

Hermitian Symmetric Domains

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Hermitian Symmetric Domains provide a higher-dimensional version of the upper half plane.

Hermitian Symmetric Spaces

Recall that a *smooth manifold* is a locally ringed space that is locally isomorphic to spaces of the form $(U, \mathcal{O}_U^\infty)$, where U is an open subset of \mathbb{R}^n and \mathcal{O}_U^∞ is the sheaf of smooth functions on U . Similarly, a *complex manifold* is a locally ringed space that is locally isomorphic to $(U, \mathcal{O}_U^\omega)$, where U is an open subset of \mathbb{C}^n and \mathcal{O}_U^ω is the sheaf of holomorphic functions on U .

Let's add some more structure: Given a smooth manifold M , a *Riemannian metric* on M is a positive-definite smooth contravariant 2-tensor field g on M . This means: g consists of positive-definite bilinear forms $g_p : T_p(M) \times T_p(M) \rightarrow \mathbb{R}$ for each point $p \in M$ such that for smooth vector fields X, Y on M , the function $g(X, Y) : p \mapsto g_p(X_p, Y_p)$ is smooth. In local coordinates $(x^i)_{1 \leq i \leq n}$ a Riemannian metric has the form

$$g_p = \sum_{i,j} g_{ij}(p) dx^i \otimes dx^j$$

for some symmetric positive-definite matrix $g_{ij}(p)$ that depends smoothly on p . A diffeomorphism of M is called *isometry* if it preserves the metric.

In differential geometry one uses Riemannian metrics to measure distances on a manifold M . Moreover, one can define geodesics on M , which are locally shortest paths between two points. Intuitively, geodesics are obtained by “walking in a straight line” along M .

Given a complex manifold M of dimension n , there is an underlying smooth manifold M^∞ of dimension $2n$. The complex structure on M gives each tangent space of M^∞ a complex structure $J_p : T_p(M^\infty) \rightarrow T_p(M^\infty)$, $J_p^2 = -1$. A *Hermitian metric* on M is a Riemannian metric g on M^∞ such that $g(JX, JY) = g(X, Y)$ for all vector fields X, Y . A *Hermitian manifold* is a complex manifold together with a Hermitian metric. An *isometry* of a Hermitian manifold (M, g) is a holomorphic diffeomorphism of M that is also an isometry of (M^∞, g) . The group of isometries is denoted $\text{Is}(M, g)$. It is known, that $\text{Is}(M, g)$ is a Lie group.

A manifold (smooth, complex, Hermitian, etc.) is *homogeneous*, if its automorphism group acts transitively. It “looks the same” everywhere. A *symmetry* s_p at p for $p \in M$ is an automorphism of M such that $s_p^2 = \text{id}$ and in some neighbourhood, p is the only fixed point of s_p . A *Hermitian symmetric space* is a Hermitian manifold that is connected, homogeneous, and has a symmetry at some point p . By homogeneity, there is a symmetry at each point.

Example. (a) Let Λ be a discrete subgroup of \mathbb{C} . Then \mathbb{C}/Λ is a Hermitian symmetric space. After identifying \mathbb{C} with \mathbb{R}^2 , the metric is given by the standard form $dx^2 + dy^2$. The translations act transitively on \mathbb{C}/Λ and $x \mapsto -x$ is a symmetry at 0. Geodesics are images of straight lines in \mathbb{C} .

(b) The Riemann sphere $\mathbb{P}^1(\mathbb{C}) \cong S^2$ is a Hermitian symmetric space. The metric is induced from the standard metric $dx^2 + dy^2 + dz^2$ of ambient space \mathbb{R}^3 of S^2 . Rotations act transitively on S^2 and symmetries are given by rotations by π around a diameter. Geodesics are great circles.

(c) The upper half-plane \mathcal{H}_1 is a Hermitian symmetric domain. After identifying \mathbb{C} with \mathbb{R}^2 , the metric is given by $\frac{dx^2 + dy^2}{y^2}$. The group $\text{SL}_2(\mathbb{R})$ acts transitively on \mathcal{H}_1 by Möbius transforms (no, it's not fun

to that they are isometries). A symmetry at i is given by $z \mapsto \bar{z}^{-1}$. Geodesics are vertical lines and half-circles with midpoint on the real line.

Hermitian Symmetric Domains

Given a Riemannian manifold M , one can define the curvature at a point p . It is measured by taking two different geodesics through p and determining, whether they converge or diverge. If they always converge, M has positive curvature at p . If they always diverge, M has negative curvature at p . If they never converge or diverge, M has zero curvature at p . If M is homogeneous, this notion is independent of p .

Example. Drawing some pictures shows:

- (a) \mathbb{C}/Λ has zero curvature.
- (b) $\mathbb{P}^1(\mathbb{C})$ has positive curvature.
- (c) \mathcal{H}_1 has negative curvature.

An important difference between these three cases is how the group $\text{Is}(M, g)^+$ of holomorphic isometries behaves. In positive curvature, $\text{Is}(M, g)^+$ is an adjoint compact Lie group. In negative curvature, it is an adjoint non-compact Lie group. If (M, g) has zero curvature, not much can be said.

It is known that a Hermitian symmetric space M can be decomposed as $M^+ \times M^0 \times M^-$, where M^+ has positive curvature, M^0 has zero curvature, and M^- has negative curvature. We are only interested in the domains with negative curvature. A *Hermitian symmetric domain* is a Hermitian symmetric space with negative curvature.

One way to construct Hermitian Symmetric Domains is using Bergman metrics. Let D be an open subset of \mathbb{C}^n that is connected, bounded, homogeneous, and has a holomorphic symmetry at some point.

Theorem (Bergman). There is a (up to a constant factor) canonical Hermitian metric on D . With this metric, D has negative curvature.

Example. The *Siegel upper half space* \mathcal{H}_g is given by the set of symmetric complex matrices $Z = X + iY$ such that Y is positive definite. The group

$$\text{Sp}_{2g}(\mathbb{R}) = \{M \in \text{M}_{2g}(\mathbb{R}) : M^T J M = J\} \quad J = \begin{pmatrix} 0 & -\mathbb{1} \\ \mathbb{1} & 0 \end{pmatrix}$$

acts transitively on \mathcal{H}_g via

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} Z = (AZ + B)(CZ + D)^{-1}.$$

J is a matrix in $\text{Sp}_{2g}(\mathbb{R})$ that has $i\mathbb{1}$ as sole fixed point. The only thing missing to give \mathcal{H}_g the structure of a Hermitian symmetric domain is a metric. The map $Z \mapsto (Z - i\mathbb{1})(Z + i\mathbb{1})$ identifies \mathcal{H}_g with the set \mathcal{D}_g of symmetric complex matrices M such that $\mathbb{1} - M^*M$ is positive definite. The last condition can be reformulated as $\|M\|_2 < 1$. Therefore, \mathcal{D}_g is bounded. Now \mathcal{D}_g and \mathcal{H}_g obtain a Bergman metric, so \mathcal{H}_g is a Hermitian symmetric domain.

Automorphisms of Hermitian Symmetric Domains

If G is a topological group, G^+ denotes the connected component of the identity. Let (M, g) be a Hermitian symmetric domain.

Theorem. The groups $\text{Is}(M, g)^+$, $\text{Is}(M^\infty, g)^+$, and $\text{Hol}(M)^+$ are identical and act transitively on M . Let $p \in M$. The stabiliser K_p of p in $\text{Is}(M, g)^+$ is compact. There is an isomorphism $\text{Is}(M, g)^+ / K_p \rightarrow M$ of smooth manifolds.

Theorem. Let \mathfrak{h} be the Lie algebra of $\text{Hol}(M)^+$. There is a unique connected algebraic subgroup G of $\text{GL}(\mathfrak{h})$, such that $G(\mathbb{R})^+ = \text{Hol}(M)^+$. Moreover, G is adjoint.

Proof. One can show that $\text{Hol}(M)^+$ is an adjoint Lie group (= semisimple, trivial center). Therefore, the adjoint representation of $\text{Hol}(M)^+$ on \mathfrak{h} is faithful, so $\text{Hol}(M)^+$ can be seen as a subgroup of $\text{GL}(\mathfrak{h})$. By some theorem of Borel, there is an algebraic subgroup G of $\text{GL}(V)$ with Lie algebra $[\mathfrak{h}, \mathfrak{h}]$. As $\text{Hol}(M)^+$ is adjoint, \mathfrak{h} is semisimple, so $[\mathfrak{h}, \mathfrak{h}] = \mathfrak{h}$. It follows $G(\mathbb{R})^+ = \text{Hol}(M)^+$. Adjointness of G follows from the fact that \mathfrak{h} is semisimple. \square

Let $U(1) = \{z \in \mathbb{C} : |z| = 1\}$. Using a lot of differential geometry, one proves:

Theorem. Let $p \in M$. There is a unique homomorphism $u_p : U(1) \rightarrow \text{Hol}(M)$ such that $u_p(z)(p) = p$ for all z and $u_p(z)$ acts on $T_p(M)$ as multiplication by z .

Representations of $U(1)$

Let T be a torus over a field k . Our goal is to describe the representations of T on finite-dimensional k -vector spaces. First suppose that T is split. Given a representation $\rho : T \rightarrow \text{GL}(V)$, each $\rho(t)$ acts semisimply since t is semisimple. Additionally, all $\rho(t)$ commute. Therefore, they can be diagonalised simultaneously. Now V decomposes as a sum of characters (= representations of dimension 1). We can write

$$V = \bigoplus_{\chi \in X^*(T)} V_\chi$$

where $X^*(T)$ is the set of characters of T and $t \in T$ acts on V_χ by multiplication with $\chi(t)$.

Now suppose T does not split over k but over some Galois extension K of k . Then $V \otimes_k K$ decomposes as above

$$V \otimes_k K = \bigoplus_{\chi \in X^*(T)} V_\chi.$$

Being a k -representation, ρ is stable under the action of $\text{Gal}(K/k)$. This is equivalent to $\sigma V_\chi = V_{\sigma\chi}$ for all $\chi \in X^*(T)$ and $\sigma \in \text{Gal}(K/k)$.

Now consider the real torus $U(1)$. It splits over \mathbb{C} . The characters are given by $\chi_n : z \mapsto z^n$ for $n \in \mathbb{Z}$. The Galois group $\text{Gal}(\mathbb{C}/\mathbb{R})$ acts via $\bar{\chi}_n = \chi_{-n}$. Thus, a representation of $U(1)$ on a real vector space V is given by a grading

$$V \otimes_{\mathbb{R}} \mathbb{C} = \bigoplus_{n \in \mathbb{Z}} V_n$$

such that $\bar{V}_n = V_{-n}$. By collecting spaces V_n and V_{-n} together and descending to \mathbb{R} one obtains that a real representation of $U(1)$ decomposes as a sum of the representations of the following type:

- $V = \mathbb{R}$ with the trivial action, $V \otimes_{\mathbb{R}} \mathbb{C} = V_0$
- $V = \mathbb{R}^2$, $x + iy \in U(1)$ acts via the matrix $\begin{pmatrix} x & y \\ -y & x \end{pmatrix}^n$ for some $n \in \mathbb{N}_+$, $V \otimes_{\mathbb{R}} \mathbb{C} = V_n \oplus V_{-n}$

Classification via Real Groups

Let G be a connected algebraic group over \mathbb{R} . An involution ϑ of \mathbb{R} is a *Cartan involution* if the subgroup

$$G^{(\vartheta)}(\mathbb{R}) = \{g \in G(\mathbb{C}) : \vartheta(\bar{g}) = g\}$$

is compact.

Example. (a) $G^{(\text{id})}(\mathbb{R}) = \{g \in G(\mathbb{C}) : g = \bar{g}\} = G(\mathbb{R})$, so id is a Cartan involution iff $G(\mathbb{R})$ is compact.

(b) $\vartheta : M \mapsto M^{-T}$ is an involution of GL_n .

$$\mathrm{GL}_n^{(\vartheta)}(\mathbb{R}) = \{M \in \mathrm{GL}_n(\mathbb{C}) : M = \bar{M}^{-T} = M\} = \{M : M^*M = \mathbb{1}\} = \mathrm{SU}(n)$$

is compact, so ϑ is a Cartan involution.

Let D be a Hermitian symmetric domain and let G be the connected algebraic group with $G(\mathbb{R})^+ = \mathrm{Hol}(D)^+$. Given $p \in D$, we have a homomorphism $u_p : U(1) \rightarrow \mathrm{Hol}(D)^+ = G(\mathbb{R})^+$. One can show that it extends to an algebraic morphism $u_p : U(1) \rightarrow G$.

Theorem. The morphism u_p constructed above has the following properties:

- (a) The representation of $U(1)$ on $\mathrm{Lie}(G) \otimes_{\mathbb{R}} \mathbb{C}$ induced by u_p contains only the complex representations χ_0 , χ_1 , and χ_{-1} .
- (b) $\mathrm{ad}(u_p(-1))$ is a Cartan involution. (ad means ‘‘conjugation with’’)
- (c) $u_p(1)$ does not project to 1 in any simple factor of G .

Conversely, suppose G is a real adjoint algebraic group and $u : U(1) \rightarrow G$ satisfies (a), (b), and (c). Let D be the set of conjugates of u by elements of $G(\mathbb{R})^+$. Then D is a Hermitian symmetric domain with $\mathrm{Hol}(D)^+ = G(\mathbb{R})^+$ and $u(-1)$ is a symmetry at $u \in D$.

Proof. Let K_p be the stabiliser of p inside $G(\mathbb{R})^+$. We have seen that $G(\mathbb{R})^+ / K_p \cong D$. The action of $U(1)$ on D via u_p corresponds to the action on the quotient by conjugation with $u_p(z)$. Considering tangent spaces, we get $\mathrm{Lie}(G) / \mathrm{Lie}(K_p) \cong T_p(D)$. One can calculate that the action of $U(1)$ on $\mathrm{Lie}(K_p)$ is trivial. By definition of u_p , the action of $z \in U(1)$ on $T_p(D)$ is given by multiplication with z . After complexifying, this representation therefore involves only χ_1 and χ_{-1} . For $\mathrm{Lie}(G) \otimes_{\mathbb{R}} \mathbb{C}$ this means that only χ_0 , χ_1 , and χ_{-1} can occur. This proves (a).

$u_p(-1)$ is a symmetry at p . It is known that conjugation by a symmetry is a Cartan involution iff the space has negative curvature. This is the case, so (b) holds.

Suppose, $u_p(-1)$ maps to 1 in some factor G' of G . Then the identity is a Cartan involution of G' , so G' is compact. This contradicts negative curvature of D . Thus, (c) is proven.

Sketch for conversely: By (b), the centraliser K_u of u in $G(\mathbb{R})^+$ is compact. Then $D \cong G(\mathbb{R})^+ / K_u$, so D is a real manifold. The tangent space $T_p(D)$ can be identified with $\mathrm{Lie}(G) / \mathrm{Lie}(K_u)_p$. By (a), this space carries a complex structure, which can be used to give D the structure of a complex manifold. Construct a K_u -invariant positive definite bilinear form on $T_p(D)$ and bring it to every point using homogeneity. Then D is a Hermitian symmetric space. Negative curvature follows from (b) and (c), since each factor of the automorphism group is non-compact. \square

Corollary. There is a natural one-to-one correspondence between pointed Hermitian symmetric domains and pairs (G, u) consisting of a real adjoint algebraic group and a homomorphism $u : U(1) \rightarrow G(\mathbb{R})$ such that (a), (b), and (c) are satisfied.

Remark. Note that there is another classification theorem for Hermitian symmetric domains that involves special nodes on connected Dynkin diagrams.