Optimization and Dynamics

Summer Semester 2015

Course Title	Optimization and Dynamics
Lecturer	Venta Terauds
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Course Objective	The course gives an introduction to dynamical systems, both discrete and continuous. Students will learn the basic quantit- ative and qualitative methods to solve problems arising in the study of dynamical systems and will become acquainted with typical phenomena associated with linear and non linear sys- tems.
Prerequisites	First courses in linear algebra and analysis
References	 R. L. Devaney, An introduction to chaotic dynamical systems, Addison-Wesley, 1989 D. K. Arrowsmith and C. M. Place, An introduction to dynam- ical systems, Cambridge Univ. Press, 1990
	(Additional references may be given during the lectures.)
Description	Discrete and continuous dynamical systems; linear and non– linear stability; bifurcations; chaos.
Tentative content	 dynamical systems with discrete time: one-dimensional systems and d-dimensional systems linear and non-linear systems stability bifurcations period doubling dynamical systems with continuous time: linear differential equations non-linear autonomous differential equations existence, uniqueness and stability of solutions flow symbolic dynamics Note: Content will be adapted according to the knowledge and needs of the students, some items may be added or skipped.
Teaching Method	Lectures, tutorials, exercises
Evaluation	One final exam