \Phi u^\sigma \geq f & \text{in } \Omega \\ u \geq h & \text{on } \partial\Omega \end{cases} \quad (5)$$

**Theorem 2** (i) If  $\sigma = 1$  then  $u \geq h \exp\left(-\frac{1}{h}G_\Omega(h\Phi)\right)$ .

(ii) If  $\sigma > 1$  then

$$u \geq \frac{h}{\left[1 + (\sigma - 1)\frac{1}{h}G_\Omega(h^\sigma\Phi)\right]^{\frac{1}{\sigma-1}}},$$

where necessarily  $-(\sigma - 1)G_\Omega(h^\sigma\Phi) < h$ .

(iii) If  $0 < \sigma < 1$  then  $u \geq h \left[1 - (1 - \sigma)\frac{1}{h}G_\Omega(1_{\{u>0\}}h^\sigma\Phi)\right]_+^{\frac{1}{1-\sigma}}$ .

## Approach to the proof of Theorem 2

Assume for simplicity that  $u > 0$  and  $h > 0$  in  $\bar{\Omega}$ . Assume first  $h \equiv 1$ . Then  $f = -\Delta h = 0$  and (5) becomes

$$\begin{cases} -\Delta u + \Phi u^\sigma \geq 0 & \text{in } \Omega \\ u \geq 1 & \text{on } \partial\Omega \end{cases}$$

Fix a  $C^2$  function  $\varphi$  on (a interval of)  $\mathbb{R}$  with  $\varphi' > 0$  and make the following change:

$$v = \varphi^{-1}(u).$$

By the chain rule we have

$$\Delta u = \Delta\varphi(v) = \varphi'(v)\Delta v + \varphi''(v)|\nabla v|^2,$$

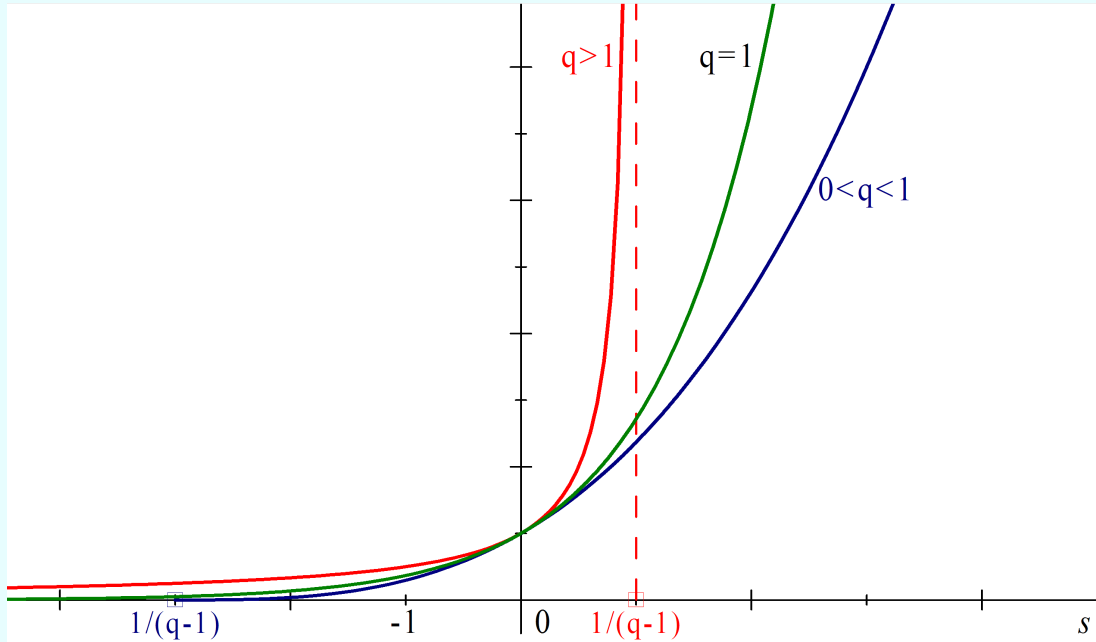
whence

$$-\Delta v = \frac{\varphi''|\nabla v|^2}{\varphi'} - \frac{\Delta u}{\varphi'} \geq \frac{\varphi''}{\varphi'}|\nabla v|^2 - \Phi \frac{\varphi(v)^\sigma}{\varphi'(v)}. \quad (6)$$

Choose  $\varphi$  to solve the following initial value problem

$$\varphi'(s) = \varphi^\sigma(s), \quad \varphi(0) = 1.$$

If  $\sigma = 1$  then  $\varphi(s) = e^s$ . If  $\sigma \neq 1$  then  $\varphi(s) = [(1 - \sigma)s + 1]^{\frac{1}{1-\sigma}}$ .



The inverse function  $\varphi^{-1}$  is always defined on  $(0, +\infty)$ .

The function  $\varphi$  is convex, and we obtain from (6)

$$-\Delta v \geq -\Phi \quad \text{in } \Omega. \quad (7)$$

Since on  $\partial\Omega$  we have  $v = \varphi^{-1}(u) \geq \varphi^{-1}(1) = 0$ , it follows that

$$v \geq -G_\Omega\Phi \quad \text{in } \Omega$$

and, hence,

$$u \geq \varphi(-G_\Omega\Phi) \quad \text{in } \Omega.$$

This yields the cases (i) – (iii) of Theorem 2 in the case  $h = 1$ .

Indeed, in the case  $\sigma = 1$  we have  $\varphi(s) = e^s$  and, hence,

$$u \geq \exp(-G_\Omega\Phi).$$

In the case  $\sigma > 1$  we have  $\varphi(s) = [(1 - \sigma)s + 1]^{-\frac{1}{\sigma-1}}$ , which gives the estimate of (ii)

$$u \geq \frac{1}{[1 + (\sigma - 1)G_\Omega\Phi]^{\frac{1}{\sigma-1}}}.$$

Similarly one treats the case  $0 < \sigma < 1$ .



For a general  $h > 0$ , we use the  $h$ -transform of  $\Delta$  in  $\Omega$ :  $\Delta^h := \frac{1}{h} \circ \Delta \circ h$ . That is,

$$\Delta^h u = \frac{1}{h} (\Delta (hu)) = \frac{1}{h} (h\Delta u + 2\nabla h \cdot \nabla h + (\Delta h)u) = \frac{1}{h^2} \operatorname{div} (h^2 \nabla u) + \frac{\Delta h}{h} u = Lu + \frac{\Delta h}{h} u$$

where

$$L = \frac{1}{h^2} \operatorname{div} (h^2 \nabla)$$

is the *weighted* Laplacian associated with measure  $d\tilde{\mu} = h^2 d\mu$ .

For function  $\tilde{u} = \frac{u}{h}$  we have

$$-\Delta^h \tilde{u} = -\frac{1}{h} \Delta u \geq \frac{1}{h} (-\Phi u^\sigma + f) = -h^{\sigma-1} \Phi \tilde{u}^\sigma - \frac{\Delta h}{h}.$$

Setting  $\tilde{\Phi} = h^{\sigma-1} \Phi$ , we obtain that  $\tilde{u}$  satisfies

$$-\Delta^h \tilde{u} + \tilde{\Phi} \tilde{u}^\sigma \geq -\frac{\Delta h}{h} \quad \text{in } \Omega, \quad \tilde{u} \geq 1 \quad \text{on } \partial\Omega.$$

Now we use the same approach as in the case  $h = 1$ , but for operator  $\Delta^h$  in place of  $\Delta$ .

Set  $v = \varphi^{-1}(\tilde{u}) = \varphi^{-1}(u/h)$  and compute  $\Delta^h v$  as in (6). For the part  $L = \frac{1}{h^2} \operatorname{div} (h^2 \nabla)$  of the operator  $\Delta^h$ , computation is the same as for  $\Delta$ .

The part  $\frac{\Delta h}{h}$  gives in the end an additional term so that instead of (7) we obtain

$$-\Delta^h v \geq -\tilde{\Phi} + \left( \frac{\varphi(v) - 1}{\varphi'(v)} - v \right) \frac{\Delta h}{h}.$$

Multiplying by  $h$ , we obtain

$$-\Delta(hv) \geq -h^\sigma \Phi + \left( \frac{\varphi(v) - 1}{\varphi'(v)} - v \right) \Delta h. \quad (8)$$

The convexity of  $\varphi$  implies

$$\frac{\varphi(s) - 1}{\varphi'(s)} - s \leq 0, \quad (9)$$

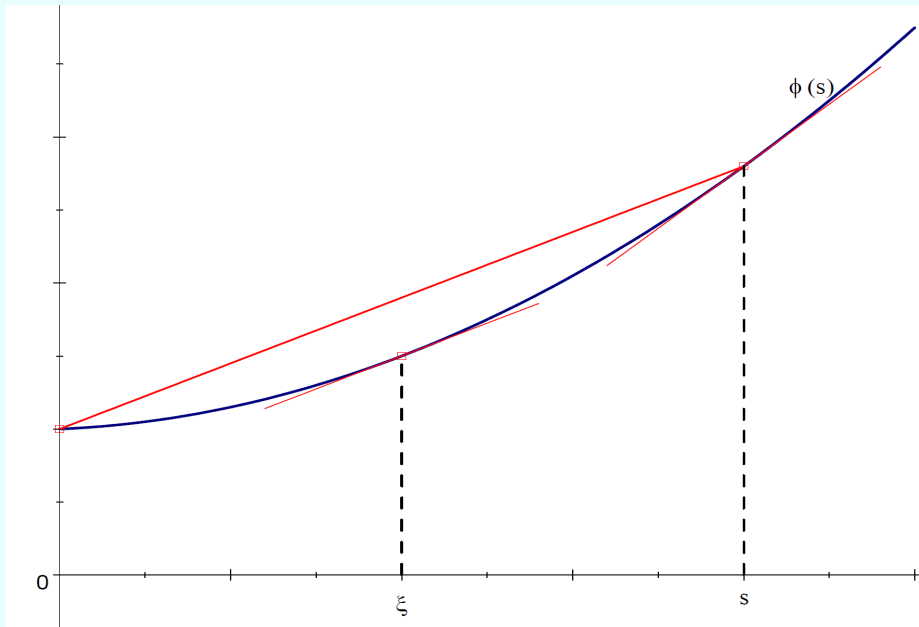
for any  $s$  in the domain of  $\varphi$ . Indeed, if  $s > 0$  then  $\exists \xi \in [0, s]$  such that

$$\varphi'(\xi) = \frac{\varphi(s) - \varphi(0)}{s}.$$

It follows that

$$\varphi'(s) \geq \varphi'(\xi) = \frac{\varphi(s) - 1}{s},$$

which yields (9).



If  $s < 0$  then  $\exists \xi \in [s, 0]$  such that

$$\frac{\varphi(s) - 1}{s} = \frac{\varphi(s) - \varphi(0)}{s} = \varphi'(\xi) \geq \varphi'(s),$$

which again implies (9) since  $s < 0$ .

Since  $\Delta h \leq 0$  and

$$\frac{\varphi(v) - 1}{\varphi'(v)} - v \leq 0,$$

we obtain

$$\left( \frac{\varphi(v) - 1}{\varphi'(v)} - v \right) \Delta h \geq 0$$

and therefore by (8)

$$-\Delta(hv) \geq -h^\sigma \Phi \quad \text{in } \Omega.$$

On  $\partial\Omega$  we have  $v = \varphi^{-1}(u/h) \geq \varphi^{-1}(1) = 0$ , which implies

$$hv \geq -G_\Omega(h^\sigma \Phi) \quad \text{in } \Omega.$$

Dividing by  $h$  and applying  $\varphi$ , we conclude that

$$\frac{u}{h} \geq \varphi \left( -\frac{1}{h} G_\Omega(h^\sigma \Phi) \right) \quad \text{in } \Omega.$$

## Existence of positive solutions

Let us ask for which values  $\sigma > 1$  the inequality

$$\Delta u + u^\sigma \leq 0 \tag{10}$$

has a positive solution  $u$  on  $M$  (the case of  $\Phi \equiv -1$ ). For example, in  $\mathbb{R}^n$  with  $n \leq 2$  any non-negative solution of (10) is 0 while in the case  $n > 2$ , the inequality (10) has a positive solution in  $\mathbb{R}^n$  if and only if

$$\sigma > \frac{n}{n-2}$$

(Mitidieri and Pohozaev, 1998). Hence,  $\sigma_{crit} = \frac{n}{n-2}$ .

Let  $d(x, y)$  be a distance function on  $M$ , not necessarily geodesic, but such that the metric balls

$$B(x, r) = \{y \in M : d(x, y) < r\}.$$

are precompact open subsets of  $M$ . Set

$$V(x, r) = \mu(B(x, r)).$$

**Theorem 3** (AG – Yuhua Sun, 2017) *Assume that, for some  $x_0 \in M$ ,*

$$V(x_0, r) \simeq r^\alpha \quad \text{for large } r \tag{V}$$

and

$$G(x, y) \simeq d(x, y)^{-\gamma} \quad \text{for large } d(x, y), \tag{G}$$

where  $\alpha > \gamma > 0$ . Then, for any  $\sigma$  satisfying

$$1 < \sigma \leq \frac{\alpha}{\gamma},$$

the inequality

$$\Delta u + u^\sigma \leq 0 \tag{11}$$

has no positive solution in any exterior domain of  $M$ .

If in addition  $d$  is the geodesic distance,  $M$  has bounded geometry, and (V) holds for all  $x_0 \in M$ , then, for any

$$\sigma > \frac{\alpha}{\gamma},$$

the inequality (11) has a positive solution on  $M$ .

Hence,  $\sigma_{crit} = \frac{\alpha}{\gamma}$ .

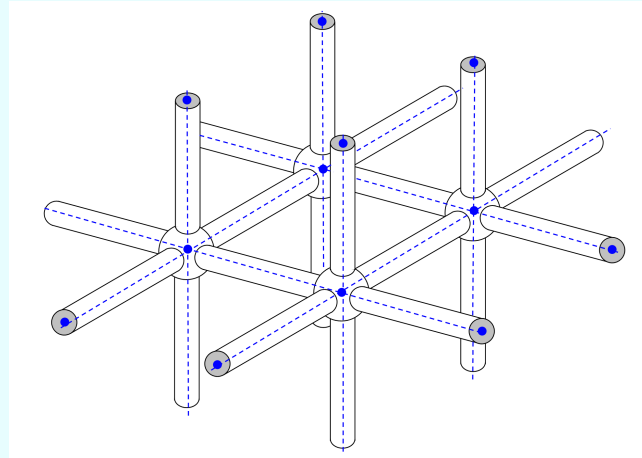
## Example 1

Let  $\Gamma$  be an infinite connected graph with a uniformly bounded degree. Let  $d(x, y)$  be the graph distance on  $\Gamma$  and  $V(x, r)$  – the volume function.

Assume that the discrete Laplace operator on  $\Gamma$  has a positive Green function  $G(x, y)$ .

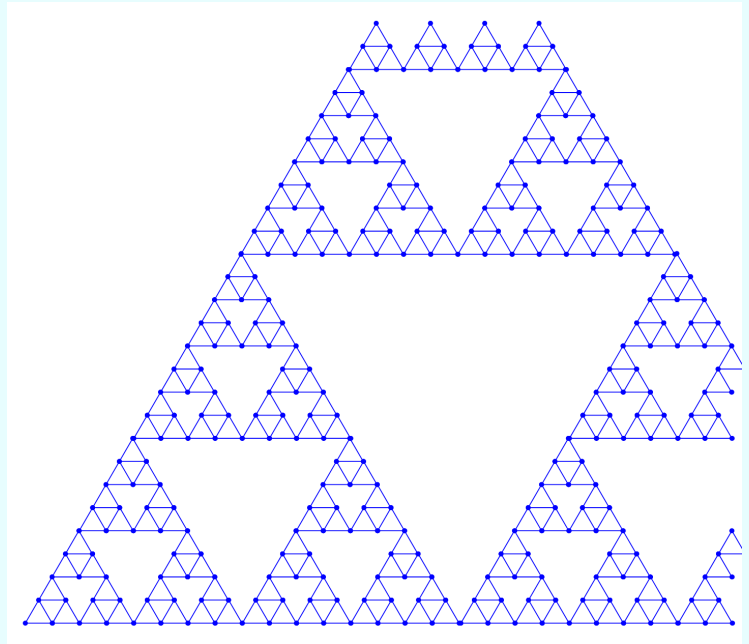
If  $\Gamma$  satisfies conditions (V) and (G) for some  $\alpha$  and  $\gamma$  then we construct a manifold  $M$  satisfying (V) and (G) inflating the edges of  $\Gamma$  into 2-dim tubes.

Since  $M$  has bounded geometry, both parts of Theorem 3 apply in this case.



M. Barlow constructed in 2004 a family of fractal-like graphs such that each graph satisfies (V) with some  $\alpha$  and has the *walk dimension*  $\beta$ , where  $\alpha, \beta$  can be any real numbers satisfying  $2 \leq \beta \leq \alpha + 1$ .

For the *graphical Sierpinski gasket* we have  $\alpha = \log_2 3$  and  $\beta = \log_2 5$  so that  $\beta > \alpha$ .



However, for higher dimensional constructions one can achieve  $\beta < \alpha$ . In this case the graph has a positive Green function satisfying (G) with  $\gamma = \alpha - \beta$ .

Since  $\gamma$  can be arbitrarily small, the critical value  $\sigma_{crit} = \frac{\alpha}{\gamma}$  can be arbitrarily large, unlike the Euclidean critical value  $\frac{n}{n-2}$ .



## Example 2

Assume that  $G(x, y)$  satisfies the following  $3G$ -inequality

$$\frac{1}{G(x, y)} \leq C \left( \frac{1}{G(x, z)} + \frac{1}{G(z, y)} \right)$$

for all  $x, y, z \in M$  and some  $C > 1$ . Then the function  $\rho(x, y) = \frac{1}{G(x, y)}$  is a quasi-metric on  $M$ . For any quasi-metric  $\rho$ , there exists  $\gamma > 0$  and a distance function  $d(x, y)$  such that  $\rho(x, y) \simeq d(x, y)^\gamma$ .

Hence,  $G(x, y) \simeq d(x, y)^{-\gamma}$ , that is,  $M$  satisfies (G). Assume that  $(M, \rho)$  satisfies (V), that is, for  $\rho$ -balls centered at  $x_0$ ,

$$\mu(B_\rho(x_0, r)) \simeq r^\alpha.$$

Then, for  $d$ -balls, we obtain

$$\mu(B_d(x_0, r)) \simeq r^{\alpha\gamma}.$$

Hence,  $(M, d)$  satisfies (V) with  $\tilde{\alpha} := \alpha\gamma$ . Assuming in addition that all balls are precompact, we obtain by Theorem 3 that, for any  $\sigma \leq \frac{\tilde{\alpha}}{\gamma} = \alpha$ , the inequality  $\Delta u + u^\sigma \leq 0$  has no positive solution in any exterior domain of  $M$ .

## Idea of the proof of Theorem 3

Assume that  $u$  is a positive solution in  $M \setminus K$  of

$$\Delta u + u^\sigma \leq 0.$$

It follows that, for any precompact open set  $U \supset K$ , we have  $u \geq G_{\overline{U}^c} u^\sigma$  in  $U^c$ .

Since  $\inf_{\partial U} u > 0$  and  $u$  is superharmonic, it follows that

$$u(y) \geq cG(y, x_0) \quad \text{for } y \in U^c,$$

for some  $c > 0$ . Hence, for any  $x \in U^c$ ,

$$u(x) \geq c^\sigma \int_{U^c} G_{\overline{U}^c}(x, y) G^\sigma(y, x_0) d\mu(y). \quad (12)$$

On the other hand, one can prove that, for any precompact open set  $\Omega \subset M$ ,

$$\sup_{\Omega} (\Delta u + \lambda_1(\Omega)u) \geq 0,$$

where  $\lambda_1(\Omega)$  is the first Dirichlet eigenvalue of  $\Delta$  in  $\Omega$ . It follows that

$$\lambda_1(\Omega) \geq \inf_{\Omega} u^{\sigma-1}. \quad (13)$$

Assuming  $\Omega \subset U^c$  and combining (13) with (12) we obtain

$$\lambda_1(\Omega)^{\frac{1}{\sigma-1}} \geq c^\sigma \inf_{x \in \Omega} \int_{U^c} G_{\overline{U}^c}(x, y) G^\sigma(y, x_0) d\mu(y).$$

If  $\sigma \leq \frac{\alpha}{\gamma}$  then we bring this inequality to contradiction by choosing  $\Omega$  large enough and by applying the hypotheses (V), (G) to estimate all the quantities involved.

For the proof of the second part of Theorem 3, we construct a positive solution of the equation

$$\Delta u + u^\sigma + \lambda^\sigma f^\sigma = 0 \quad \text{in } M,$$

where  $f$  is a specifically chosen decreasing function and  $\lambda > 0$  is small enough. This differential equation amounts to the integral equation

$$u(x) = \int_M G(x, y) (u^\sigma(y) + \lambda^\sigma f(y)^\sigma) d\mu(y),$$

and the latter is solved in a certain closed subset of  $L^\infty(M)$  by observing that the operator in the right hand side is a contraction for small enough  $\lambda$ . Next, we improve the regularity properties of  $u$  in two steps: first show that  $u$  is Hölder and then that  $u \in C^2$ .